

WT3000
Precision Power Analyzer
Expansion Function
U S E R ' S M A N U A L

Thank you for purchasing the WT3000 Precision Power Analyzer.

This Expansion Function User's Manual contains useful information about the operating procedures and lists the handling precautions of the expansion functions. To ensure correct use, please read this manual thoroughly before beginning operation. After reading the manual, keep it in a convenient location for quick reference whenever a question arises during operation.

Three manuals, including this one, are provided as manuals for the WT3000. Please read all of them.

| Manual Title | Manual No. | Description |
|--|---------------|---|
| WT3000 Precision Power Analyzer User's Manual (Vol 1/3) | IM 760301-01E | Explains all functions and procedures of the WT3000 excluding the expansion functions and communication functions. |
| WT3000 Precision Power Analyzer Communication Interface User's Manual (CD-ROM) (Vol 2/3) | IM 760301-17E | Explains the functions for controlling the WT3000 using communication commands. |
| WT3000 Precision Power Analyzer Expansion Function User's Manual (vol 3/3) | IM 760301-51E | This manual. Explains the expansion functions (motor evaluation function and options) of the WT3000 and their operating procedures. |

Note

- The contents of this manual are subject to change without prior notice as a result of continuing improvements to the instrument's performance and functions. The figures given in this manual may differ from those that actually appear on your screen.
- Every effort has been made in the preparation of this manual to ensure the accuracy of its contents. However, should you have any questions or find any errors, please contact your nearest YOKOGAWA dealer as listed on the back cover of this manual.
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Revisions

- 1st Edition December, 2004
- 2nd Edition June, 2005

Safety Precautions

This instrument is an IEC safety class 01 instrument (provided with a terminal for protective earth grounding).

The general safety precautions described in the *User's Manual IM760301-01E* and this manual (IM760301-51E) must be observed during all phases of operation. If the instrument is used in a manner not specified in these manuals, the protection provided by the instrument may be impaired. Yokogawa Electric Corporation assumes no liability for the customer's failure to comply with these requirements.

Conventions Used in This Manual

Safety Markings

The following markings are used in this manual.



Improper handling or use can lead to injury to the user or damage to the instrument. This symbol appears on the instrument to indicate that the user must refer to the user's manual for special instructions. The same symbol appears in the corresponding place in the user's manual to identify those instructions. In the manual, the symbol is used in conjunction with the word "WARNING" or "CAUTION."

WARNING

Calls attention to actions or conditions that could cause serious or fatal injury to the user, and precautions that can be taken to prevent such occurrences.

CAUTION

Calls attentions to actions or conditions that could cause light injury to the user or damage to the instrument or user's data, and precautions that can be taken to prevent such occurrences.

Note

Calls attention to information that is important for proper operation of the instrument.

Subheadings

On pages that describe operating procedures, the following symbols, displayed characters, and terminology are used to distinguish the procedures from their explanations:

Procedure

Follow the numbered steps. All procedures are written with inexperienced users in mind; experienced users may not need to carry out all the steps.

Explanation

This subsection describes the setting parameters and the limitations on the procedures.

Displayed Characters and Terminology Used in the Procedural Explanations

Panel Keys and Soft keys

Bold characters used in the procedural explanations indicate characters that are marked on the panel keys or the characters of the soft keys or menus displayed on the screen.

SHIFT+Panel Key

SHIFT+key means you will press the SHIFT key to turn ON the SHIFT key followed by the operation key. The setup menu marked in purple below the panel key that you pressed appears on the screen.

Unit

k Denotes 1000. Example: 12 kg, 100 kHz

K Denotes 1024. Example: 459 KB (file data size)

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
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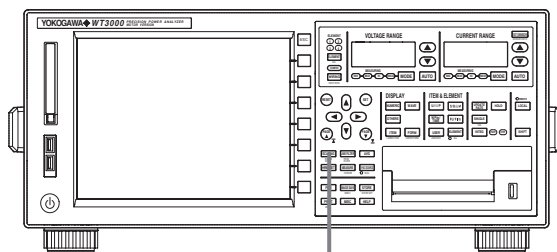
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1.1 Names and Functions of Parts of the Motor Evaluation Function

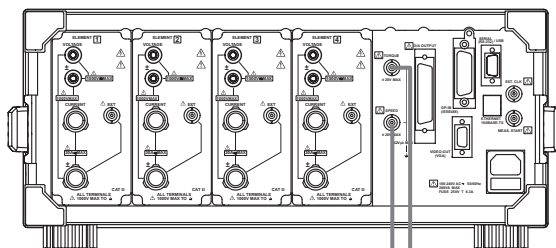
Front Panel



SHIFT+SCALING (MOTOR SET) key (motor version)

Sets items that are required in the motor evaluation such as torque, number of rotations, and motor output.

Rear Panel



Torque signal input connector (TORQUE) (motor version)

Receives signals from torque meters when evaluating motors.

Revolution signal input connector (SPEED) (motor version)

Receives signals from revolution sensors when evaluating motors.

Functional Description

By using the motor evaluation function (motor version), the rotating speed, torque, and output of a motor can be determined from the signal that is proportional to the rotating speed of the motor, and the signal received from a torque meter, which is proportional to the motor's torque. The signal applied from the revolution sensor or torque meter to the WT3000 can be selected from analog signal (DC voltage) or pulse signal. In addition, the synchronous speed and slip of a motor can be determined by setting the motor's number of poles. Furthermore, the active power and frequency that are measured by the WT3000 and the motor output can be used to compute the motor efficiency and the total efficiency.

Types of Measurement Functions

Measurement functions consists of Speed (rotating speed), Torque, Pm (motor output or mechanical power), SyncSp (synchronous speed), and Slip. For details on the determination of the measurement functions, see section 1.10.

Set equations for the motor efficiency $((P_m)/(P_{\Sigma A}) \times 100)$ and total efficiency $((P_m)/(P_{\Sigma B}) \times 100)$ according to the procedures in section 5.7 in the *User's Manual IM760301-01E*.

1.2 Applying Signals of Rotating Speed and Torque



CAUTION

Applying a voltage exceeding the maximum allowable input to the revolution signal input connector (SPEED) or torque signal input connector (TORQUE) can damage the instrument.

Revolution Signal Input Connector (SPEED)

Input the signal output from the revolution sensor (a DC voltage (analog signal) or a pulse signal that is proportional to the rotating speed of the motor) according to the following specifications.



• DC Voltage (Analog Input)

| Item | Specifications |
|--|--|
| Connector type | Isolated BNC connector |
| Input range | 1 V, 2 V, 5 V, 10 V, and 20 V |
| Effective input range | 0% to $\pm 110\%$ of the measurement range |
| Input resistance | Approx. 1 M Ω |
| Maximum allowable input | ± 22 V |
| Continuous maximum common mode voltage | ± 42 V _{peak} or less |

• Pulse Input

| Item | Specifications |
|--|------------------------------------|
| Connector type | Isolated BNC connector |
| Frequency range | 2 Hz to 200 kHz |
| Amplitude input range | ± 12 V _{peak} |
| Effective amplitude | 1 V (peak to peak) or more |
| Input waveform | 50% duty ratio rectangular wave |
| Input resistance | Approx. 1 M Ω |
| Continuous maximum common mode voltage | ± 42 V _{peak} or less |

Torque Signal Input Connector (TORQUE)

Input the signal output from the torque meter (a DC voltage (analog signal) that is proportional to the torque of the motor) according to the following specifications.



• DC Voltage (Analog Input)

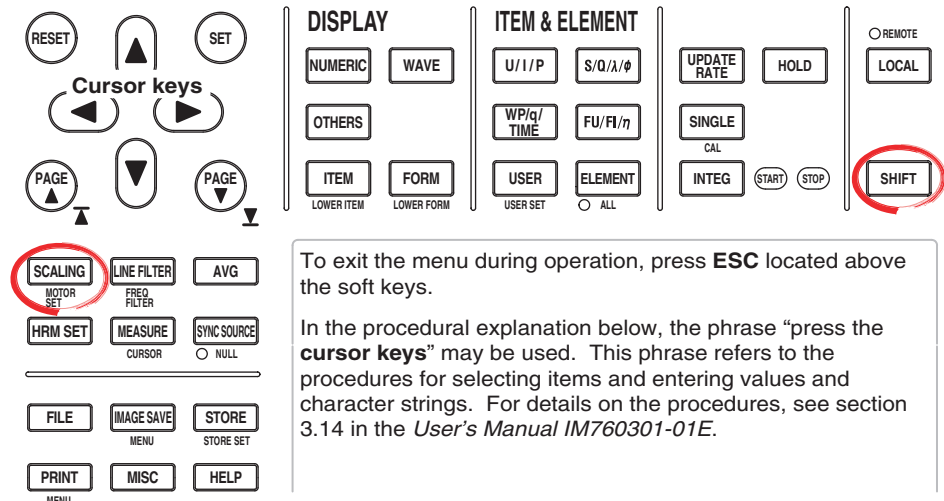
| Item | Specifications |
|--|--------------------------------------|
| Connector type | Isolated BNC connector |
| Input range | 1 V, 2 V, 5 V, 10 V, and 20 V |
| Effective input range | 0% to ±110% of the measurement range |
| Input resistance | Approx. 1 MΩ |
| Maximum allowable input | ±22 V |
| Continuous maximum common mode voltage | ±42 Vpeak or less |

• Pulse Input

| Item | Specifications |
|--|---------------------------------|
| Connector type | Isolated BNC connector |
| Frequency range | 2 Hz to 200 kHz |
| Amplitude input range | ±12 Vpeak |
| Effective amplitude | 1 V (peak to peak) or more |
| Input waveform | 50% duty ratio rectangular wave |
| Input resistance | Approx. 1 MΩ |
| Continuous maximum common mode voltage | ±42 Vpeak or less |

1.3 Selecting the Type of the Revolution and Torque Signals

Procedure



1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Selecting the Revolution Signal Type**
 2. Press the **cursor keys** to select the Sense Type under Speed.
 3. Press **SET**. A signal type selection box appears.
 4. Press the **cursor keys** to select Analog or Pulse.
 5. Press **SET** to confirm the signal type.

Motor Set

| | Speed | Torque | Pm |
|-------------|------------|----------|----------------|
| Scaling | 1.0000 | 1.0000 | 1.0000 |
| Unit | rpm | Nm | V _u |
| Sense Type | Analog | Set | |
| | Speed | Analog | |
| Auto Range | OFF | Pulse | |
| Range | 20V | | |
| Line Filter | 0 | | |
| Sync Source | None | | |
| Pulse | | | |
| Range Upper | 10000.0000 | 50.0000 | |
| Range Lower | 0.0000 | -50.0000 | |
| Rated Upper | 50.0000 | 15000Hz | |
| Rated Lower | -50.0000 | 5000Hz | |
| Pulse N | 60 | | |
| Sync Speed | | | |
| Pole | 2 | | |
| Source | 11 | | |

- **Selecting the Torque Signal Type**
 2. Press the **cursor keys** to select the Sense Type under Torque.
 3. Press **SET**. A signal type selection box appears.
 4. Press the **cursor keys** to select Analog or Pulse.
 5. Press **SET** to confirm the signal type.

The screenshot shows the 'Motor Set' menu with the 'Torque' sub-menu selected. The 'Sense Type' for Torque is currently set to 'Analog'. A selection box is open, showing 'Analog' and 'Pulse' options. The 'Pulse' option is highlighted. Other settings visible include Speed and Pm scaling and units, and various filter and synchronization options.

Explanation

- **Selecting the Signal Type**
The signal applied from the revolution sensor or torque meter to the WT3000 can be selected from the following two types.

- **Analog**
Select this when the signal type is a DC voltage (analog signal).
- **Pulse**
Select this when the signal type is a pulse signal.

- **Signal Type and Setup Items**

Some of the settings described in the subsequent sections are not required depending on the signal type as described below.

- **Settings Related to the Revolution Signal Type**

| | Revolution Signal Type | |
|--|------------------------|--------------|
| | Analog | Pulse |
| Analog range (section 1.4) | Required | Not required |
| Line filter (section 1.5) | Required | Not required |
| Synchronization source (section 1.5) | Required | Recommended* |
| Pulse range (section 1.6) | Not required | Required |
| Pulse count per revolution (section 1.6) | Not required | Required |

* Measurement is possible using None (default), but it is recommended that you specify the setting to improve the measurement accuracy. For details, see the explanation in section 1.5.

1.3 Selecting the Type of the Revolution and Torque Signals

- **Settings Related to the Torque Signal Type**

| | Torque Signal Type | |
|--------------------------------------|--------------------|--------------|
| | Analog | Pulse |
| Analog range (section 1.4) | Required | Not required |
| Line filter (section 1.5) | Required | Not required |
| Synchronization source (section 1.5) | Required | Recommended* |
| Pulse range (section 1.6) | Not required | Required |
| Pulse rating (section 1.6) | Not required | Required |

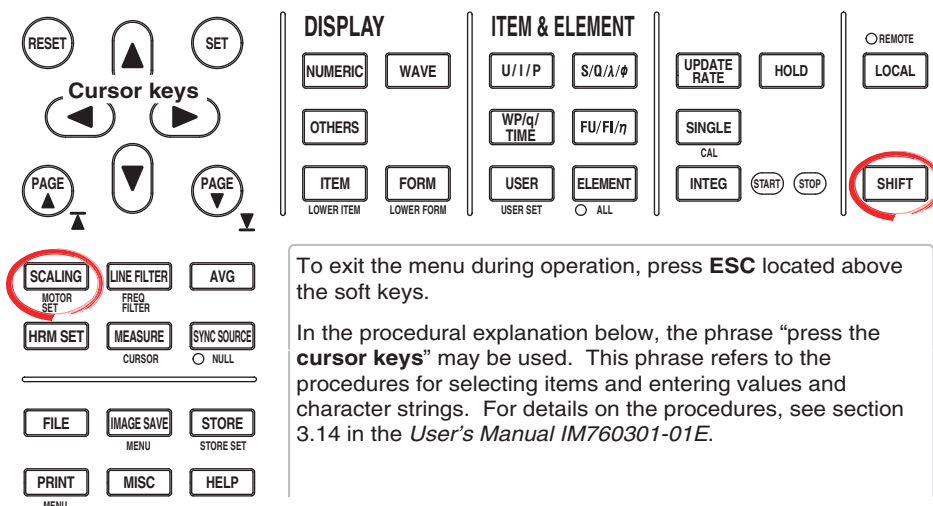
* Measurement is possible using None (default), but it is recommended that you specify the setting to improve the measurement accuracy. For details, see the explanation in section 1.5.

- **Common Settings Not Dependent on the Signal Type**

- Motor's number of poles and frequency measurement source (section 1.7)
- Scaling factor and unit (section 1.8)

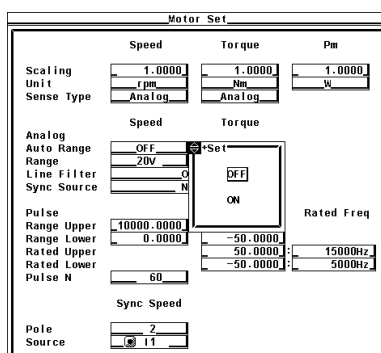
1.4 Selecting the Analog Range

Procedure



The settings covered in this section apply to the case when the input signal type is set to Analog. You do not have to specify the settings in this section if the input signal type is set to Pulse.

1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Selecting the Analog Input Range of the Revolution Signal**
 - **Selecting Auto Range**
 2. Press the **cursor keys** to select Auto Range under Speed.
 3. Press **SET**. An auto range selection box appears.
 4. Press the **cursor keys** to select ON or OFF.
 5. Press **SET** to confirm the auto range setting.



1.4 Selecting the Analog Range

- **When Measuring Using a Fixed Range (When Auto Range Is Set to OFF)**

6. Press the **cursor keys** to select Range under Speed.
7. Press **SET**. An input range selection box appears.
8. Press the **cursor keys** to select a value between 20 V to 1 V.
9. Press **SET** to confirm the input range.

The screenshot shows the 'Motor Set' menu with three columns: Speed, Torque, and Pm. Under the Torque column, the 'Range' option is selected, and a sub-menu is displayed with the following options: 20V, 10V, 5V, 2V, and 1V. The 20V option is highlighted. Other settings visible include Scaling (1.0000), Unit (rpm), Sense Type (Analog), and Auto Range (OFF).

- **Selecting the Analog Input Range of the Torque Signal**

- **Selecting Auto Range**

2. Press the **cursor keys** to select Auto Range under Torque.
3. Press **SET**. An auto range selection box appears.
4. Press the **cursor keys** to select ON or OFF.
5. Press **SET** to confirm the auto range setting.

The screenshot shows the 'Motor Set' menu with the Torque column selected. The 'Auto Range' option is highlighted, and a sub-menu is displayed with 'ON' and 'OFF' options. The 'ON' option is selected. Other settings visible include Scaling (1.0000), Unit (Nm), Sense Type (Analog), and Auto Range (OFF).

- **When Measuring Using a Fixed Range (When Auto Range Is Set to OFF)**

6. Press the **cursor keys** to select Range under Torque.
7. Press **SET**. An input range selection box appears.
8. Press the **cursor keys** to select a value between 20 V to 1 V.
9. Press **SET** to confirm the input range.

The screenshot shows the 'Motor Set' menu with the Torque column selected. The 'Range' option is highlighted, and a sub-menu is displayed with the following options: 20V, 10V, 5V, 2V, and 1V. The 20V option is highlighted. Other settings visible include Scaling (1.0000), Unit (Nm), Sense Type (Analog), and Auto Range (OFF).

Explanation

- **Selecting the Input Range of the Revolution and Torque Signals**

Two types of range settings are available: fixed and auto.

- **Fixed Range**

Select the input range from the following:

20 V, 10 V, 5 V, 2 V, or 1 V

- **Auto Range**

Select ON for the auto range setting to enable auto range. The range changes automatically depending on the amplitude of the input signal.

- **Range Increase**

- When the rotating speed or torque data exceeds 110% of the current measurement range, the measurement range is increased.
 - When the peak value of the input signal exceeds approximately 150% of the measurement range, the range is increased.

- **Range Decrease**

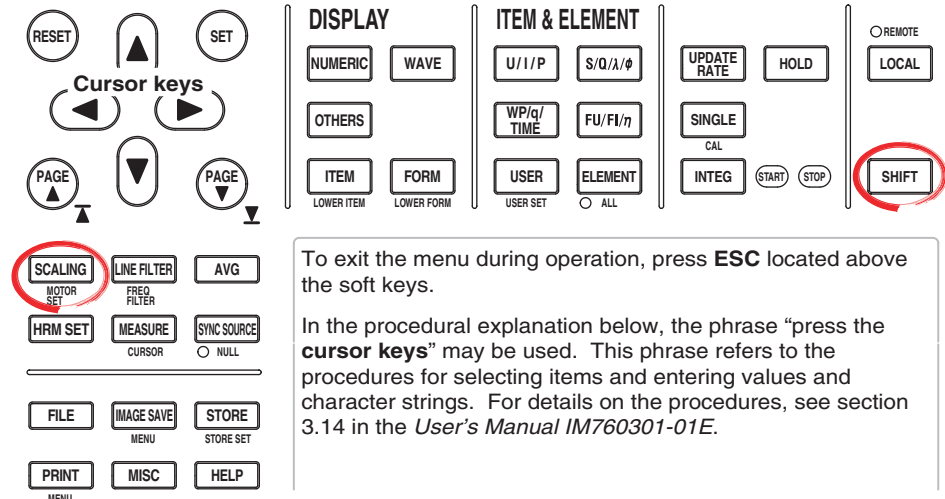
When the rotating speed or torque data is less than 30% of the measurement range and the peak value of the input signal is less than 125% of the next lower range, the measurement range is decreased.

Note

When non-periodic pulse waveforms are applied during auto range, the range may not remain constant. If this happens, use the fixed range setting.

1.5 Selecting the Line Filter and Synchronization Source

Procedure



The settings covered in this section apply to the case when the input signal type is set to Analog. You do not have to specify the settings in this section if the input signal type is set to Pulse.

1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Selecting the Line Filter**
 2. Press the **cursor keys** to select Line Filter.
 3. Press **SET**. A line filter selection box appears.
 4. Press the **cursor keys** to select a value between OFF and 50 kHz.
 5. Press **SET** to confirm the line filter. The same filter is set to both the revolution signal and the torque signal.

Motor Set dialog box showing settings for Speed, Torque, and Pm. The Line Filter is set to OFF. The Sync Source is set to None. The Pulse Range Upper is 10000.0000, Range Lower is 0.0000, Rated Upper is 50.0000, Rated Lower is -50.0000, and Pulse N is 60. The Pole Source is set to 11.

- **Selecting the Synchronization Source**
 2. Press the **cursor keys** to select Sync Source.
 3. Press **SET**. A synchronization source selection box appears.
 4. Press the **cursor keys** to select any of the elements/wiring units starting with U1.
 5. Press **SET** to confirm the synchronization source.

Explanation

- **Selecting the Line Filter**
A line filter can be inserted into the circuits that measure the revolution signal and torque signal. It eliminates harmonic noise.
The cutoff frequency can be selected from the list of choices below.
OFF, 100 Hz, and 50 kHz
Selecting OFF disables the filter.

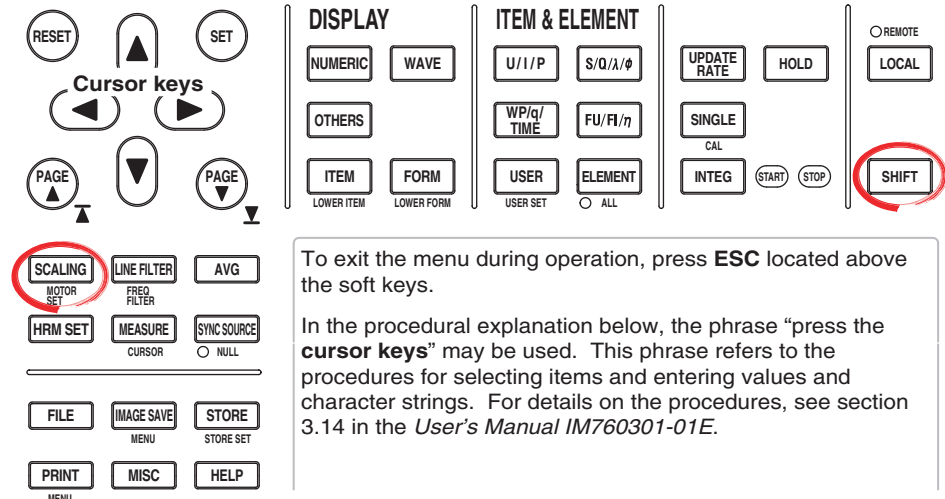
Note

If the signal type (see section 1.3) is Pulse, the filter function does not work.

- **Selecting the Synchronization Source**
 - Select which element's input signal will be used as a synchronization source (synchronized to the zero-crossing point of the selected signal) when measuring the analog signal of the revolution signal and torque signal. Select the signal to be the synchronization source from the choices below. The selectable items vary depending on the installed elements.
U1, I1, U2, I2, U3, I3, U4, I4, Ext Clk (external clock)*, and None
 - * For the specifications of the Ext Clk (external clock), see the explanation in section 7.4.
 - The measurement period determined by the synchronization source selected here is used to measure the analog signal of the revolution signal and torque signal. If you specify no synchronization source by selecting "None," the entire sampled data within the data update interval is the data used to determine the rotating speed and torque. For details on the synchronization source, see appendix 6 in the *User's Manual IM760301-01E*.
 - If the rotating or torque signal is a pulse signal, the average of the pulse signal interval over the measurement period determined by the synchronization source selected here is the measured value of the rotating or torque signal. If the pulse signal interval is not within this measurement period, the measured value is determined from the previous interval.
 - To achieve stable measured values by matching the measurement period with the measurement functions of voltage, current, active power, and so on such as during the measurement of the motor efficiency, it is recommended that the synchronization source be set to the same synchronization source specified in section 4.7 in the *User's Manual IM760301-01E*.

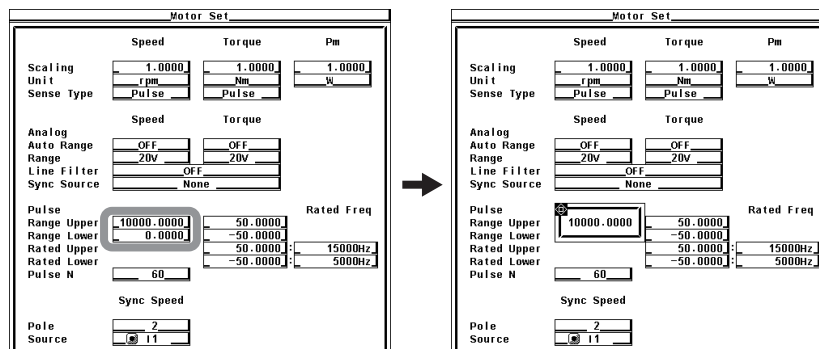
1.6 Setting the Pulse Range, Pulse Count, and Pulse Rating

Procedure



The settings covered in this section apply to the case when the input signal type is set to Analog. You do not have to specify the settings in this section if the input signal type is set to Pulse.

1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Setting the Pulse Input Range of the Revolution Signal**
If the revolution signal type is Pulse, set the upper and lower limits of the pulse input range.
 2. Press the **cursor keys** to select Pulse Range Upper under Speed.
 3. Press **SET**. A pulse input range setup box appears.
 4. Press the **cursor keys** to set the upper limit of the pulse input range.
 5. Press **SET** or **ESC** to close the box.
 6. Press the **cursor keys** to select Pulse Range Lower under Speed.
 7. Press **SET**. A pulse input range setup box appears.
 8. Press the **cursor keys** to set the lower limit of the pulse input range.
 9. Press **SET** or **ESC** to close the box.



- **Setting the Pulse Input Range of the Torque Signal**

If the torque signal type is Pulse, set the upper and lower limits of the pulse input range.

2. Press the **cursor keys** to select Pulse Range Upper under Torque.
3. Press **SET**. A pulse input range setup box appears.
4. Press the **cursor keys** to set the upper limit of the pulse input range.
5. Press **SET** or **ESC** to close the box.
6. Press the **cursor keys** to select Pulse Range Lower under Torque.
7. Press **SET**. A pulse input range entry box appears.
8. Press the **cursor keys** to set the lower limit of the pulse input range.
9. Press **SET** or **ESC** to close the box.

The figure shows two screenshots of the 'Motor Set' screen, illustrating the steps to set the pulse input range for the Torque signal. The screen is divided into sections for Speed, Torque, and Pm. The Torque section is active, showing the Pulse Range Upper and Lower fields. In the first screenshot, the Pulse Range Upper field is being edited from 10000.0000 to 50.0000. In the second screenshot, the Pulse Range Lower field is being edited from 0.0000 to -50.0000. The Pulse Range Upper field is highlighted with a red box in the first screenshot, and the Pulse Range Lower field is highlighted with a red box in the second screenshot. An arrow points from the first screenshot to the second, indicating the sequence of steps.

- **Setting the Pulse Count per Revolution of the Revolution Signal**

2. Press the **cursor keys** to select Pulse N.
3. Press **SET**. A pulse count entry box appears.
4. Press the **cursor keys** to set the pulse count.
5. Press **SET** or **ESC** to close the box.

The figure shows a screenshot of the 'Motor Set' screen, illustrating the step to set the pulse count per revolution of the Revolution signal. The screen is divided into sections for Speed, Torque, and Pm. The Torque section is active, showing the Pulse N field. The Pulse N field is highlighted with a red box, and its value is being edited from 60 to 100. The Pulse N field is highlighted with a red box.

1.6 Setting the Pulse Range, Pulse Count, and Pulse Rating

- **Setting the Pulse Rating of the Torque Signal**

Set the pulse rating of the torque sensor.

- **Setting the Positive Rating**

2. Press the **cursor keys** to select Pulse Rated Upper under Torque.
3. Press **SET**. A pulse rating (torque) entry box appears.
4. Press the **cursor keys** to set the positive pulse rating (torque).
5. Press **SET** or **ESC** to close the box.
6. Press the **cursor keys** to select Rated Upper under Rated Freq under Torque.
7. Press **SET**. A pulse rating (pulse frequency) entry box appears.
8. Press the **cursor keys** to set the positive pulse rating (pulse frequency).
9. Press **SET** or **ESC** to close the box.

- **Setting the Negative Rating**

2. Press the **cursor keys** to select Pulse Rated Lower under Torque.
3. Press **SET**. A pulse rating (torque) entry box appears.
4. Press the **cursor keys** to set the negative pulse rating (torque).
5. Press **SET** or **ESC** to close the box.
6. Press the **cursor keys** to select Rated Lower under Rated Freq under Torque.
7. Press **SET**. A pulse rating (pulse frequency) entry box appears.
8. Press the **cursor keys** to set the positive pulse rating (pulse frequency).
9. Press **SET** or **ESC** to close the box.

The figure shows three sequential screenshots of the 'Motor Set' screen, illustrating the steps to set pulse ratings. The screen is divided into sections for Speed, Torque, and Pm. The Torque section is the focus, showing settings for Pulse Range Upper, Pulse Range Lower, Rated Upper, and Rated Lower. The Rated Freq section shows settings for Rated Upper and Rated Lower. The Pulse N section shows the Pulse N setting. The Sync Speed section shows the Sync Speed setting. The Pole Source section shows the Pole and Source settings.

Top Left Screenshot: The 'Motor Set' screen. The 'Torque' section shows 'Pulse Range Upper' set to 10000.0000 and 'Pulse Range Lower' set to 0.0000. The 'Rated Freq' section shows 'Rated Upper' set to 15000Hz and 'Rated Lower' set to 5000Hz. The 'Pulse N' section shows 'Pulse N' set to 60. The 'Sync Speed' section shows 'Sync Speed' set to 60. The 'Pole Source' section shows 'Pole' set to 2 and 'Source' set to 11.

Top Right Screenshot: The 'Motor Set' screen. The 'Torque' section shows 'Pulse Range Upper' set to 10000.0000 and 'Pulse Range Lower' set to 0.0000. The 'Rated Freq' section shows 'Rated Upper' set to 50.0000 and 'Rated Lower' set to 5000Hz. The 'Pulse N' section shows 'Pulse N' set to 60. The 'Sync Speed' section shows 'Sync Speed' set to 60. The 'Pole Source' section shows 'Pole' set to 2 and 'Source' set to 11.

Bottom Screenshot: The 'Motor Set' screen. The 'Torque' section shows 'Pulse Range Upper' set to 10000.0000 and 'Pulse Range Lower' set to 0.0000. The 'Rated Freq' section shows 'Rated Upper' set to 50.0000 and 'Rated Lower' set to 5000Hz. The 'Pulse N' section shows 'Pulse N' set to 60. The 'Sync Speed' section shows 'Sync Speed' set to 60. The 'Pole Source' section shows 'Pole' set to 2 and 'Source' set to 11.

Explanation

- **Pulse Input Range**

Set an appropriate range that includes the maximum and minimum values of the input signal. For example, if you are measuring a signal whose rotating speed is between 120 rpm and 180 rpm and the torque is between $-18 \text{ N}\cdot\text{m}$ to $+18 \text{ N}\cdot\text{m}$, set the pulse input range of the rotating speed to 100 rpm to 200 rpm and that of the torque to $-20 \text{ N}\cdot\text{m}$ to $+20 \text{ N}\cdot\text{m}$.

The selectable range of pulse range of input signals is as follows:

- Revolution signal: 0.0001 to 99999.9999 [rpm]
- Torque signal: -10000.0000 to $10000.0000 \text{ [N}\cdot\text{m]}$

If the input signal type is Pulse, the upper and lower limits of the waveform display are set to the values specified here.

- On models with the D/A output (option), the rated value of the D/A output is as follows.

| Input Signal of Rotating Speed or Torque | D/A Output |
|--|------------|
| Pulse Range Upper setting | +5 V |
| Pulse Range Upper setting $\times (-1)$ | -5 V |

- **Setting the Rotation Pulse Count**

Set the pulse count per rotation. Set the value in the range of 1 to 9999.

$$\text{Rotating Speed} = \frac{\text{Input pulse count from the revolution sensor per minute}}{\text{Pulse count (pulse count per revolution)}} \times \text{scaling factor}^*$$

- * If the scaling factor is 1, the rotating speed is the number of rotations per minute (min^{-1} or rpm). In addition, if the revolution signal is a changed signal, you can set the scaling factor (see section 1.7) to determine the rotating speed before the change.

- **Pulse Rating of the Torque Signal**

If the torque signal type is Pulse, set the positive and negative ratings of the torque sensor. Refer to the torque sensor specifications to set the values.

The selectable range of the values is as follows:

- Torque: -10000.0000 to $10000.0000 \text{ [N}\cdot\text{m]}$
- Pulse count: 1 to 100000000 [Hz]

$$\text{Torque} = (\text{torque pulse coefficient}^{*1} \times \text{pulse frequency} + \text{torque pulse offset}^{*1} \times \text{scaling factor}^{*2})$$

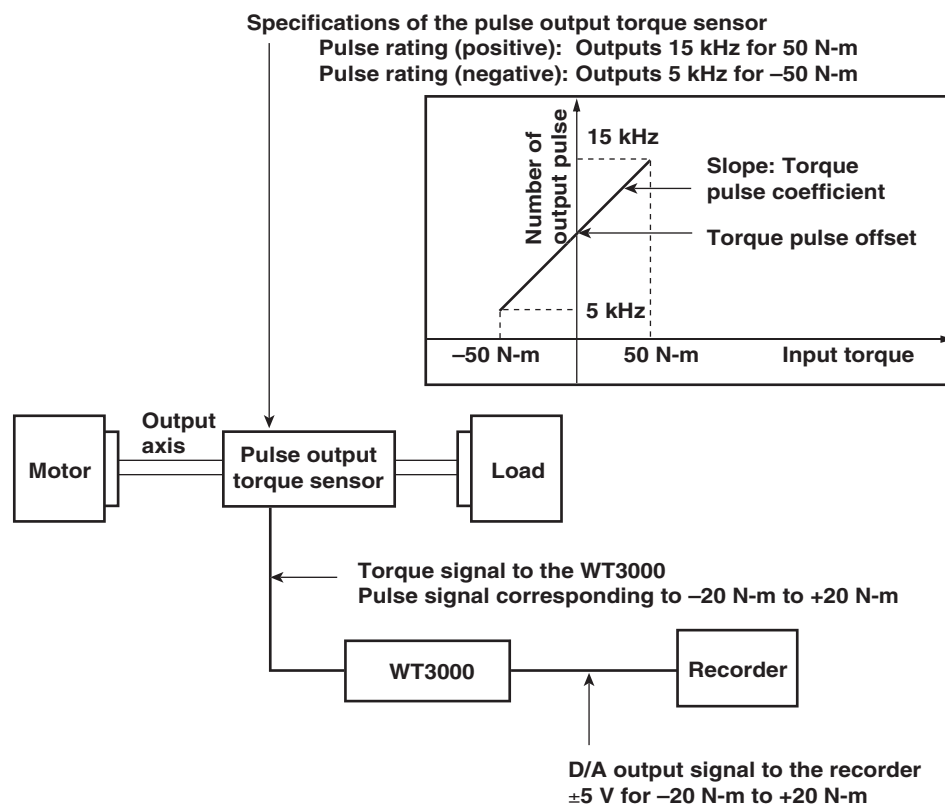
- *1 The torque pulse count and torque pulse offset are set as shown in the figure on the next page depending on the pulse rating of the torque signal.

- *2 If the torque signal is a changed signal, you can set the scaling factor (see section 1.7) to determine the torque before the change.

1.6 Setting the Pulse Range, Pulse Count, and Pulse Rating

- Relationship between the Pulse Input Range and Pulse Rating of the Torque Signal**

If the torque sensor with the specifications below is used to measure the torque in the range of -20 N-m to $+20$ N-m, the pulse input range and pulse rating settings are as shown in the screen example below.

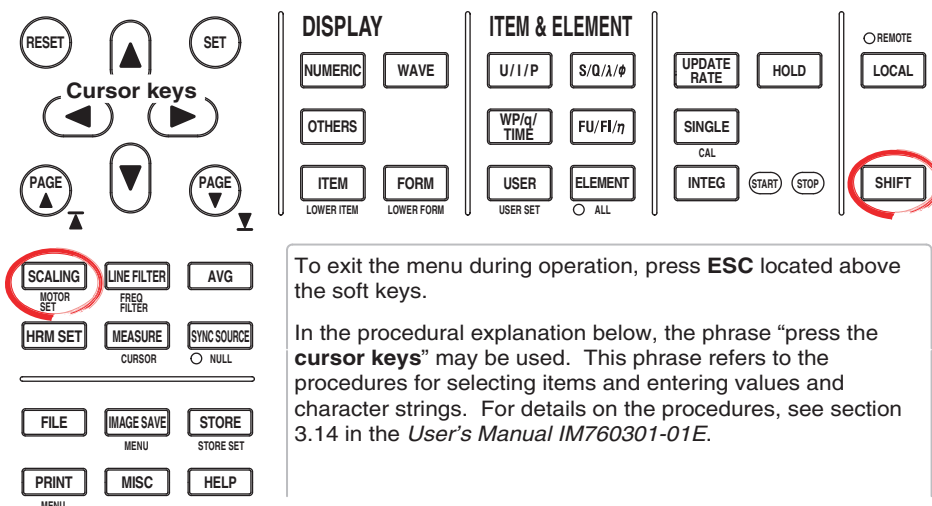


| Motor Set | | |
|-------------|------------|------------|
| | Speed | Torque |
| Scaling | 1.0000 | 1.0000 |
| Unit | rpm | Nm |
| Sense Type | Analog | Analog |
| | Speed | Torque |
| Analog | | |
| Auto Range | OFF | OFF |
| Range | 20V | 20V |
| Line Filter | OFF | |
| Sync Source | None | |
| Pulse | | Rated Freq |
| Range Upper | 10000.0000 | 20.0000 |
| Range Lower | 0.0000 | -20.0000 |
| Rated Upper | | 50.0000 |
| Rated Lower | | -50.0000 |
| Pulse N | 60 | |
| | Sync Speed | |
| Pole | 2 | |
| Source | I1 | |

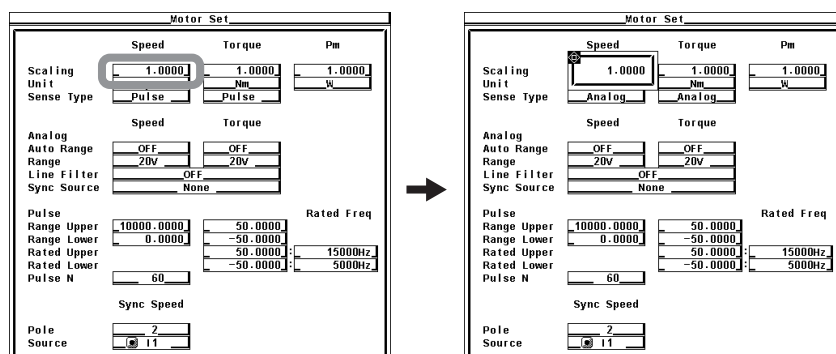
Pulse input range and pulse rating settings of the torque signal

1.7 Setting the Scaling Factor and Unit

Procedure



1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Setting the Scaling Factor Used to Transform the Revolution Signal**
 2. Press the **cursor keys** to select Scaling under Speed.
 3. Press **SET**. A scaling factor entry box appears.
 4. Press the **cursor keys** to set the scaling factor.
 5. Press **SET** or **ESC** to close the box.



1.7 Setting the Scaling Factor and Unit

- **Setting the Unit of Rotating Speed**

2. Press the **cursor keys** to select Unit under Speed.
3. Press **SET**. A keyboard appears.
4. Use the **keyboard** to set the unit.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

The screenshot shows the 'Motor Set' menu with three tabs: Speed, Torque, and Pm. The 'Speed' tab is active. Under the 'Unit' field, the value 'rpm' is displayed. A numeric keypad is overlaid on the screen, showing digits 0-9, a decimal point, and function keys like 'INSERT', 'ENT', and 'ESC'. The keypad is positioned over the 'Unit' field, indicating that the user is in the process of setting the unit.

- **Setting the Scaling Factor Used to Transform the Torque Signal**

2. Press the **cursor keys** to select Scaling under Torque.
3. Press **SET**. A scaling factor entry box appears.
4. Press the **cursor keys** to set the scaling factor.
5. Press **SET** or **ESC** to close the box.

The first screenshot shows the 'Motor Set' menu with the 'Torque' tab selected. The 'Scaling' field is highlighted, and a numeric keypad is overlaid on the screen. The second screenshot shows the same menu after the scaling factor has been set to '1.0000'. The 'Scaling' field now displays '1.0000'.

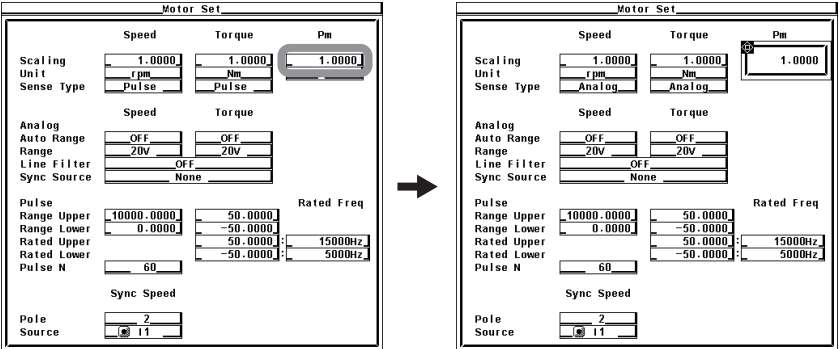
- **Setting the Unit of Torque**

2. Press the **cursor keys** to select Unit under Torque.
3. Press **SET**. A keyboard appears.
4. Use the **keyboard** to set the unit.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

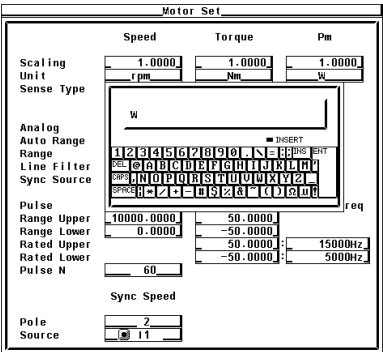
The screenshot shows the 'Motor Set' menu with the 'Torque' tab selected. Under the 'Unit' field, the value 'Nm' is displayed. A numeric keypad is overlaid on the screen, showing digits 0-9, a decimal point, and function keys like 'INSERT', 'ENT', and 'ESC'. The keypad is positioned over the 'Unit' field, indicating that the user is in the process of setting the unit.

- **Setting the Scaling Factor Used to Compute the Motor Output**
 2. Press the **cursor keys** to select Scaling under Pm.
 3. Press **SET**. A scaling factor entry box appears.
 4. Press the **cursor keys** to set the scaling factor.
 5. Press **SET** or **ESC** to close the box.



- **Setting the Unit of Motor Output**
 2. Press the **cursor keys** to select Unit under Pm.
 3. Press **SET**. A keyboard appears.
 4. Use the **keyboard** to set the unit.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.



Explanation

- **Setting the Scaling Factor Used to Transform the Revolution Signal**

Set the factor used to transform the revolution signal. Set the value in the range of 0.0001 to 99999.9999.

- **When the Revolution Signal Type is Analog**

By setting the number of rotations per volt of input voltage, the rotating speed is derived from the following equation.

$$\text{Rotating speed} = \text{Input voltage from the revolution sensor} \times \text{scaling factor}$$

- **When the Revolution Signal Type is Pulse**

The value is used as a scaling factor in the equation given in “Setting the Rotation Pulse Count” in section 1.6

- **Setting the Scaling Factor Used to Transform the Torque Signal**

You can specify the scaling factor used to transform the torque signal to the torque of the motor. Set the value in the range of 0.0001 to 99999.9999.

- **When the Torque Signal Type is Analog**

By setting the torque per volt of input voltage, the torque is derived from the input voltage from the torque meter using the following equation.

$$\text{Torque} = \text{Input voltage from the torque meter} \times \text{scaling factor}$$

- **When the Torque Signal Type is Pulse**

The value is used as a scaling factor in the equation given in “Setting the Torque Signal Pulse Count” in section 1.6

- **Setting the Scaling Factor Used to Compute the Motor Output**

You can specify the scaling factor used to compute the motor output (mechanical power) from the rotating speed and torque. Set the value in the range of 0.0001 to 99999.9999.

The equation is indicated below. The scaling factors of the rotating speed and torque are set so that the unit of the rotating speed is min^{-1} (or rpm) and the unit of torque is N-m. When the scaling factor of the motor output specified here is 1, the unit of the motor output P_m is W. Because the efficiency in section 1.9 is computed with the unit of P_m to be W, it is recommended that the scaling factor of each item be set so that the unit of P_m is W.

$$\text{Motor output } P_m = \frac{2 \times \pi \times \text{rotating speed}^{*1}}{60} \times \text{scaling factor} \times \text{torque}^{*2}$$

*1 Rotating speed derived in section 1.6.

*2 Torque derived in section 1.6.

- **Setting the Unit of Rotating Speed, Torque, and Motor Output**

- **Number of Characters**

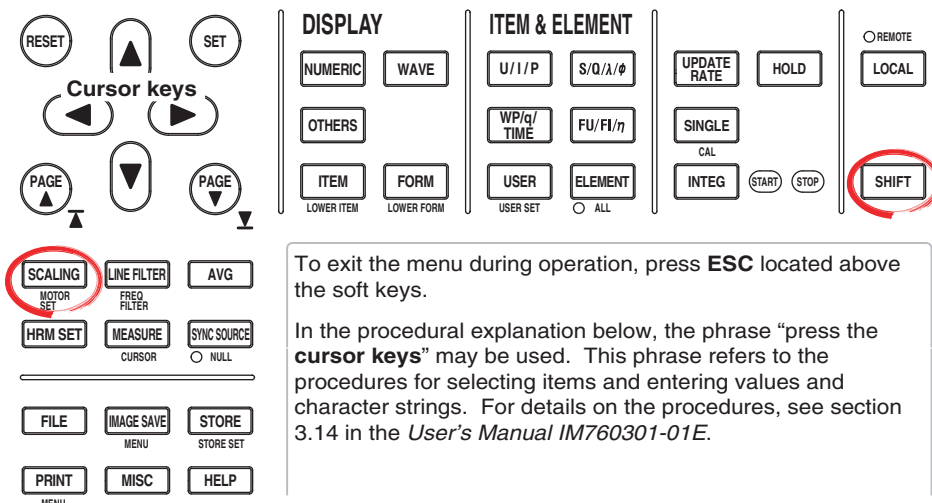
Eight characters or less.

- **Types of Characters**

Characters that are displayed on the keyboard or spaces.

1.8 Setting the Motor and Frequency Measurement Source for Computing the Sync Speed and Slip

Procedure



1. Press **SHIFT+SCALING (MOTOR SET)** to display the Motor Set dialog box.
- **Setting the Motor's Number of Poles**
 2. Press the **cursor keys** to select Pole.
 3. Press **SET**. A box for entering the number of poles appears.
 4. Press the **cursor keys** to set the number of poles.
 5. Press **SET** or **ESC** to close the box.

| Motor Set | | |
|-------------|------------|------------|
| Speed | Torque | Pm |
| Scaling | 1.0000 | 1.0000 |
| Unit | rpm | Nm |
| Sense Type | Analog | V |
| Speed | Torque | |
| Auto Range | OFF | OFF |
| Range | 20V | 20V |
| Line Filter | OFF | |
| Sync Source | None | |
| Pulse | | Rated Freq |
| Range Upper | 10000.0000 | 50.0000 |
| Range Lower | 0.0000 | -50.0000 |
| Rated Upper | 50.0000 | 15000Hz |
| Rated Lower | -50.0000 | 5000Hz |
| Pulse N | 60 | |
| Sync Speed | | |
| Pole | 2 | |
| Source | | |

1.8 Setting the Motor and Frequency Measurement Source for Computing the Sync Speed and Slip

- **Selecting the Frequency Measurement Source Signal (Voltage or Current Signal Supplied to the Motor)**

2. Press the **cursor keys** to select Sync Speed Source.
3. Press **SET**. A frequency measurement source selection box appears.
4. Press the **cursor keys** to select any of the target input signals for frequency measurement (see section 5.3 in the *User's Manual IM760301-01E*).

When the button to the left of the input signal in the selection box is highlighted, that is the source input signal for frequency measurement selected in section 5.3 in the *User's Manual IM760301-01E*.

5. Press **SET** to confirm the frequency measurement source.

The screenshot shows the 'Motor Set' menu with the following sections:

- Speed, Torque, Pm:** Each has a 'Scaling' field (all set to 1.0000), a 'Unit' dropdown (Speed: rpm, Torque: Nm, Pm: W), and a 'Sense Type' dropdown (all set to Analog).
- Speed, Torque:** Each has an 'Analog' section with 'Auto Range' (OFF), 'Range' (20V), and 'Line Filter' (OFF).
- Speed:** Has a 'Sync Source' dropdown set to 'None'.
- Pulse:** Has 'Range Upper' (10000.0000), 'Range Lower' (0.0000), 'Rated Upper', 'Rated Lower', and 'Pulse N' (60).
- Sync Speed:** Has a 'Pole' dropdown (2) and a 'Source' dropdown (11).
- Frequency Measurement Source Selection:** A grid of buttons for U1, U2, U3, U4, I1, I2, I3, I4. U1 and I1 are highlighted.
- Rated Freq:** Two dropdowns showing 1500Hz and 5000Hz.

Explanation

- **Setting the Motor's Number of Poles**

The number can be set in the range of 1 to 99. Sets the number of poles for the motor being measured.

- **Setting the Frequency Measurement Source Signal**

- Select the frequency measurement source from the choices below. The selectable items vary depending on the installed elements.
U1, I1, U2, I2, U3, I3, U4, and I4
- Select any of the source input signals for frequency measurement. When the button to the left of the input signal in the frequency measurement source selection box is highlighted, that is the source input signal for frequency measurement selected in section 5.3 in the *User's Manual IM760301-01E*. If you select an input signal that is not a frequency measurement source, an error results.
- In normal cases, the frequency measurement source (see section 5.3 in the *User's Manual IM760301-01E*) is set to the voltage or current supplied to the motor. If a frequency other than that of the voltage and current supplied by the motor is specified, the synchronous speed may not be determined correctly.

- **Equation for Deriving the Synchronous Speed**

The unit of synchronous speed is fixed to min^{-1} (or rpm). The equation is indicated below.

$$\text{Rotating speed SyncSp } (\text{min}^{-1}) = \frac{120 \times \text{frequency of the frequency measurement source (Hz)}}{\text{Motor's number of poles}}$$

1.8 Setting the Motor and Frequency Measurement Source for Computing the Sync Speed and Slip

- **Equation for Deriving the Slip**

The unit of synchronous speed is fixed to min^{-1} (or rpm). Therefore, to determine the slip, set the scaling coefficient of the rotating speed (see section 1.7) so that the unit of rotating speed is also min^{-1} (or rpm).

$$\text{Slip (\%)} = \frac{\text{Synchronous speed (min}^{-1}\text{)} - \text{rotating speed}^*(\text{min}^{-1}\text{)}}{\text{Rotating speed (min}^{-1}\text{)}} \times 100$$

* Rotating speed derived in section 1.6.

Note

Please select a stable voltage or current (supplied by the motor) with small distortion or noise for the frequency measurement source.

1.9 Computing the Motor Efficiency and Total Efficiency

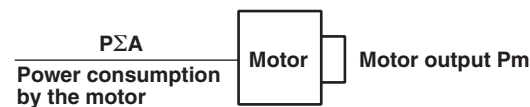
From the active power that the WT3000 measures and the motor output determined in section 1.7, the WT3000 can compute the motor efficiency (the ratio of the motor output versus the power consumption by the motor) and total efficiency*. Set the equation according to the procedures given in section 5.7 or 5.4 in the *User's Manual IM760301-01E*. Computation examples are indicated below.

* The ratio of the motor output versus the power consumption by the motor as well as the converter through which power is fed to the motor.

When the Motor Input Is Wired to ΣA

$$\text{Motor efficiency (\%)} = \frac{\text{Motor output } P_m^*(W)}{P_{\Sigma A}(W)} \times 100$$

* Motor output P_m derived in section 1.7.

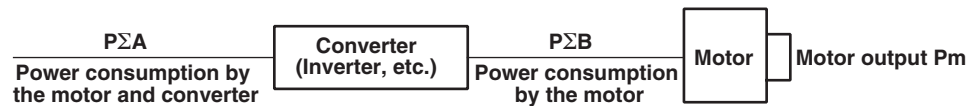


When the Converter and Motor Inputs Are Wired to ΣA and ΣB , Respectively

$$\text{Motor efficiency (\%)} = \frac{\text{Motor output } P_m^*(W)}{P_{\Sigma B}(W)} \times 100$$

$$\text{Total efficiency (\%)} = \frac{\text{Motor output } P_m^*(W)}{P_{\Sigma A}(W)} \times 100$$

* Motor output P_m derived in section 1.7.

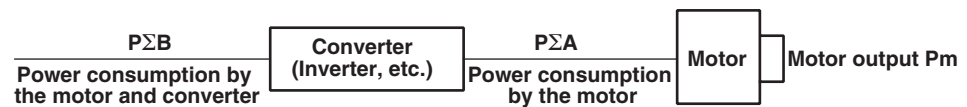


When the Converter and Motor Inputs Are Wired to ΣB and ΣA , Respectively

$$\text{Motor efficiency (\%)} = \frac{\text{Motor output } P_m^*(W)}{P_{\Sigma A}(W)} \times 100$$

$$\text{Total efficiency (\%)} = \frac{\text{Motor output } P_m^*(W)}{P_{\Sigma B}(W)} \times 100$$

* Motor output P_m derived in section 1.7.



Note

If ΣA or ΣB is a three-phase, three-wire (3P3W) system, the delta computation function (see chapter 6) can be used to make a 3P3W>3V3A transformation of ΣA or ΣB . From the 3P3W>3V3A transformation, you can determine one set of line voltage and common mode current that is not being measured.

1.10 Specifications of the Motor Evaluation Function

| Item | Specifications |
|--|---|
| Rotating signal and torque signal | <ul style="list-style-type: none"> For DC voltage (analog input) |
| Item | Specifications |
| Connector type | Isolated BNC connector |
| Input range | 1 V, 2 V, 5 V, 10 V, and 20 V |
| Effective input range | 0% to $\pm 110\%$ of the measurement range |
| Input resistance | Approx. 1 M Ω |
| Maximum allowable input | ± 22 V |
| Continuous maximum common mode voltage | ± 42 V _{peak} or less |
| Accuracy | $\pm (0.1\%$ of reading + 0.1% of range) |
| Temperature coefficient | $\pm 0.03\%$ of range/ $^{\circ}\text{C}$ |
| | <ul style="list-style-type: none"> For pulse input |
| Item | Specifications |
| Connector type | Isolated BNC connector |
| Frequency range | 2 Hz to 200 kHz |
| Amplitude input range | ± 12 V _{peak} |
| Effective amplitude | 1 V (peak-to-peak) or more |
| Input waveform | 50% duty ratio rectangular wave |
| Input resistance | Approx. 1 M Ω |
| Continuous maximum common mode voltage | ± 42 V _{peak} or less |
| Accuracy | $\pm (0.05\%$ of reading + 1 mHz) |

Measurement Function

| Item | Symbol and Meaning |
|-------------------|--|
| Rotating speed | Speed: Motor's rotating speed |
| Torque | Torque: Motor's torque |
| Synchronous speed | SyncSp |
| Slip (%) | Slip |
| Motor output | Pm: Motor's mechanical output (mechanical power) |

For the default values and displayed order of numeric data, see appendix 3 in the *User's Manual IM760301-01E*.

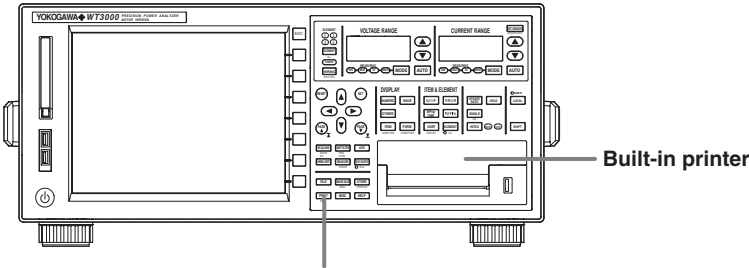
Symbols and Determination of Motor Evaluation Measurement Functions

| Measurement Functions during Normal Measurement | | Method of Determination, Equation |
|---|-----------------------------|--|
| Motor evaluation | Rotating speed | <p>When the type of input signal from the revolution sensor is DC voltage (analog signal) Input voltage from the revolution sensor • Scaling factor Scaling factor: Number of rotations per volt of input voltage</p> <p>When the type of input signal from the revolution sensor is pulse count $\frac{\text{Number of input pulses from the revolution sensor per minute}}{\text{Number of pulses per rotation}} \cdot \text{Scaling factor}$ Scaling factor: When the signal of the gear ratio or revolution sensor is a converted signal, you can specify the gear ratio for the scaling factor to determine the rotating speed before the gear change.</p> |
| | Torque | <p>When type of input signal from the torque meter is DC voltage (analog signal) Scaling factor • input voltage from the torque meter Scaling factor: torque per volt of input voltage</p> <p>When the type of input signal from the torque meter is pulse (Torque pulse coefficient • pulse frequency + torque pulse offset) • scaling factor Torque pulse coefficient and torque pulse offset: Calculated in the WT3000 from the torque values [N-m] at two points corresponding to the upper and lower limits of frequency. Scaling factor: Normally, use the value of 1. When using a unit other than N-m, set the conversion ratio of the unit.</p> |
| | Synchronous speed | <p>$120 \cdot \text{Frequency of the frequency measurement source (Hz)}$ Motor's number of poles</p> <ul style="list-style-type: none"> • The unit of synchronized speed is fixed to “min⁻¹ (or rpm).” • Normally, the frequency measurement source is set to the voltage or current that is supplied to the motor. The synchronized speed may not be determined correctly if a different signal is specified. |
| | Slip [%] | <p>$\frac{\text{SyncSp} - \text{Speed}}{\text{SyncSp}} \cdot 100$</p> |
| | Motor output P _m | <p>$\frac{2 \pi \cdot \text{Speed} \cdot \text{Torque}}{60} \cdot \text{Scaling factor}$</p> <p>When the unit of speed is “min⁻¹ (or rpm),” the unit of torque is “N-m,” and the scaling factor is 1, the unit of motor output P_m is “W.”</p> |

Set the efficiency equation or user-defined function to determine the motor efficiency and total efficiency.

2.1 Names and Functions of Parts of the Built-in Printer

Front Panel



PRINT key
Prints the screen image data or numeric data list.

SHIFT+PRINT (MENU) key
Feeds the paper and sets the screen image data and numeric data list printing.

Functional Description

Screen images and numeric data list can be printed on the built-in printer. Comments can be inserted in the screen images.

* For the procedure to print the screen image on a network printer, see section 5.4. The numeric data list cannot be printed on a network printer.

When auto print is used, screen images and numeric data lists can be printed automatically on the built-in printer at the specified print interval. In addition, you can print screen images and numeric data at the desired time by setting the reservation time for auto print start/stop. Printing is also possible by synchronizing to the integration time.

| | Output Format | | Auto Print |
|------------------|---------------|--------------|------------|
| | Screen Image | Numeric List | |
| Built-in printer | Yes | Yes | Yes |
| Network printer | Yes | No | No |

Yes: Printing is possible.
No: Printing is not possible.

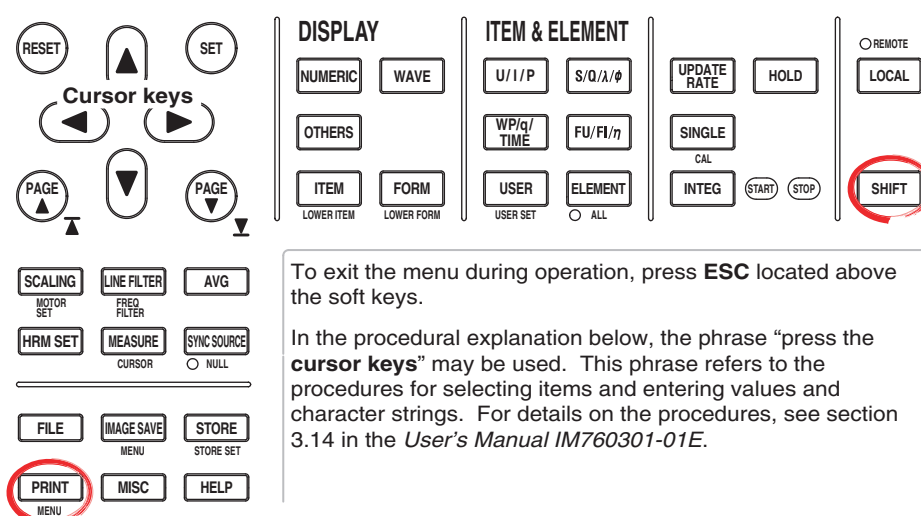
2.2 Loading the Roll Paper and Feeding the Paper

WARNING

A roll paper cutter is attached to the printer unit cover. Be careful not to injure your hand or fingers on the cutter.

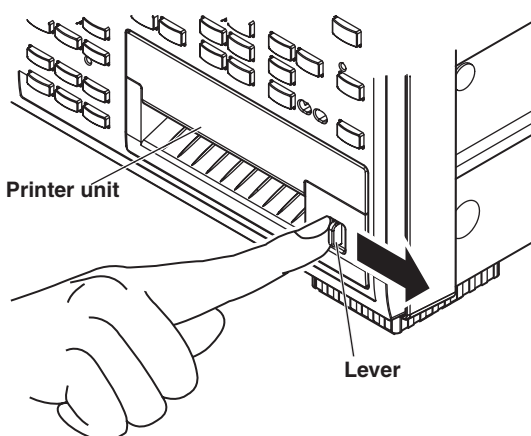
- Do not insert your finger into the printer unit opening where the roll paper is fed out.
- Do not let your hand or fingers come in contact with the cutter when opening the printer unit cover and loading the roll paper in the holder.

Procedure

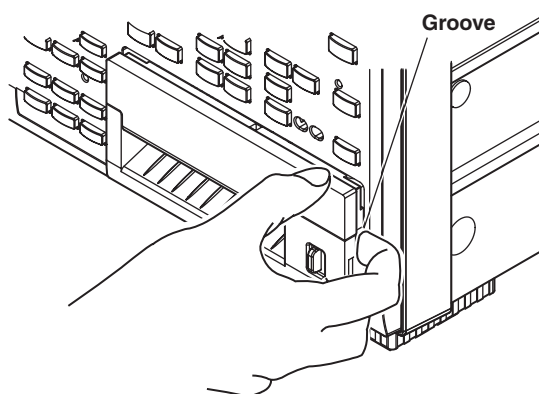


• Loading the Roll Paper

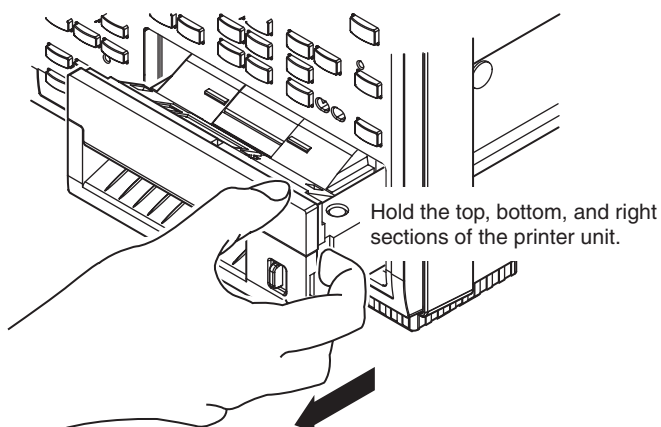
1. Slide the lever to the right. The printer unit comes out.



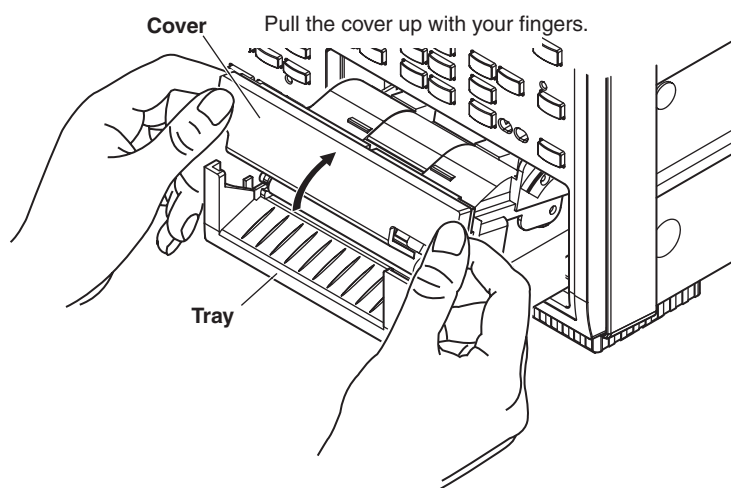
- Hook your finger in the groove on the right side of the printer unit.



- Hold the top, bottom, and right sections of the printer unit and pull the printer unit out until it stops (approximately 5 cm).

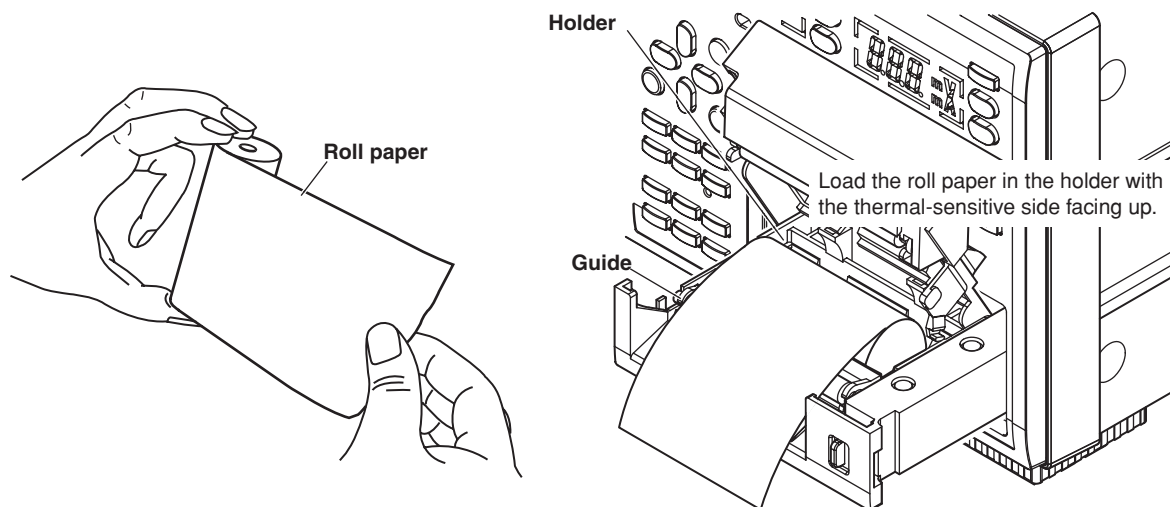


- While holding the left and right sides of the tray with your hands, pull up both sides of the front cover of the printer unit with your thumbs.

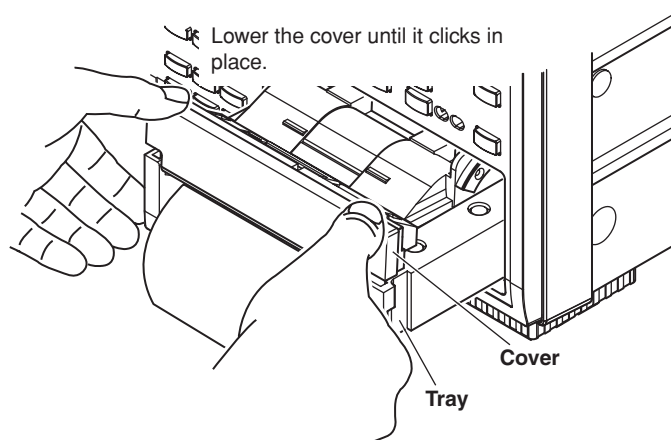
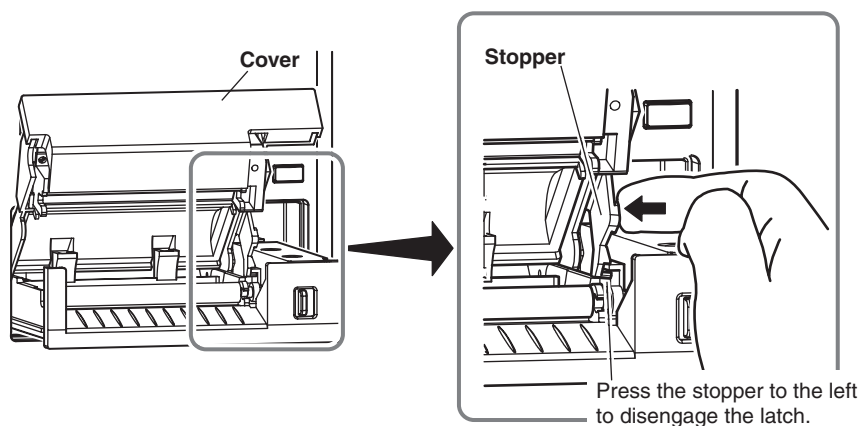


2.2 Loading the Roll Paper and Feeding the Paper

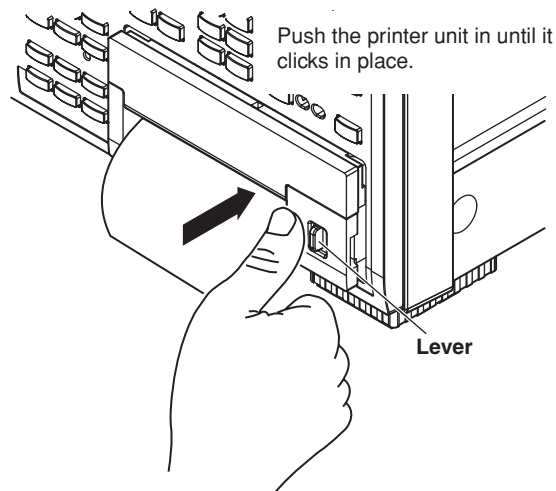
5. With approximately 10 cm of the paper unrolled, load the roll paper in the holder with the thermal-sensitive side facing up. Load the roll paper so that it fits into the guide.



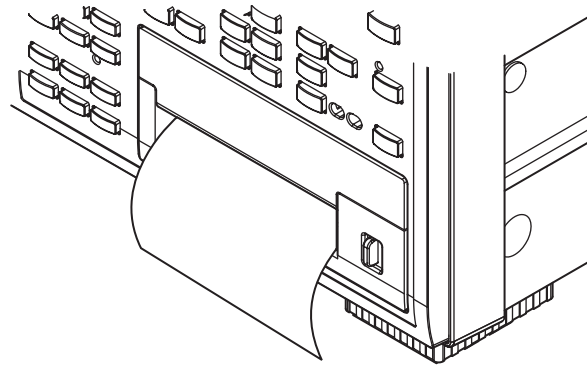
6. While pressing the stopper to the left so that the latch is disengaged, lower the cover. Support the tray from the bottom with both hands, and close the cover until it clicks in place.



7. Placing your thumb on the front panel (left of the lever) of the printer, push the printer unit in until it clicks in place.

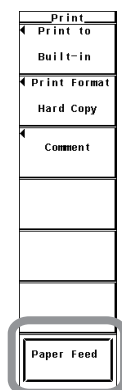


This completes the loading of roll paper.



• Feeding the Paper

1. Press **SHIFT+PRINT (MENU)** to display the Print menu.
2. Press the **Paper Feed** soft key. Each time the soft key is pressed, the roll paper is fed approximately 3 cm.



• Cutting the Roll Paper

To cut the paper after the paper roll is loaded and the printer cover is closed or after printing the measured data, pull the roll paper upward against the cover.

2.2 Loading the Roll Paper and Feeding the Paper

Explanation

- **Printer Roll Paper**

Use only the dedicated roll paper provided by YOKOGAWA. Do not use other types of roll paper. When using the printer for the first time, use the roll paper that is included in the package. Order extra rolls from your nearest YOKOGAWA dealer.

| | |
|----------------|-----------------------------|
| Part No. | B9316FX |
| Specifications | Thermalsensible paper, 10 m |
| Quantity | 10 rolls |

- **Handling Precautions of the Roll Paper**

The paper is a thermalsensible paper that changes color with the application of heat. Note the following points.

- **Storage Precautions**

The paper starts changing color at around 70°C. It is affected by heat, humidity, light, and chemicals regardless of whether the paper has been used or not.

- Store the paper rolls in a cool, dry, and dark place.
- After opening the package, use it quickly.
- If the paper is left in contact with plastic film containing plasticizers (such as a vinyl chloride film or Scotch tape) for an extended time, the paper will lose some of its ability to reproduce color. If you are going to store the paper in a folder, for example, use a folder made of paper stock or polypropylene.
- When using glue on the paper, do not use glue containing organic solvents such as alcohol or ether, as they will change the color of the paper.
- For prolonged storage, we suggest you copy the roll chart. Due to the characteristics of the thermalsensible paper, it may lose color over time.

- **Handling Precautions**

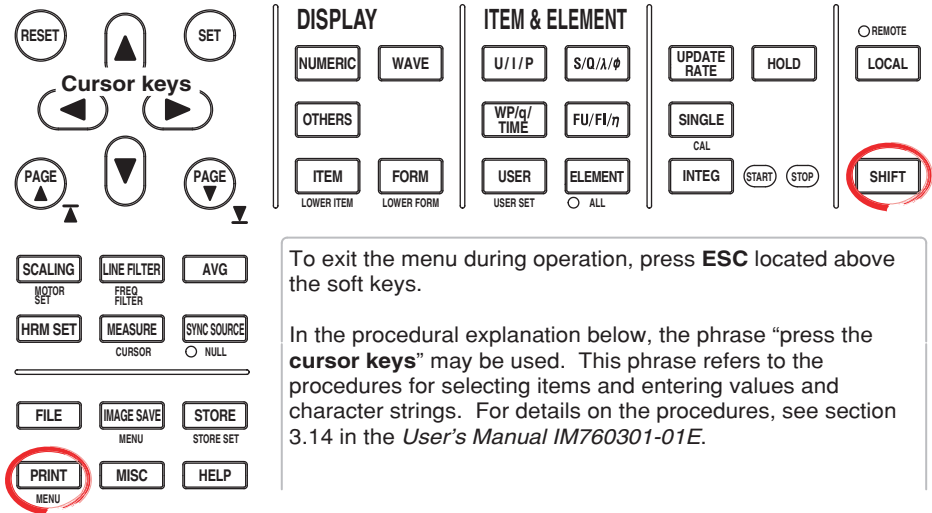
- Use only genuine paper rolls provided by YOKOGAWA.
- Touching the paper with sweaty hands can leave finger prints or blur the printing.
- Rubbing the surface with a hard object can cause the paper to change color due to the heat caused by friction.
- If chemicals, oil, or other liquids come in contact with the paper, the paper may change color or the printing may fade.

Note

- If you open the printer cover immediately after you cut the roll paper, repeat steps 5 to 7.
 - After loading the roll paper and closing the printer cover, feed the paper to check that the paper is being fed correctly. If the paper is not being fed evenly, repeat steps 1 to 7.
 - If you reverse the direction in which the roll paper is placed, the printer head does not make contact with the thermal-sensitive surface. If this happens, nothing may be printed, or the paper may not feed properly. Be sure to load the roll paper in the correct direction in the holder.
-

2.3 Printing Screen Images on the Built-in Printer

Procedure



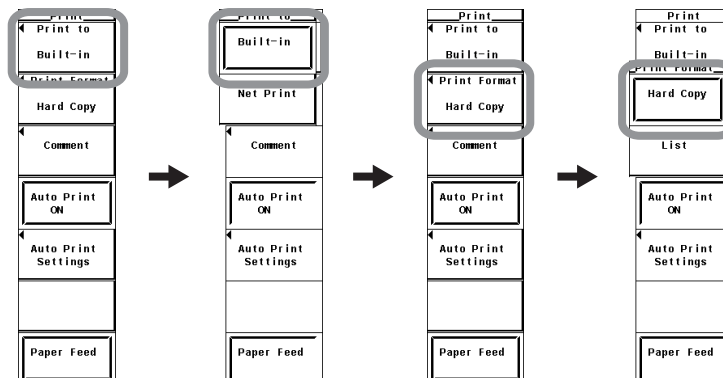
1. Press **SHIFT+PRINT (MENU)** to display the Print menu.

• Selecting the Printer

2. Press the **Print to** soft key to display the Print to menu.
3. Press the **Built-in** soft key.

• Selecting the Print Format

4. Press the **Print Format** soft key to display the Print Format menu.
5. Press the **Hard Copy** soft key.

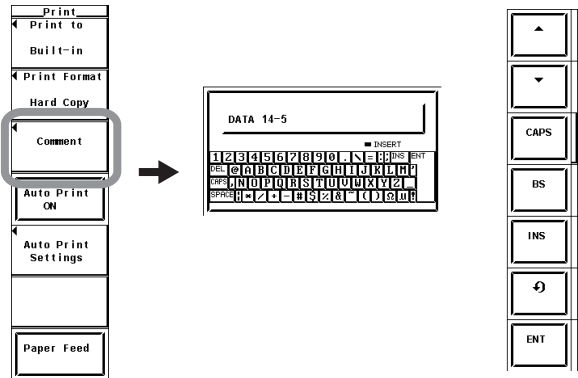


2.3 Printing Screen Images on the Built-in Printer

• Setting Comments

- 2. Press the **Comment** soft key. A keyboard appears.
- 3. Use the **keyboard** to enter the comment.

For keyboard operations, see section 3.14, “Entering Values and Strings” in the *User’s Manual IM760301-01E*.



• Executing the Print Operation

Check that the roll paper is loaded properly, and that the printer unit is pushed into the correct position.

- 4. Switch to the screen you wish to print.
- 5. Press **PRINT** to print the screen image.

• Aborting the Print Operation

- 6. Press **PRINT** while the print operation is in progress to abort the operation.

Explanation

Screen images can be printed on the built-in printer (option).

Setting Comments

The comment that you entered is displayed at the bottom of the screen. The comment on the screen is also printed as a screen image.

Number and Types of Characters That Can Be Used

| Item | Number of Characters | Characters That Can Be Used |
|---------|----------------------|--|
| Comment | 0 to 20 * characters | Characters that are displayed on the keyboard and spaces |

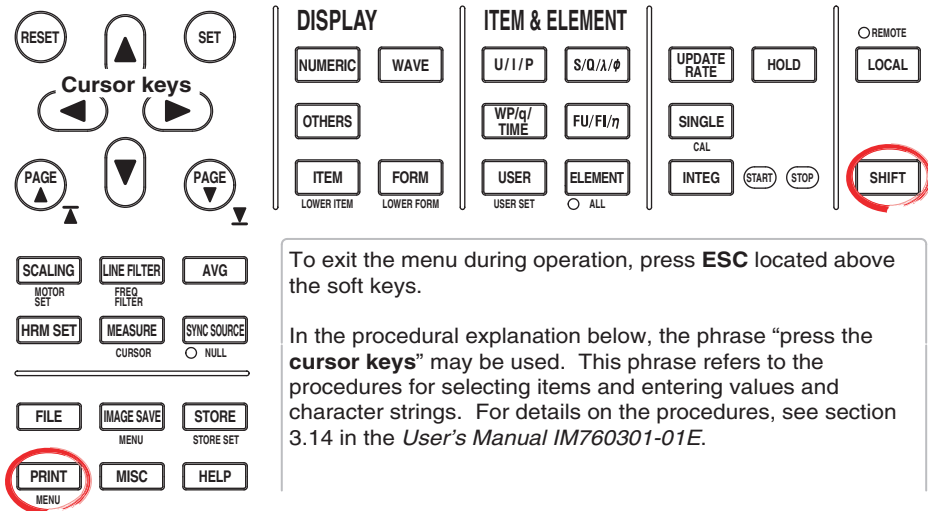
* More than 20 characters can be entered for the comment, but only the first 20 characters are displayed on the screen.

Note

If the roll paper runs out while printing, an error is displayed, and the screen image data being printed is discarded. If this happens, load a new roll paper, show the screen you wish to print again, and execute the print operation.

2.4 Printing Numeric Data Lists on the Built-in Printer

Procedure



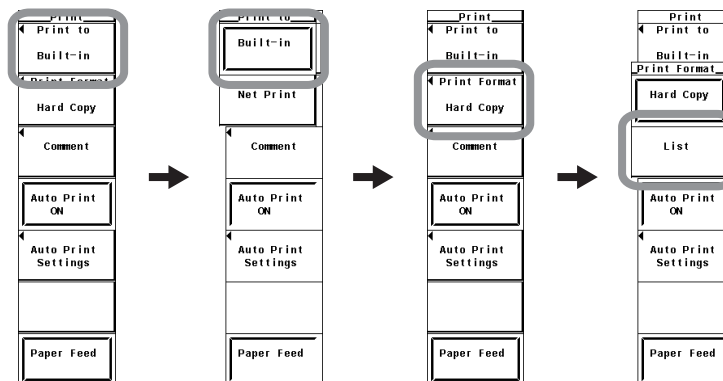
1. Press **SHIFT+PRINT (MENU)** to display the Print menu.

• Selecting the Printer

2. Press the **Print to** soft key to display the Print to menu.
3. Press the **Built-in** soft key.

• Selecting the Print Format

4. Press the **Print Format** soft key to display the Print Format menu.
5. Press the **List** soft key.



2-10

- **Printing or Not Printing (ON/OFF) the Header Information**

10. Press the **Information** soft key to select ON or OFF.



- **Executing the Print Operation**

11. Press **PRINT** to print the numeric data list.

- **Aborting the Print Operation**

12. Press **PRINT** while the print operation is in progress to abort the operation.

Explanation

- **Header Information**

The following items are available as header information.

- Measurement mode (Normal)*1
- Date/Time*1
- Measurement range of each element*2
- PLL source*2

Turning ON/OFF Header Information Printing

- ON: Prints the header information.
- OFF: Does not print the header information.

*1 Even if Information is set to OFF, the measurement mode and date/time are always printed.

*2 Only installed elements are applicable for the selection.

- **Selecting the Numeric Data**

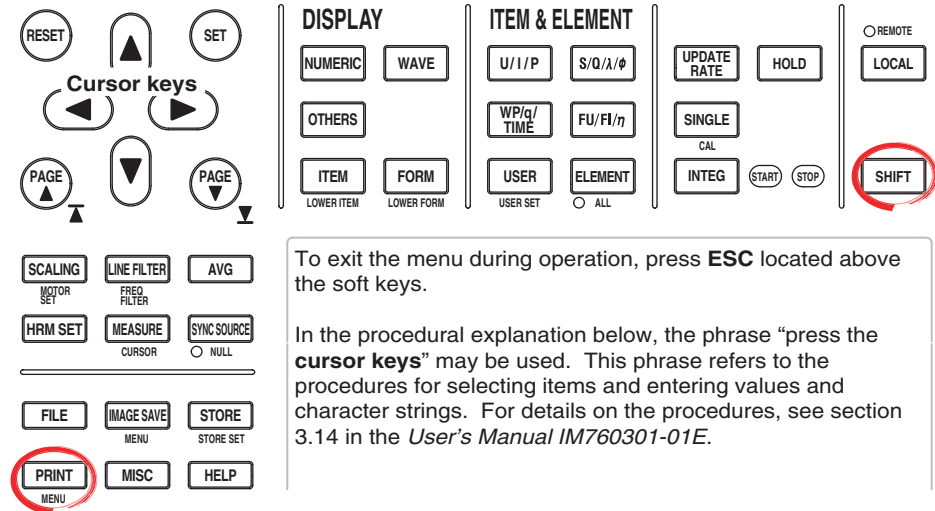
- Only installed elements and wiring units are applicable for the selection.
- The harmonic order range is DC (0th) to the Max Order specified in section 7.5.

- **Print Format of the Numeric Data List**

- The selected numeric data items are printed.
- For harmonic order data, the elements and measurement functions are printed horizontally, and the order list is printed vertically.

2.5 Auto Print

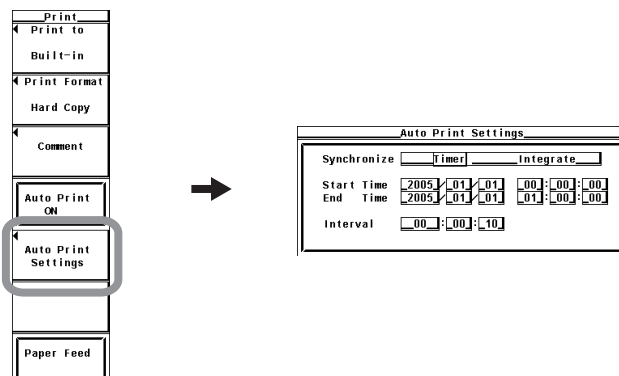
Procedure



1. Press **SHIFT+PRINT (MENU)** to display the Print menu.
- **Setting the Print Destination, Output Format, Etc.**
 2. Set the print destination to the built-in printer, and set the output format according to the procedures given in sections 2.3 and 2.4.
 - **Selecting the Synchronization Mode**
 3. Press the **Auto Print Setting** soft key to display the Auto Print Setting menu.
 4. Press the **cursor keys** to select Synchronize.
 5. Press **SET** to select Timer or Integrate.

If you select Timer, proceed to step 6 in “Print Timer Synchronized Auto Print” on the next page.

If you selected Integrate, proceed to step 6 in “Integration Synchronized Auto Print” on page 2-14.



Print Timer Synchronized Auto Print

- **Setting the Reservation Time**

5. Press the **cursor keys** to select one of the reservation year, month, date, hour, minute, and second boxes for specifying when the printing will start (Start Time).
6. Press **SET** to display the entry box.
7. Press the **cursor keys** to set the year, month, date, hour, minute, or second that you selected in step 5.
8. Press **SET** or **ESC** to close the box.
9. Repeat steps 5 to 8 to set the year, month, date, hour, minute, and second.
10. Press the **cursor keys** to select one of the reservation year, month, date, hour, minute, and second boxes for specifying when the printing will end (End Time).
11. Repeat steps 6 to 8 to set the year, month, date, hour, minute, and second.

- **Setting the Print Interval**

12. Press the **cursor keys** to select the hour, minute, or second box of the print interval.
13. Press **SET** to display the entry box.
14. Press the **cursor keys** to set the hour, minute, or second that you selected in step 12.
15. Press **SET** or **ESC** to close the box.
16. Repeat steps 12 to 15 to set the hour, minute, and second.

- **Executing the Auto Print**

Check that the roll paper is loaded properly, and that the printer unit is pushed into the correct position.

17. Press the **Auto Print ON** soft key. If the reservation time for starting the printing is later than the time when Auto Print ON is pressed, the PRINT key blinks, and the WT3000 enters the Ready state. When the reservation time for starting the printing is reached, the PRINT key illuminates (stops blinking), and the auto print is started. If the reservation time for starting the printing is earlier than the time when Auto Print ON is pressed, the PRINT key illuminates, and auto print starts.

- **Aborting the Print Operation**

18. Press **PRINT** while the print operation is in progress to abort the operation.

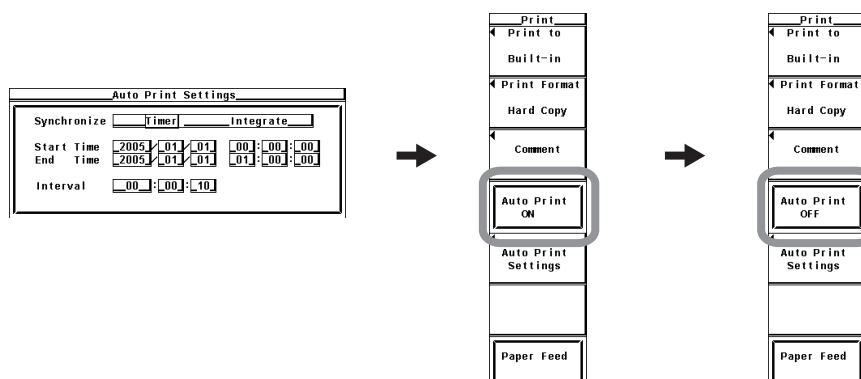
- **Terminating the Auto Print**

- **Stopping the Auto Print**

8. Press the **Auto Print OFF** soft key while auto print is in progress to stop the auto print. The PRINT key turns OFF.

- **Automatically Stopping the Auto Print**

8. When the reservation time for stopping the auto print is reached, the auto print stops. The PRINT key turns OFF.



Integration Synchronized Auto Print

- **Setting the Print Interval**

5. Press the **cursor keys** to select the hour, minute, or second box of the print interval.
6. Press **SET** to display the entry box.
7. Press the **cursor keys** to set the hour, minute, or second that you selected in step 12.
8. Press **SET** or **ESC** to close the box.
9. Repeat steps 5 to 8 to set the hour, minute, and second.

- **Executing the Auto Print**

Check that the roll paper is loaded properly, and that the printer unit is pushed into the correct position.

10. Press the **Auto Print ON** soft key. If Auto Print is turned ON while integration is not started, the PRINT key blinks, and the WT3000 enters the Ready state. When integration starts, the PRINT key illuminates (stops blinking), and the auto print is started. If Auto Print is turned ON while integration is in progress, the PRINT key illuminates, and the auto print starts

- **Aborting the Print Operation**

11. Press **PRINT** while the print operation is in progress to abort the operation.

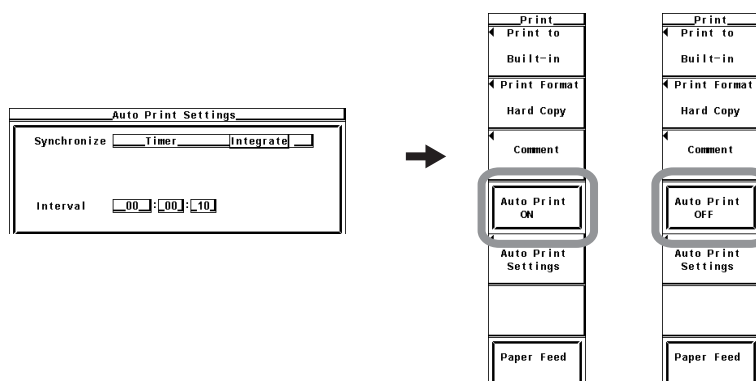
- **Terminating the Auto Print**

- **Stopping the Auto Print**

8. Press the **Auto Print OFF** soft key while auto print is in progress to stop the auto print. The PRINT key turns OFF.

- **Automatically Stopping the Auto Print**

8. When the integration stops, auto print also stops. The PRINT key blinks.
9. Press the **Auto Print OFF** soft key to turn the PRINT key OFF.



Explanation

When auto print is used, screen images and numeric data lists can be printed automatically on the built-in printer at the specified print interval.

- **Setting the Print Destination, Output Format, Etc.**

To use the auto print function, you must set the print destination to the built-in printer and set the output format (screen image/numeric data) and other settings. For the procedure, see section 2.3 or 2.4.

Note

- If numerous measurement functions are set as print items, printing may take a long time. Set the print interval longer than the time needed for printing.
- If you operate the keys or perform communications at the time of printing, the print start time may be delayed, or the printing may take a long time.

- **Selecting the Synchronization Mode of the Auto Print**

You can select the method used to start/stop the auto print from the following:

- **Timer:** Starts/Stops printing in sync with preset reservation times (start and stop times) (print timer synchronized auto print).
- **Integrate:** Starts/Stops printing in sync with integration start/stop (integration synchronized auto print).

- **Setting the Reservation Time**

Set the time to start/stop the auto print in year:month:day, hour:minute:second. The start and stop times can be specified only when the synchronization mode is set to Timer. Make sure the reservation time for stopping the auto print is after the reservation time for starting the auto print.

The selectable range of the values is as follows:

Year: 4-digit year

Hour:Minute:Second: 00:00:00 to 23:59:59

Note

- The reservation time allows up to 31 days to be specified for February. If an invalid time is specified, an error message is displayed at the time of execution of the auto print. Reset the reservation time in this case.
- Leap years are recognized at the time of execution of the auto print.

- **Setting the Print Interval**

Set the time interval for carrying out auto print in hour:minute:second. The selectable range varies depending on the data update rate as follows:

- When the data update rate is less than 10 s: 00:00:10 to 99:59:59
- When the data update rate is greater than or equal to 10 s: 00:01:00 to 99:59:59

In integration synchronized auto print, the print interval is rounded up to an integer multiple of the data update rate. For example if the data update rate is set to 5 s and the print interval is set to 21 s, the print interval is set to 25 s.

Note

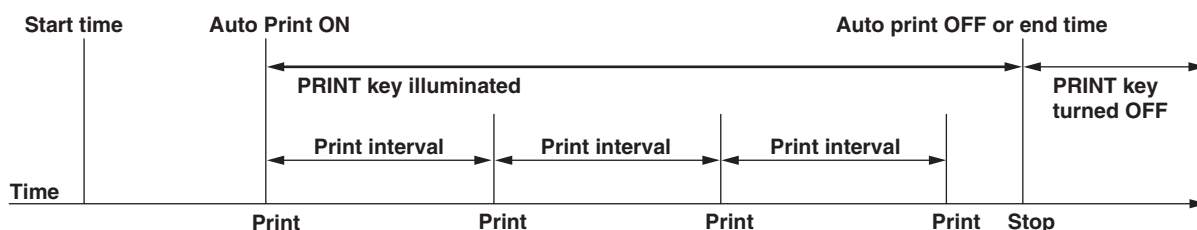
- The print interval can be set to a value smaller than the minimum value indicated above. If an invalid time is specified, an error message is displayed at the time of execution of the auto print. Reset the reservation time in this case.
-

- **Limitations When Auto Print is in Progress**

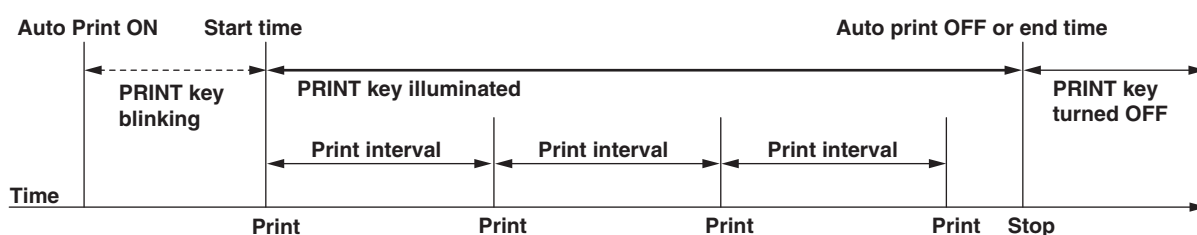
- To use the auto print function, you must set the print destination to the built-in printer and set the output format and other settings. For the procedure, see section 2.3 or 2.4.
- The settings of the following functions cannot be changed while auto print is in progress.
The synchronization mode, reservation time and interval of auto print; printer output items; wiring system; crest factor; synchronization source; data update rate; setting or execution of store/recall; and loading of setup parameter files
- If the following operation is carried out when auto print is to be executed, the auto print is not executed.
 - Formatting the storage medium
 - Accessing the storage medium such as saving data or settings
 - Carrying out an FTP server command
 - Printing manually or through communication commands
- If the print format is set to Hard Copy and an error or warning message is shown on the screen when the auto print is executed, the screen image including the message is printed. The message is automatically cleared after the printing. This prevents the screen images from being covered by the message on subsequent auto prints.

- **Print Timing of the Print Timer Synchronized Auto Print**

- When the start time is before turning Auto Print ON



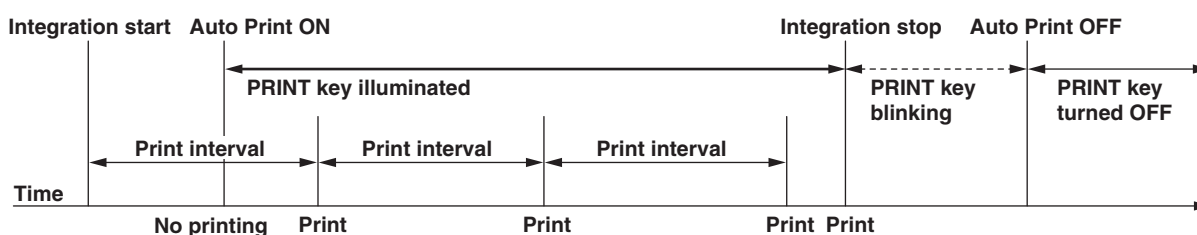
- When the start time is after turning Auto Print ON



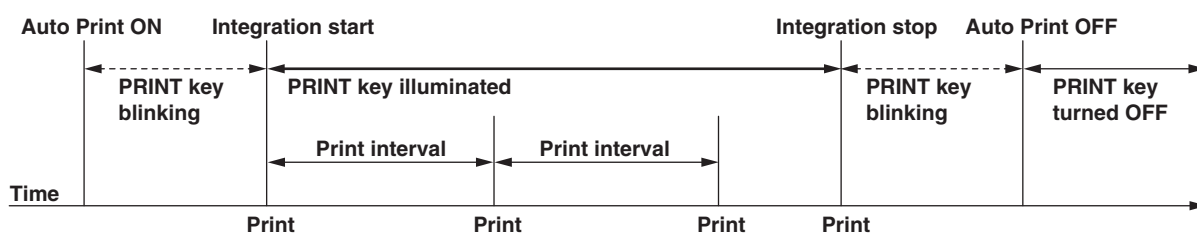
- **Print Timing of the Integration Synchronized Auto Print**

Auto print is executed based on the integration start time.

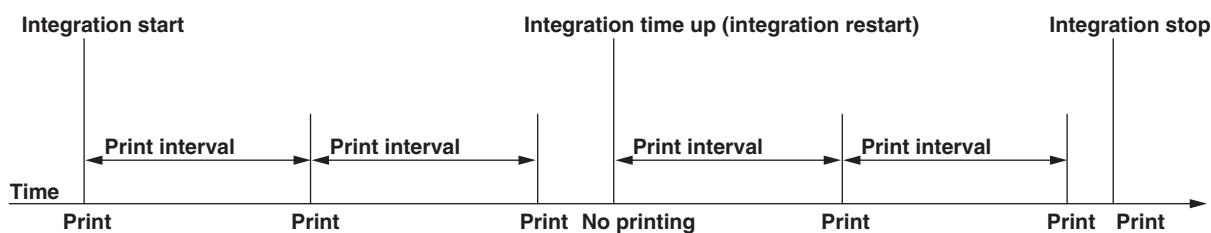
- When integration start is before turning Auto Print ON



- When integration start is after turning Auto Print ON

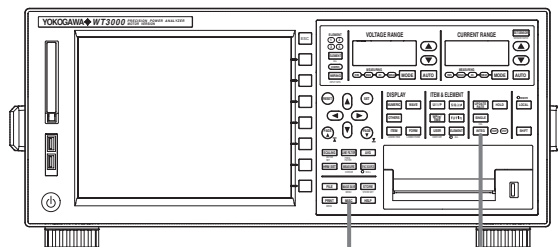


- Integration time and print interval during repetitive integration mode or real-time repetitive integration mode
When the integration timer expires, auto print is repeated based on that time.



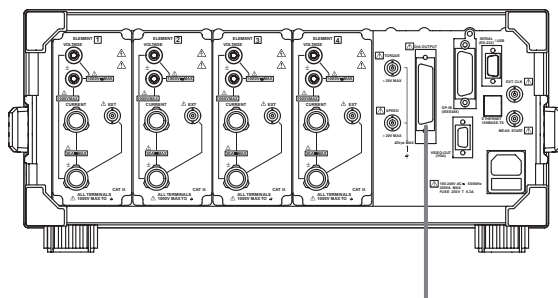
3.1 Part Names and Functions of D/A Output

Front Panel



- MISC**
Sets the items necessary for D/A output.
- INTEG**
Sets the rated time of integrated D/A output.

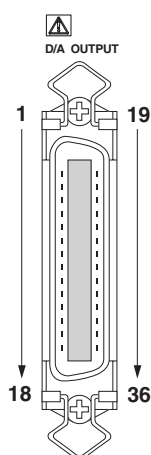
Rear Panel



- D/A output and remote control (option)**
D/A output: Outputs numeric data that has been converted to analog DC voltage.
Remote control: Controls the WT3000 using an external signal between 0 to 5 V.

Pin Arrangement and Signal Assignment of the D/A Output Connector

The pin arrangement and assignments of the connector are as follows:



| Pin No. | Signal Name | Pin No. | Signal Name |
|---------|-------------|---------|-------------|
| 1 | D/A CH1 | 19 | D/A CH2 |
| 2 | D/A CH3 | 20 | D/A CH4 |
| 3 | D/A CH5 | 21 | D/A CH6 |
| 4 | D/A CH7 | 22 | D/A CH8 |
| 5 | D/A CH9 | 23 | D/A CH10 |
| 6 | D/A CH11 | 24 | D/A CH12 |
| 7 | D/A CH13 | 25 | D/A CH14 |
| 8 | D/A CH15 | 26 | D/A CH16 |
| 9 | D/A CH17 | 27 | D/A CH18 |
| 10 | D/A CH19 | 28 | D/A CH20 |
| 11 | D/A COM | 29 | D/A COM |
| 12 | D/A COM | 30 | D/A COM |
| 13 | D/A COM | 31 | D/A COM |
| 14 | EXT PRINT | 32 | EXT RESET |
| 15 | EXT STOP | 33 | EXT START |
| 16 | EXT SINGLE | 34 | EXT HOLD |
| 17 | INTEG BUSY | 35 | EXT COM |
| 18 | EXT COM | 36 | EXT COM |

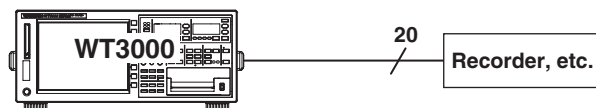
Note

D/A COM and EXT COM are connected internally.

Functional Description

- **D/A Output**

The numeric data measured on the WT3000 can be output as analog signals to other instruments. The analog signal is DC voltage of ± 5 V FS. The numeric data of up to 20 items can be output.

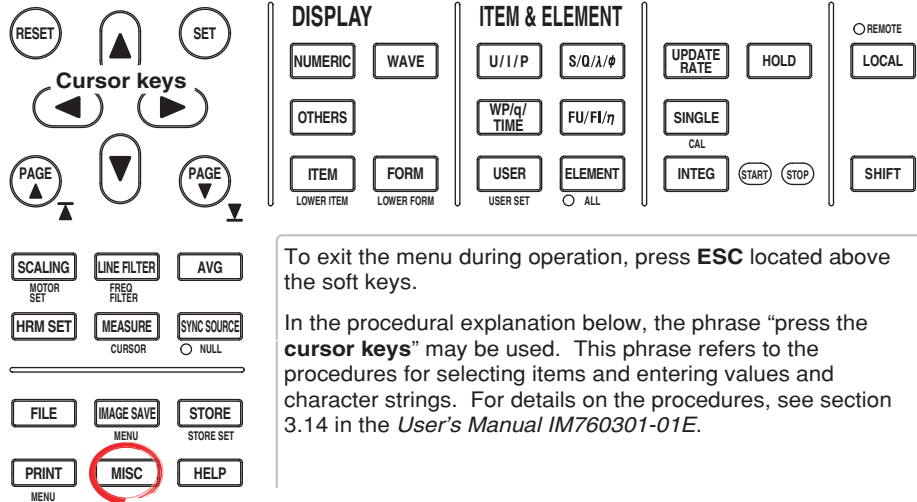


- **Remote Control**

Hold, single measurement, integration start/stop/reset, and print output can be controlled externally.

3.2 Setting the D/A Output

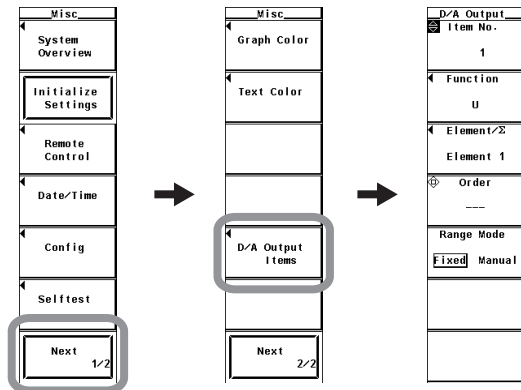
Procedure



To exit the menu during operation, press **ESC** located above the soft keys.

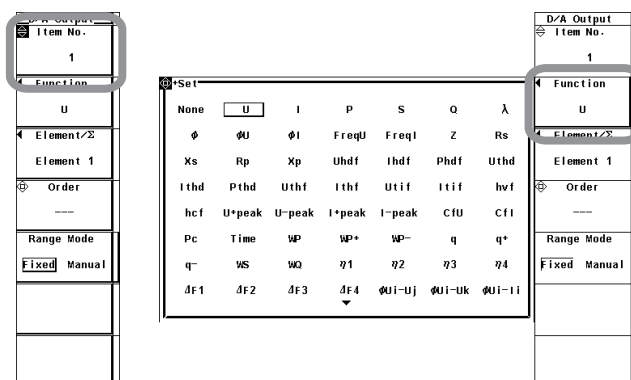
In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key to display the Next 2/2 menu.
3. Press the **D/A Output Items** soft key to display the D/A Output menu.



Setting the D/A Output Items

- **Selecting the Target Channel**
 4. Press the **cursor keys** to select a value between 1 and 20.
- **Selecting the Measurement Function**
 5. Press the **Function** soft key. The measurement function selection box appears.
 6. Press the **cursor keys** to select any of the measurement functions starting with None.
 7. Press **SET** to confirm.

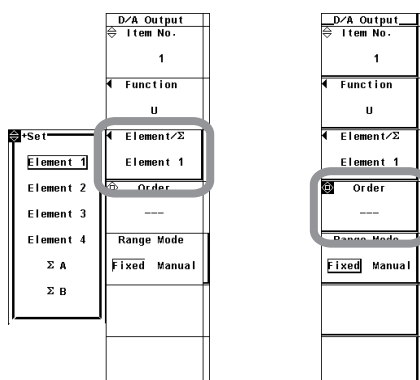


- **Selecting the Element/Wiring Unit**
 8. Press the **Element/Σ** soft key. The element/wiring unit selection box appears.
 9. Press the **cursor keys** to select any of the elements/wiring units starting with Element1.
 10. Press **SET** to confirm.
- **Selecting the Harmonic Order (Applicable Only on Models with the Harmonic Measurement Option)**

This is displayed only on models with the harmonic measurement option.

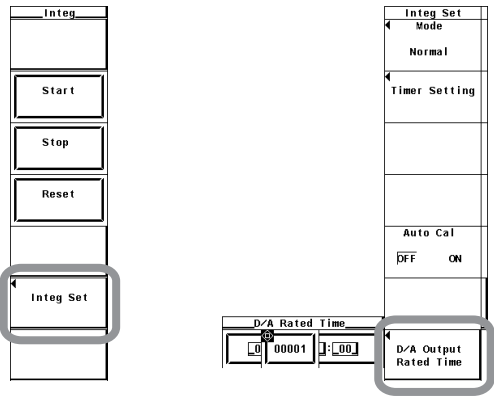
 11. Press **Order** soft key.
 12. Press the **cursor keys** to select the order from --- (normal measured value) and 0 to the maximum measured order (see section 7.5).

To output measurement functions related to integration through the D/A output, proceed to step 13.



Setting the Rated Time of Integrated D/A Output

- 13. Press **INTEG** to display the Integ menu.
- 14. Press the **Integ Set** soft key to display the Integ Set menu.
- 15. Press the **D/A Output Rated Time** soft key to display the D/A Rated Time dialog box.
- 16. Press the **cursor keys** to select the hour, minute, or second box.
- 17. Press **SET**. An entry box appears.
- 18. Press the **cursor keys** to set the hour, minute, or second that you selected in step 16.
- 19. Press **SET** or **ESC** to close the box.
- 20. Repeat steps 16 to 19 to set the hour, minute, and second.



Checking the D/A Output Items

- 1. Press **SHIFT+WIRING**(INPUT INFO.). **Power Element Settings** appears.
- 2. Press **PAGE ▼** to show **DA Output Settings** (a list of D/A output settings). The relation table of D/A output channels and measurement functions is displayed.

D/A Output Settings

| | Item | Rate |
|-------|-------|-------|
| Ch.1 | Urms1 | Fixed |
| Ch.2 | Irms1 | Fixed |
| Ch.3 | P1 | Fixed |
| Ch.4 | S1 | Fixed |
| Ch.5 | Q1 | Fixed |
| Ch.6 | λ1 | Fixed |
| Ch.7 | φ1 | Fixed |
| Ch.8 | IU1 | Fixed |
| Ch.9 | FI1 | Fixed |
| Ch.10 | ---- | Fixed |
| Ch.11 | ---- | Fixed |
| Ch.12 | ---- | Fixed |
| Ch.13 | ---- | Fixed |
| Ch.14 | ---- | Fixed |
| Ch.15 | ---- | Fixed |
| Ch.16 | ---- | Fixed |
| Ch.17 | ---- | Fixed |
| Ch.18 | ---- | Fixed |
| Ch.19 | ---- | Fixed |
| Ch.20 | ---- | Fixed |

3.2 Setting the D/A Output

Explanation

The numeric data can be output using ± 5 -V FS DC voltage from the D/A output connector on the rear panel. Up to 20 items (channels) can be specified.



CAUTION

Do not short the D/A output terminal or apply external voltage to it. If you do, the instrument may malfunction.

D/A Output Item

- **Selecting the Measurement Function**
 - The types of measurement functions that can be selected are the items that are indicated in “Types of Measurement Functions during Normal Measurement” of section 2.2, “User-Defined Function” and “Corrected Power” of section 1.5, “Measurement Functions of Integration” of section 1.6 in the *User’s Manual IM760301-01E*, as well as “Motor Evaluation Function (Motor Version)” of chapter 1, “Delta Computation (Option)” of chapter 6, and “Harmonic Measurement (Option)” of chapter 7 in this manual.
 - You can also select not to output the measurement functions (None). For channels that are set to None, 0 V is output since no corresponding data exists.
 - If the range mode (see section 3.3) is set to fixed, the D/A output of a channel whose measurement function is set to Z, Rs, Xs, Rp, Xp, or F1 to F20 is fixed to 0 V. It is output when the range mode is set to manual.
- **Selecting the Element/Wiring Unit**
 - You can select the element/wiring unit from the choices below. The selectable items vary depending on the installed elements.
Element1, Element2, Element3, Element4, ΣA , and ΣB
 - If there are no elements that are assigned to the selected wiring unit, there is no numeric data. Thus, 0 V is output in this case. For example, if elements are assigned to ΣA and no elements are assigned to ΣB , then 0 V is output for the measurement function of ΣB .

- **Changing the Harmonic Order of the Measurement Function of Harmonic Measurement**

The measured order can be set to normal measured value (---) or from dc (0th order) up to 100th order.

Note

- For the meanings of the measurement function symbols that are output, see section 2.2, "Measurement Function and Measurement Period", 1.5, "Computation," 1.6, "Integration", and appendix 1, "Symbols and Determination of Measurement Functions" in the *User's Manual IM760301-01E* as well as chapter 1, "Motor Evaluation Function," chapter 6, "Delta Computation", and chapter 7, "Harmonic Measurement" in this manual.
- For details on the wiring units expressed as ΣA and ΣB , see section 4.1, "Selecting the Wiring System" in the *User's Manual IM760301-01E*.
- 0 V is output in places where the measurement function is not selected or there are no numeric data.
- The harmonic order can be set to normal measured value (---) or from dc (0th order) up to 100th order. However, the numeric data up to the upper limit of measured order (see section 7.9) that is automatically determined from the minimum measured order specified in section 7.5 to the PLL source frequency is the data determined by the harmonic measurement. For harmonic orders less than the minimum measured order specified in section 7.5 (for example, 0th order when Min Order is set to 1st order) and those greater than the maximum measured order, the output is 0 V.
- If scaling factors such as VT ratio, CT ratio, and power coefficient are specified on the voltage, current, and power, and the scaling is ON, 100% (5 V) is output when the scaled value is equal to the scaled rated value (measurement range \times scaling factor).
- For Σ functions, 100% (5 V) is output when the input is equal to the total value that is obtained when the rated value is input to each corresponding element. If different scaling factors are placed on each element, 100% (5 V) is output when the scaled value is equal to the scaled rated value (measurement range \times scaling factor).

3.2 Setting the D/A Output

Rated Time of Integrated D/A Output

In the case of integrated values, the integrated value that is obtained while continuously applying a rated value (same value as the measurement range) for the specified time is taken to be 100%. The D/A output at that point is 5 V. The D/A output from the integrated value of 0 (0 V) to the integrated value of 100% (5 V) is assumed to change linearly with time. The D/A output value is determined by the level of the actual input with respect to this assumed line (see the figure on the next page).

Setting the Rated Time of Integrated D/A Output

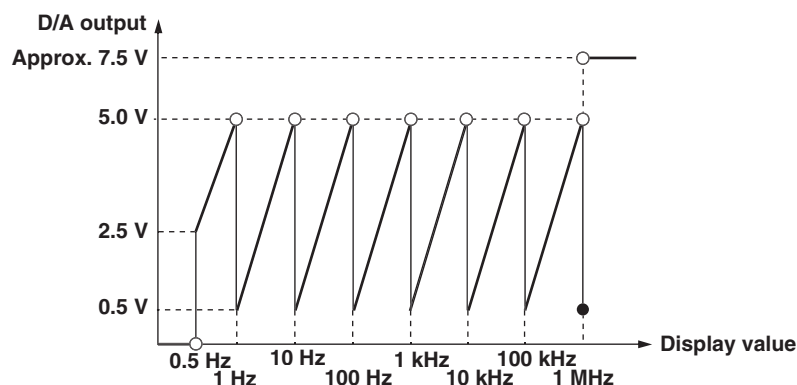
- Set the time in units of hour : minute : second in the following range.
00000:00:00 to 10000:00:00
- This setting is valid in the manual integration mode.
- For normal integration and repetitive integration modes (includes real-time), the time specified for the timer is the rated time of integrated D/A output.

Note

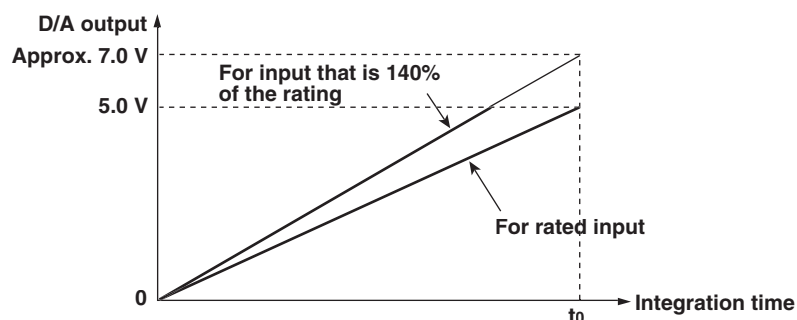
When the rated time of integrated D/A output is 00000:00:00, the D/A output of the integrated value is fixed to 0 V.

Relationship between the Output Items and D/A Output Voltages

- Frequency (Simplified Figure Below)

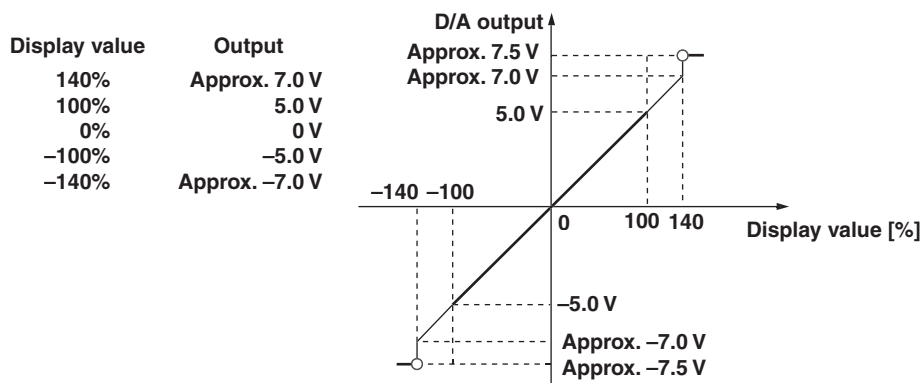


- Integration Value



t_0 : Integrated D/A output rated time when in manual integration mode
Time specified for the timer when in standard integration or repetitive (continuous) integration mode

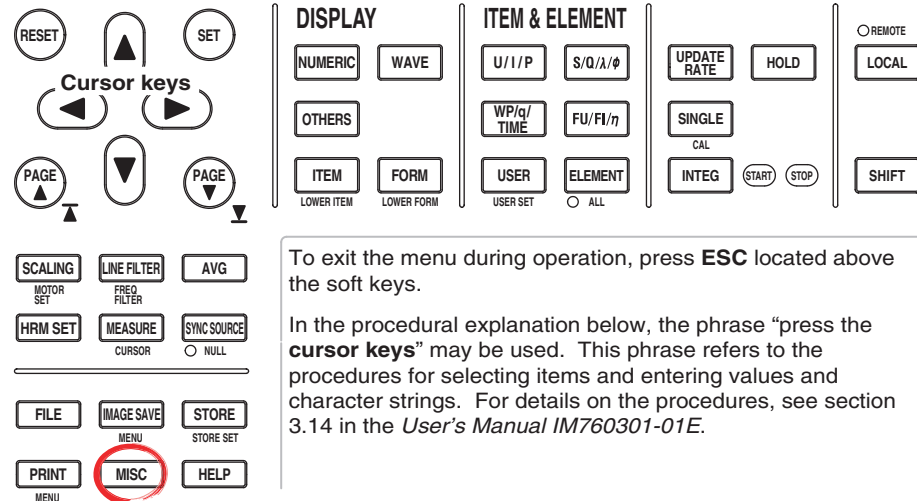
- Other Items



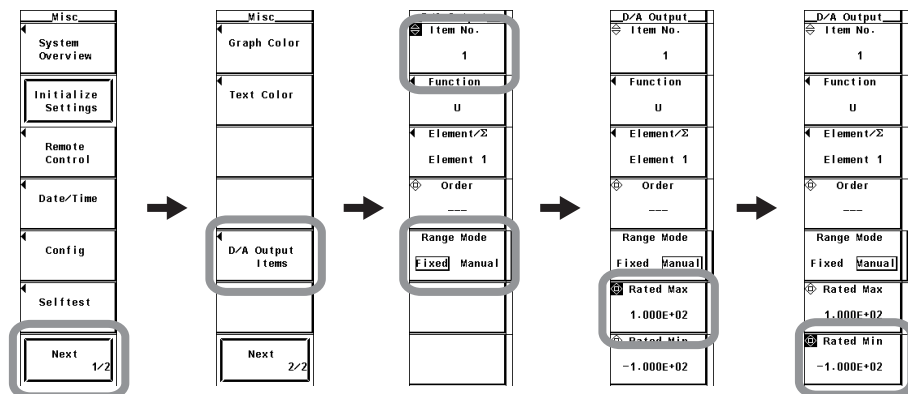
- λ and ϕ are not output outside ± 5 V. If the display format is ϕ is 360 degrees (360° format), ϕ is output in the range of 0 V to +5 V. If the display format is ϕ is 180 Lead/lag (180° lag to 180° lead), ϕ is output in the range of -5 V to +5 V. When an error occurs, approximately 7.5 V is output. For U-pk and I-pk only, approximately -7.5 V is output when an error occurs.
 - For η_1 to η_4 , Uhdf, lhdf, Phdf, Uthd, lthd, Pthd, Uthf, lthf, hvf, hcf, and Slip*, +5 V is output when the measured value is equal to 100%.
 - For Utif and Itif, +5 V is output when the measured value is equal to 100.
 - For Torque*, +5 V is output when the torque signal is an analog signal and the measured value is equal to a value (rated value) defined by "input range" \times "torque scaling factor." For example, with an input range of 10 V, if the scaling factor is set to 1 N-m torque per 1 V input voltage, +5 V is output when torque is 10 N-m.
 - For Speed*, +5 V is output when the rotating signal is an analog signal and the measured value is equal to a value (rated value) defined by "input range" \times "torque scaling factor." For example, with an input range of 10 V, if the scaling factor is set to 100 rpm rotating speed per 1 V input voltage, +5 V is output when the rotating speed is 1000 rpms.
 - For Speed*, -5 V is output when the rotating signal is a pulse signal and the rotating speed falls to the lower limit $\times (-1)$ of Pulse Range under Speed in section 1.6, and +5 V is output when the rotating speed reaches the upper limit.
 - For Torque*, -5 V is output when the torque signal is a pulse signal and the torque falls to the lower limit $\times (-1)$ of Pulse Range under Torque in section 1.6, and +5 V is output when the torque reaches the upper limit.
 - For SyncSp*, +5 V is output when measured value is equal to the rated value of speed.
 - For Pm*, +5 V is output when the measured value is equal to a motor output determined by the torque and the rated value of the rotating speed.
- * Applicable only to products with the motor evaluation function (motor version).

3.3 Setting the D/A Zoom

Procedure



1. Press **MISC** to display the Misc menu.
 2. Press the **Next 1/2** soft key to display the Next 2/2 menu.
 3. Press the **D/A Output Items** soft key to display the D/A Output menu.
- **Selecting the Target Channel**
 4. Press the **cursor keys** to select a value between 1 and 20.
 - **Selecting Whether to D/A Zoom (Manual Range Mode or Fixed Range Mode)**
 5. Press the **Range Mode** soft key to select Manual or Fixed. If Manual is selected, proceed to step 6.
 - **Setting the Maximum Value of the D/A Output Range for Manual Range Mode**
 6. Press the **Rated Max** soft key.
 7. Press the **cursor keys** to set the maximum value.
 - **Setting the Minimum Value of the D/A Output Range for Manual Range Mode**
 8. Press the **Rated Min** soft key.
 9. Press the **cursor keys** to set the minimum value.



Explanation

- **D/A Zoom**

The D/A output can be magnified or reduced for each channel in manual range mode by setting the D/A output range. For example, if a current varying in the range of 0.6 A to 0.8 A is measured at the 1-A range and the D/A output is set to fixed range mode, the D/A output voltage varies between 3.0 V and 4.0 V. If you wish to magnify this variation, you can use the D/A zoom function. In this example, set the D/A output to manual range mode and set the maximum and minimum values to 0.6 and 0.8, respectively. Then, the D/A output delivers -5 V and +5 V when the measured current is 0.6 A and 0.8 A, respectively.

- **Selecting the D/A Output Range Mode**

Select either mode from below.

- **Manual**

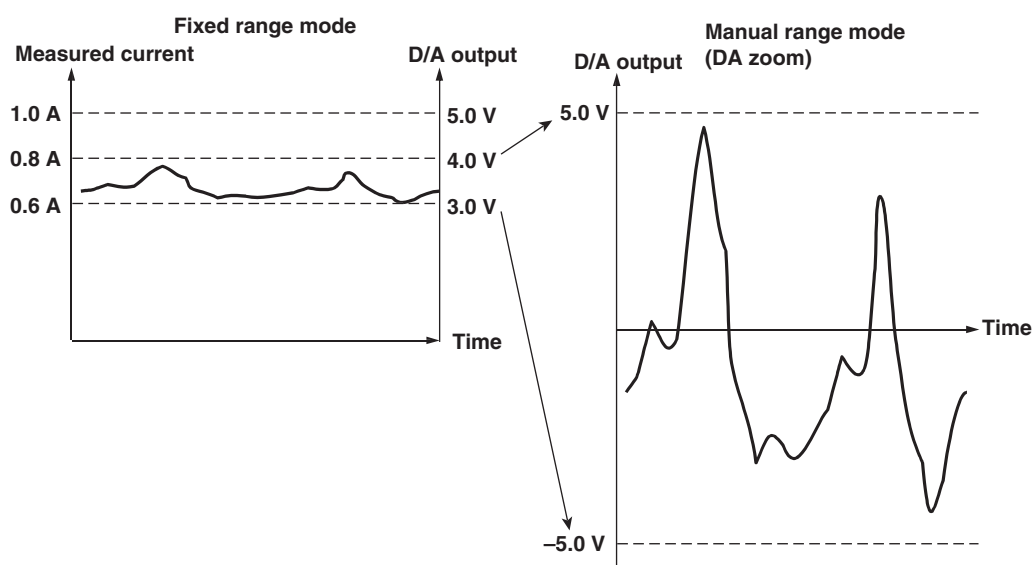
The displayed values of the measurement functions corresponding to the D/A output of -5 V and +5 V can be set arbitrarily.

- **Fixed**

Outputs +5 V when the rated value of each measurement function is applied. For details, see section 3.2.

- **Setting the Maximum and Minimum Values for Manual Range Mode**

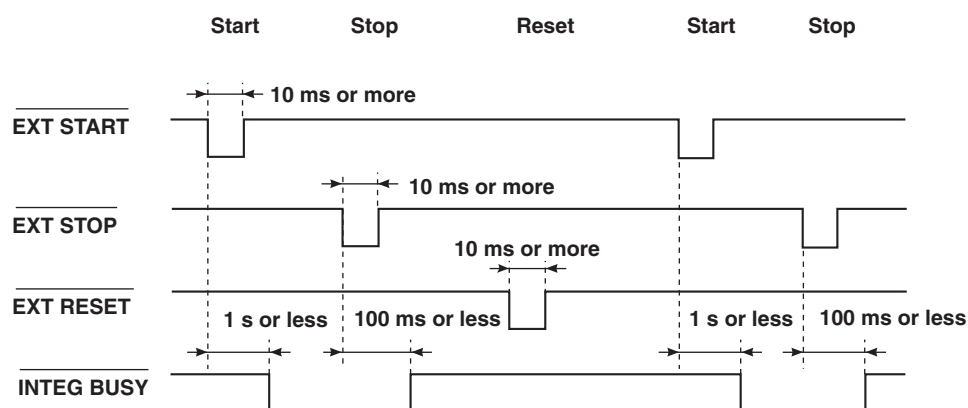
The maximum and minimum values can be set in the range of $-9.999\text{E}+30$ to $9.999\text{E}+30$.



3.4 Remote Control

- **Remotely Controlling the Integration**

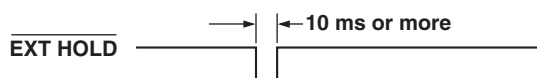
Enter the signals according to the timing chart below.



The **INTEG BUSY** output signal is set to low level while integration is in progress. Use this signal to monitor the integration operation.

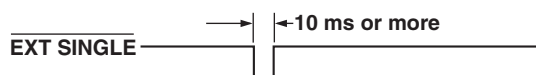
- **Holding the Data Display (Same Function as the HOLD Key)**

Apply the **EXT HOLD** signal as shown in the figure below.



- **Updating the Display Data Being Held (Same Function as the SINGLE Key)**

Applying the **EXT SINGLE** signal while the display is held updates the display.

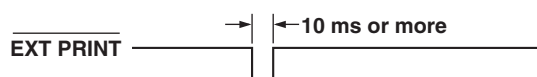


Note

If the period of the **EXT SINGLE** signal does not meet the conditions of the figure above, the signal may not be recognized by the WT3000.

- **Printing on the Built-in Printer (Option) (Same Function as the PRINT Key)**

Apply the **EXT PRINT** signal as shown in the figure below.



Explanation

Hold, single measurement, integration start/stop/reset, and print output can be controlled externally.

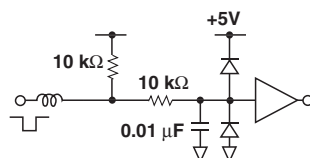


CAUTION

Do not apply voltage outside the range of 0 to 5 V to the remote control input pins. Also, do not short the output pins or apply external voltage to them. If you do, the instrument may malfunction.

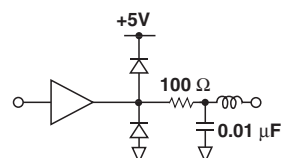
- Remote Control Input/Output Circuit

Input circuit



Low level: 0 to 1 V
High level: 4 to 5 V

Output circuit



Low level: 0 to 1.5 V (8 mA)
High level: 2.8 to 5 V (−8 mA)

3.5 D/A Output and Remote Control Specifications

D/A Output

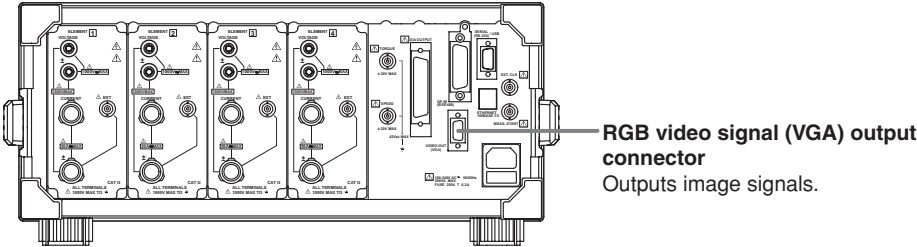
| Item | Specifications |
|---|--|
| D/A conversion resolution | 16 bits |
| Output voltage | ± 5 V FS (approx. ± 7.5 V maximum) against each rated value. |
| Update interval | The same as the data update interval of the WT3000 |
| Number of outputs | 20 channels Output item for each channel specifiable. |
| Accuracy | \pm (accuracy of each measurement function + 0.1% of FS) FS = 5 V |
| Minimum load | 100 k Ω |
| Temperature coefficient | $\pm 0.05\%$ of FS/ $^{\circ}$ C |
| Continuous maximum common mode voltage | ± 42 V _{peak} or less |
| Relationship between the output items and D/A output voltages | See section 3.2. |

Remote Control

| Item | Specifications |
|-------------|---|
| Signal | EXT START, EXT STOP, EXT RESET, INTEG BUSY, EXT HOLD, EXT SINGLE, and EXT PRINT |
| Input level | 0 to 5 V |

4.1 Names and Functions of the Parts of the RGB Video Signal (VGA) Output

Rear Panel



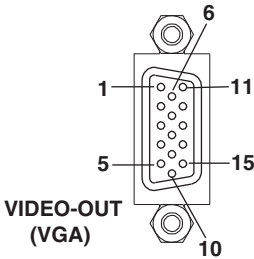
The WT3000 screen can be output to a monitor through the RGB video signal (VGA) output. Connectable monitors are VGA monitors or multi-sync monitors capable of displaying VGA.

CAUTION

- Connect the cable after turning OFF the WT3000 and the monitor.
- Do not short the RGB VIDEO OUT terminal or apply external voltage to it. If you do, the instrument may malfunction.

Pin Arrangement and Assignments of the Video Signal Output Connector

The pin arrangement and assignments of the connector are as follows:



| Pin No. | Signal Name | Specifications |
|---------|------------------------|--|
| 1 | Red | 0.7 Vp-p |
| 2 | Green | 0.7 Vp-p |
| 3 | Blue | 0.7 Vp-p |
| 4 | — | |
| 5 | — | |
| 6 | GND | |
| 7 | GND | |
| 8 | GND | |
| 9 | — | |
| 10 | GND | |
| 11 | — | |
| 12 | — | |
| 13 | Horizontal sync signal | Approx. 31.5 kHz, TTL (negative logic) |
| 14 | Vertical sync signal | Approx. 60 Hz, TTL (negative logic) |
| 15 | — | |

Connecting to the Monitor

1. Turn OFF the WT3000 and the monitor.
2. Connect the WT3000 and the monitor using an analog RGB cable.
3. The WT3000 screen appears on the monitor when both the WT3000 and the monitor are turned ON.

Note

- The RGB video signal is constantly output from the video signal output connector.
- The monitor screen may flicker if the WT3000 or another instrument is brought close to the monitor.
- The edge of the screen may drop out depending on the monitor type.

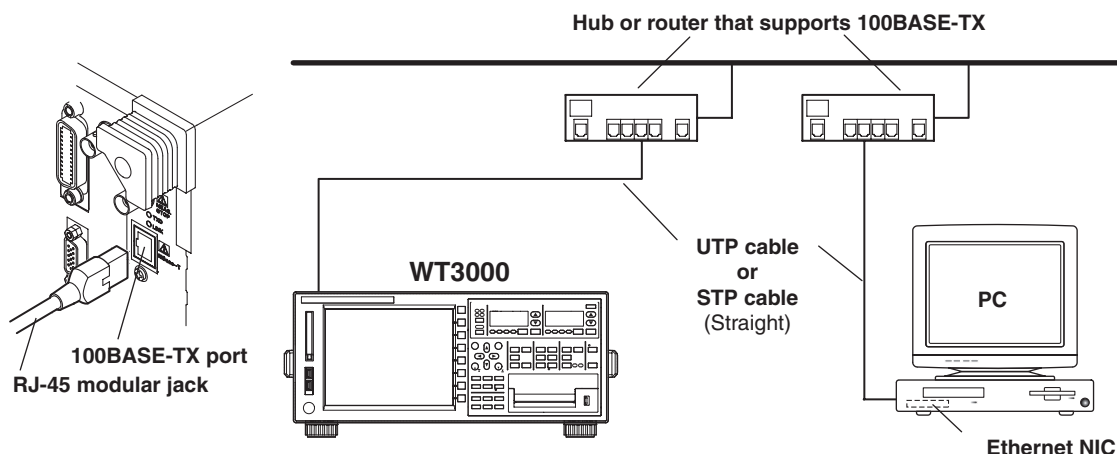
4.2 RGB Video Signal (VGA) Output Specifications

| Item | Specifications |
|----------------|---------------------------|
| Connector type | D-sub 15 pin (receptacle) |
| Output type | VGA compatible |

5.1 Connecting to the Network

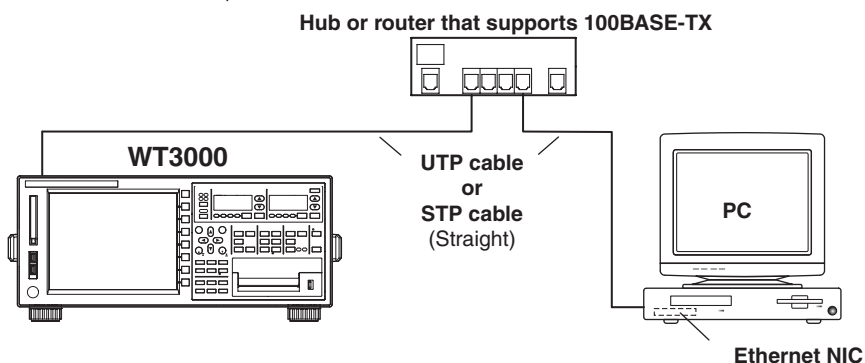
When Connecting to a PC on the Network

1. Turn OFF the WT3000 power switch (see section 3.4 in the *User's Manual IM760301-01E*).
2. Connect one end of the UTP (or STP) cable to the ETHERNET 100BASE-TX terminal on the rear panel.
3. Connect the other end of the UTP (or STP) cable to a hub or router.
4. Turn ON the WT3000 power switch.



Connecting to the PC in a One-to-One Configuration

1. Turn OFF the WT3000 power switch (See section 3.4 in the *User's Manual IM760301-01E*).
2. Connect one end of the UTP (or STP) cable to the ETHERNET 100BASE-TX terminal on the rear panel.
3. Connect the other end of the UTP (or STP) cable to a hub or router.
4. Likewise, connect the PC to a hub or router.
5. Turn ON the WT3000 power switch (see section 3.4 in the *User's Manual IM760301-01E*).

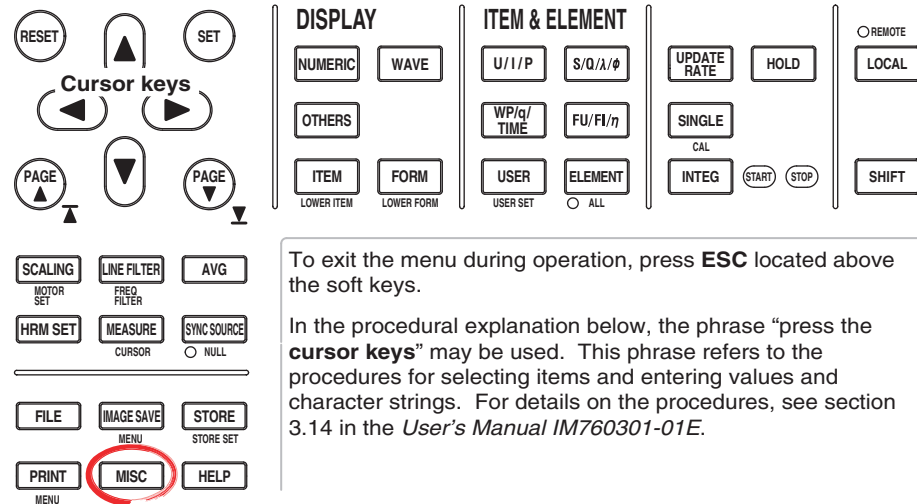


Note

- When connecting the WT3000 and a PC in a one-to-one configuration, use a 10BASE-T/100BASE-TX auto switching NIC or a 100BASE-TX NIC on the PC side.
- Use UTP (Unshielded Twisted-Pair) or STP (Shielded Twisted-Pair) cables of straight type and category 5 or better.
- Do not connect the WT3000 and a PC directly without going through a hub. Operations are not guaranteed for communications using direct connection.

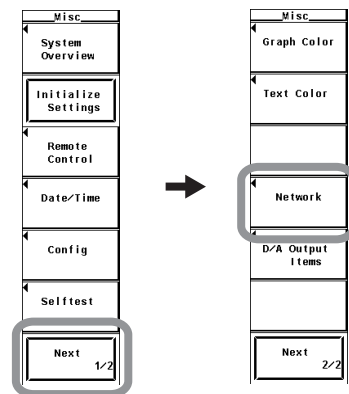
5.2 Setting TCP/IP

Procedure

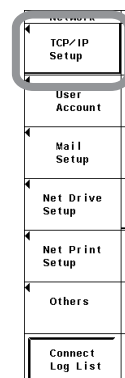


If you set the TCP/IP parameters for the first time or change the parameters, restart the WT3000 to apply the new settings.

1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key to display the Next 2/2 menu.
3. Press the **Network** soft key to display the Network menu.



4. Press the **TCP/IP Setup** soft key to display the TCP/IP Setup dialog box.



When Using Only DHCP

5. Press the **cursor keys** to select DHCP.
6. Press **SET** to select ON.
7. Press the **cursor keys** to select DNS.
8. Press **SET**. A DNS selection box appears.
9. Press the **cursor keys** to select OFF.

The screenshot shows the 'TCP/IP Setup' window. At the top, 'DHCP' is set to 'ON' and 'DNS' is set to 'OFF'. Below these, there are fields for 'IP Address' (0.0.0.0), 'Net Mask' (255.255.255.255), and 'Gate Way' (0.0.0.0).

When Using Only DNS

5. Press the **cursor keys** to select DHCP.
 6. Press **SET** to select OFF.
- **Entering the IP Address**
 7. Press the **cursor keys** to select IP Address.
 8. Press **SET**. An IP address entry box appears.
 9. Press the **cursor keys** to enter the IP address of the WT3000.
 10. Press **SET** or **ESC** to close the box.
 11. Enter all four octets of the **IP address**.

The screenshot shows the 'TCP/IP Setup' window. 'DHCP' is set to 'OFF' and 'DNS' is set to 'OFF'. The 'IP Address' field is highlighted with a cursor, indicating it is the active field for input.

- **Entering the Subnet Mask**
Enter the subnet mask according to the system or network to which the WT3000 belongs. If the subnet mask is not required, proceed to "Entering the Default Gateway."
 12. Press the **cursor keys** to select Net Mask.
 13. Enter all four octets of the subnet mask of the network to which the WT3000 belongs in the same fashion as the IP address.
- **Entering the Default Gateway**
Enter the default gateway according to the system or network to which the WT3000 belongs. If the default gateway is not required, proceed to "Turning ON the DNS."
 14. Press the **cursor keys** to select Gate Way.
 15. Enter all four octets of the default gateway of the network to which the WT3000 belongs in the same fashion as the IP address.

- **Turning ON the DNS**

16. Press the **cursor keys** to select DNS.
17. Press **SET**. A DNS selection box appears.
18. Press the **cursor keys** to select ON.
19. Press **SET** to confirm the DNS ON setting.

- **Entering the Domain Name**

Enter the domain name of the system or network to which the WT3000 belongs.

20. Press the **cursor keys** to select Domain Name.
21. Press **SET**. A keyboard appears.
22. Use the **keyboard** to enter the domain name of the network to which the WT3000 belongs.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Entering the Address of the Primary DNS Server**

23. Press the **cursor keys** to select DNS Server1.
24. Enter all four octets of the primary DNS server address in the same fashion as the IP address.

- **Entering the Address of the Secondary DNS Server**

Enter the information if the system or network to which the WT3000 belongs uses a secondary DNS server. If a secondary server is not used, proceed to "Entering the Primary Domain Suffix."

25. Press the **cursor keys** to select DNS Server2.
26. Enter all four octets of the secondary DNS server address in the same fashion as the IP address.

- **Entering the Primary Domain Suffix**

Enter the information if a domain suffix is required.

27. Press the **cursor keys** to select Domain Suffix1.
28. Enter the primary domain suffix in the same fashion as the domain name.

- **Entering the Secondary Domain Suffix**

Enter the information if a secondary domain suffix is present.

29. Press the **cursor keys** to select Domain Suffix2.
30. Enter the secondary domain suffix in the same fashion as the domain name.

The screenshot shows a 'TCP/IP Setup' window. At the top, there's a title bar 'TCP/IP Setup'. Below it, the 'DHCP' section has two radio buttons: 'OFF' and 'ON', with 'ON' selected. The 'IP Address' field is set to '192.168.111.24'. The 'Net Mask' field is set to '255.255.255.0'. The 'Gate Way' field is set to '0.0.0.0'. The 'DNS' section has two radio buttons: 'OFF' and 'ON', with 'ON' selected. Below this, the 'Domain Name' field is empty. The 'DNS Server1' field is set to '0.0.0.0'. The 'DNS Server2' field is set to '0.0.0.0'. The 'Domain Suffix1' field is empty. The 'Domain Suffix2' field is empty.

When Using Both DHCP and DNS

5. Press the **cursor keys** to select DHCP.
6. Press **SET** to select ON.
7. Press the **cursor keys** to select DNS.
8. Press **SET**. A DNS selection box appears.
9. Press the **cursor keys** to select ON or Auto.
 If you selected ON, you must enter information according to “Entering the Domain Name” through “Entering the Secondary Domain Suffix” on the previous page.
 If you selected Auto, the DHCP automatically sets the entry information from “Entering the Domain Name” to “Entering the Secondary Domain Suffix.”
 Therefore, you do not have to enter the information.

The screenshot shows the 'TCP/IP Setup' window. At the top, 'DHCP' is set to 'ON'. Below it, 'IP Address', 'Net Mask', and 'Gate Way' are each followed by four empty boxes for digits. The 'DNS' section has a dropdown menu open, showing 'OFF', 'ON', and 'Auto'. Below the dropdown, there are two rows for 'Domain' and 'Domain Suffix2', each followed by a text input field.

Restarting the WT3000

After you set the TCP/IP parameters for the first time or change the parameters, restart the WT3000 to apply the new settings.

Explanation

To use the Ethernet communication functions of the WT3000, the DHCP, IP address, IP address, subnet mask, default gateway, and DNS must be specified. Consult your system or network administrator when setting these parameters.

- **DHCP (Dynamic Host Configuration Protocol)**

DHCP is a protocol that allocates settings that are needed temporarily to PCs connecting to the network. If DHCP is turned ON when a DHCP server exists on the network, the parameters below are automatically assigned to PCs and other devices connected to the network.

IP address
 Subnet mask
 Default gateway
 Broadcast
 DNS

- To use DHCP, the network must have a DHCP server. Consult your network administrator to see if DHCP can be used.
- If DHCP is switched from OFF to ON, it may take several tens of seconds before the IP address can be retrieved.
- When DHCP is turned ON, different settings may be assigned each time the power is turned ON. When accessing the WT3000 from a PC using the FTP server function (see section 5.6), you must check the WT3000 TCP/IP settings such as the IP address each time the power is turned ON.

- **IP Address (Internet Protocol Address)**

You can set the IP address assigned to the WT3000. The default setting is 0.0.0.0.

- The IP address is an ID that is assigned to each device on an IP network such as the internet or an intranet.
- The address is a 32-bit value expressed using four octets (each 0 to 255), each separated by a period as in [192.168.111.24].
- Obtain an IP address from your network administrator.
- This parameter is automatically configured in environments using DHCP.

- **Subnet Mask**

You can set the mask value used when determining the subnet network address from the IP address. The default setting is 255.255.255.0.

- Huge TCP/IP networks such as the Internet are often divided up into smaller networks called sub networks. The subnet mask is a 32 bit value that specifies the number of bits of the IP address used to identify the network address. The portion other than the network address is the host address that identifies individual computers on the network.
- Consult your network administrator for the subnet mask value. You may not need to set the value.
- This parameter is automatically configured in environments using DHCP.

- **Default Gateway**

You can set the IP address of the gateway (default gateway) used to communicate with other networks. The default setting is 0.0.0.0.

- The default gateway has control functions that handle protocol exchanges when communicating with multiple networks, so that data transmission is carried out smoothly.
- Consult your network administrator for the default gateway value. You may not need to set the value.
- This parameter is automatically configured in environments using DHCP.

- **DNS (Domain Name System)**

The DNS is a system that correlates the host name/domain name to the IP address. Given AAA.BBBBBB.com, AAA is the host name and BBBBBB.com is the domain name. Instead of using the IP address, which is a sequence of numbers, a host name and domain name can be used to access the network.

- Set the domain name, the DNS server address, and the domain suffix. If DHCP can be used, the address can be automatically assigned.
- When accessing a network drive or a network printer from the WT3000, a name can be used to access the destination rather than an IP address.
- For details, consult your network administrator.

- **Domain name**

- Set the network domain name to which the WT3000 belongs.
- Enter up to 30 characters.
- The characters that can be used are 0-9, A-Z, %, _, () (parentheses), - (minus sign).

- **DNS Server Address**
 - Set the IP address of the DNS server. The default setting is 0.0.0.0.
 - You can specify up to two DNS server addresses, primary and secondary. If the primary DNS server is down, the secondary DNS server is automatically looked up for the mapping of the host name/domain name and IP address.
- **Domain Suffix**
 - When the IP address corresponding to the server name with the domain name specified in the previous section is not found, the system may be set up to search using a different domain name. Enter this alternate domain name as the domain suffix.
 - You can specify up to two domain suffixes, primary and secondary.
- **Setting TCP/IP Parameters for Network Connection**
When connecting the WT3000 to a network, set the TCP/IP parameters as shown below depending on whether the DHCP server and DNS server are available.

| | DHCP Server is available | DHCP Server is not available |
|-----------------|--|---|
| DHCP | ON | OFF |
| IP address | Setting not necessary (Automatically set by the DHCP server) | Set manually (supplied by your network administrator) |
| Subnet mask | | Set manually (check with your network administrator) |
| Default gateway | | Set manually (check with your network administrator) |

| | DHCP Server is available | DHCP Server is not available |
|--------------------|--------------------------|------------------------------|
| DNS | ON | OFF |
| Domain name | Set manually* | Setting not necessary |
| DNS server address | Set manually* | Setting not necessary |
| Domain suffix | Set manually* | Setting not necessary |

* If DHCP can be used, these settings can be automatically assigned. For details, consult your network administrator.

- **TCP/IP Configuration Example When a PC and WT3000 Are Connected on an Independent Ethernet Network**

Examples of TCP/IP settings on the WT3000 are shown below. Specify the TCP/IP settings on the PC to comply with the settings in this example as shown in the example given later.

| | |
|-----------------|----------------|
| DHCP | OFF |
| IP address | 192.168.21.127 |
| Subnet mask | 255.255.255.0 |
| Default gateway | 0.0.0.0 |
| DNS | OFF |

Note

- If you set the TCP/IP parameters for the first time or change the parameters, restart the WT3000 to apply the new settings.
- If the WT3000 is turned ON with the DHCP function enabled without an Ethernet cable connected, communications and file functions may not operate properly. In such case, turn DHCP OFF and restart the WT3000.

5.2 Setting TCP/IP

Configuring the TCP/IP Settings of the PC

Communication parameters such as the IP address must be specified also on the PC side. Communication parameters are specified for each Ethernet NIC that is installed in the PC. Here, the settings of the NIC required for connecting your PC and the WT3000 are explained.

If the IP address and other parameters are to be assigned dynamically using the DHCP server, the settings below are not necessary.

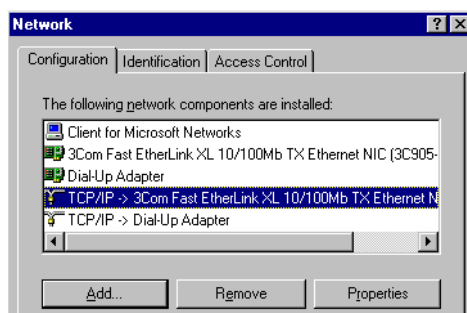
Select **Obtain an IP address automatically** under the **IP Address** tab of the **TCP/IP Properties** dialog box.

For example, if you are connecting a PC and the WT3000 to an independent Ethernet network, you can specify parameters as indicated in the next table. For details on the parameters, consult your system or network administrator.

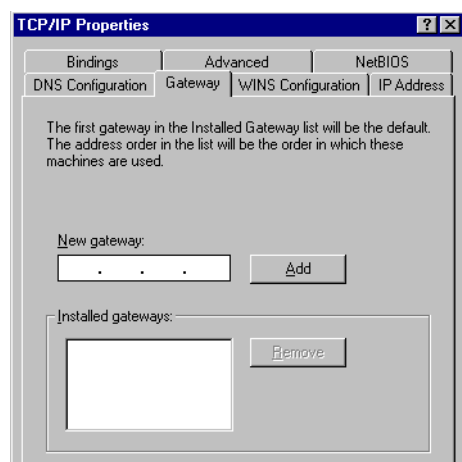
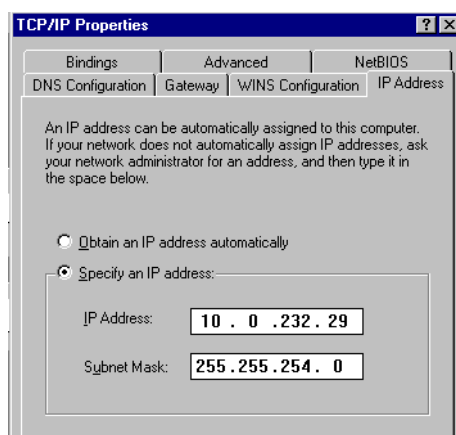
| Parameter | Value | Note |
|-------------|-------------------------|--|
| IP address | Example: 192.168.21.128 | IP address for the PC |
| Subnet mask | Example: 255.255.255.0 | Set the same value as the subnet mask that was specified for the WT3000. |
| Gateway | None | |
| DNS | Disable | |
| WINS | Disable | |

The following procedure describes the steps for Windows 95/98. For Windows NT/2000 Pro, carry out equivalent steps accordingly.

1. Select **Start > Settings > Control Panel**. The Control Panel opens.
2. Double-click the **Network** icon. The Network dialog box opens.
3. Select **TCP/IP** corresponding to the Ethernet NIC that is connected to your PC and click **Properties**. The TCP/IP Properties dialog box appears.



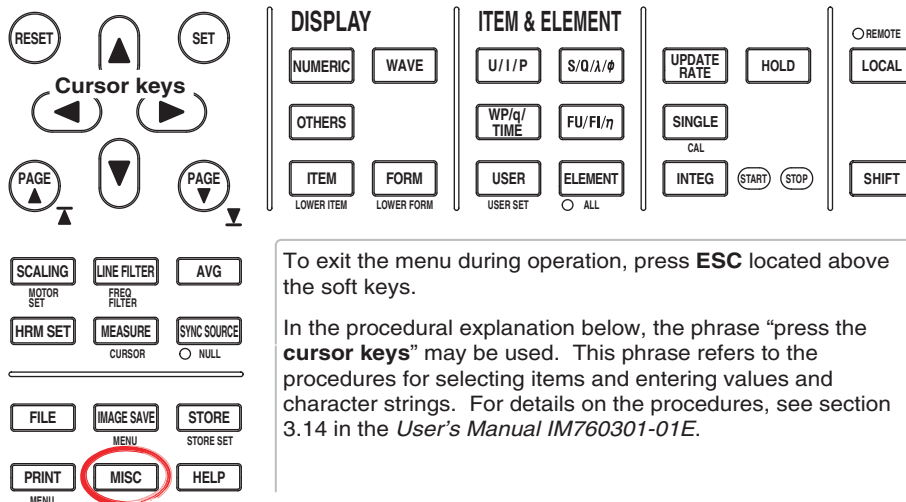
4. Set the parameters such as the IP address according to the previous table and click **OK**.



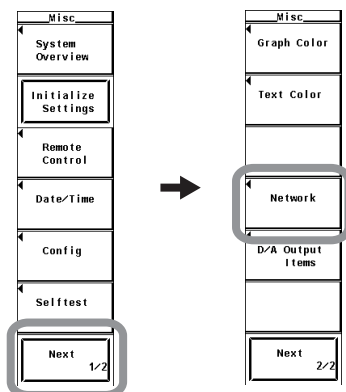
5. Restart your PC.

5.3 Saving Setup, Waveform Display, Numeric , and Image Data to the FTP Server (FTP Client Function)

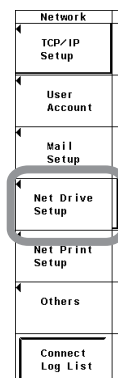
Procedure



1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key The Next 2/2 menu appears.
3. Press the **Network** soft key to display the Network menu.



4. Press the **Net Drive Setup** soft key to display the Net Drive Setup dialog box.



5.3 Saving Setup, Waveform Display, Numeric , and Image Data to the FTP Server (FTP Client Function)

- **Specifying the Save Destination FTP Server**

5. Press the **cursor keys** to select FTP Server.
6. Press **SET**. A keyboard appears.
7. Use the **keyboard** to enter the IP address of the FTP server. If you are using DNS, you can specify the server by name.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Entering the Login Name and Password for Accessing the Save Destination FTP Server**



8. Press the **cursor keys** to select Login Name.
9. Press **SET**. A keyboard appears.
10. Use the **keyboard** to enter the login name.
11. Press the **cursor keys** to select Password.
12. Press **SET**. A keyboard appears.
13. Use the **keyboard** to enter the password. A password is not required if the login name is anonymous.

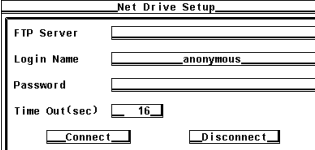
For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Setting the Timeout Value**

14. Press the **cursor keys** to select Time Out.
15. Press **SET**. The timeout value entry box appears.
16. Press the **cursor keys** to set the timeout value.
17. Press **SET** or **ESC** to close the box.

- **Connecting to/Disconnecting from the Save Destination FTP Server**

18. Press the **cursor keys** to select Connect or Disconnect.
19. Press **SET**.
 - If you select Connect and press SELECT, a connection is established to the save destination FTP server. When the connection is made,  is displayed in the upper left corner of the screen.
 - If you select Disconnect and press SELECT, connection to the save destination FTP server is dropped. The  displayed in the upper left corner of the screen disappears.



The image shows a 'Net Drive Setup' dialog box. It contains the following fields and controls:

- FTP Server**: A text input field.
- Login Name**: A text input field containing the text 'anonymous'.
- Password**: A text input field.
- Time Out(sec)**: A text input field containing the value '16'.
- Connect**: A button.
- Disconnect**: A button.

- **Saving the Data**

- To save the setup parameters, waveform display data, or numeric data, carry out the save operation according to the procedure given in section 9.3 in the *User's Manual IM760301-01E*.
- To save the screen image data, carry out the save operation according to the procedure given in section 9.4 in the *User's Manual IM760301-01E*.
- For the procedure "Selecting the Storage Medium" in section 9.3 in the *User's Manual IM760301-01E*, set the storage medium to **NetWork**.

Explanation

The FTP client function of the WT3000 can be used to save the setup parameters, waveform display data, numeric data, and screen image data to an FTP server on the network in a similar fashion to saving various data on a PC card.

- **Save Destination FTP Server**

- Specify the FTP server by entering the IP address.
- If you are using DNS (see section 5.2), you can specify the server by name.
- The FTP server program must be running on the PC or workstation that is to become the save destination FTP server. In addition, the following points need attention regarding the server program settings.
 - Set the list output (string returned by the dir command) to UNIX format.
 - Set the home directory and its subdirectories to allow writing.
 - The client cannot move above the home directory.
 - The newest file is not necessarily displayed at the top of the file list.
 - Files and directories that are longer than 8 characters cannot be accessed.
 - Depending on the server, the parent directory symbol "<.. >" may not be displayed.
- The time information in the file list will not be displayed correctly for the following cases.
 - On Windows NT when the time stamp is displayed using am and pm.
 - Servers that return characters other than ASCII characters in the list
- The following operations are not possible from the WT3900 on files that have been saved on an FTP server.
 - Enabling/Disabling file protection, copying, and renaming
 - Formatting the FTP server medium

- **Entering the Login Name and Password**

Enter the login name and password for accessing the save destination FTP server.

- **Login Name**

- Enter up to 15 characters.
- The characters that can be used are 0-9, A-Z, %, _ , () (parentheses), - (minus sign).

- **Password**

- Enter up to 15 characters.
- The characters that can be used are 0-9, A-Z, %, _ , () (parentheses), - (minus sign).

- **Setting the Timeout Value**

When an FTP server is accessed from the WT3000 and connection cannot be established after a certain period of time (timeout value), the WT3000 decides that the connection to the FTP server is not possible and closes the connection.

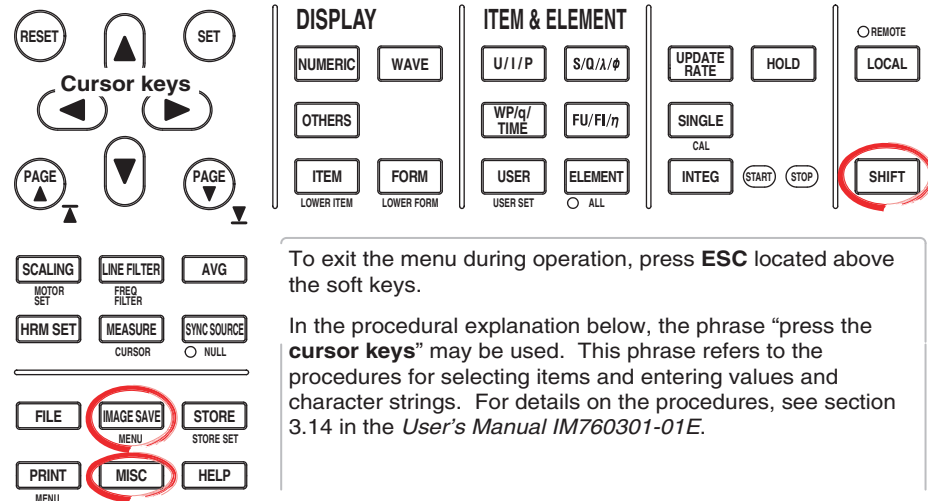
You can set the timeout value in the range of 0 to 3600 s. The default value is 15 s.

Note

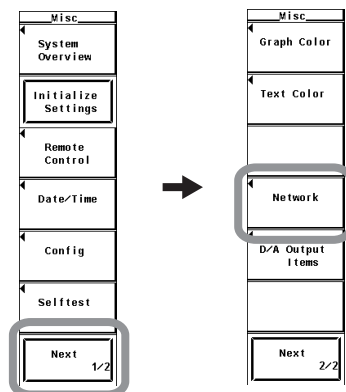
- The LPR client function cannot be used under the following cases.
 - When the WT3000 is performing file operations (see chapter 9 in the *User's Manual IM760301-01E*).
 - When the WT3000 is being accessed by a PC or workstation on the network (FTP server function, see section 5.6).
 - To use the FTP client function, you must configure TCP/IP (see section 5.2) in advance.
 - To apply new settings that are made while the connection is up, drop the connection using Disconnect and reconnect.
 - If a connection is dropped by the server while you are operating the FTP client, the connection will be automatically reestablished when you display the File List dialog box through file operation as described in chapter 9 in the *User's Manual IM760301-01E*.
-

5.4 Printing Screen Images on a Network Printer

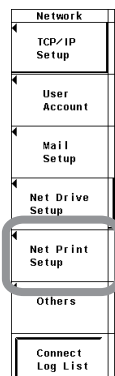
Procedure



1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key. The Next 2/2 menu appears.
3. Press the **Network** soft key to display the Network menu.



4. Press the **Net Print Setup** soft key to display the Net Print Setup dialog box.



- **Specifying the Printer Server**

5. Press the **cursor keys** to select LPR Server.
6. Press **SET**. A keyboard appears.
7. Use the **keyboard** to enter the IP address of the printer server. If you are using DNS, you can specify the server by name.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Entering the Printer Name**

8. Press the **cursor keys** to select LPR Name.
9. Press **SET**. A keyboard appears.
10. Use the **keyboard** to set the printer name.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

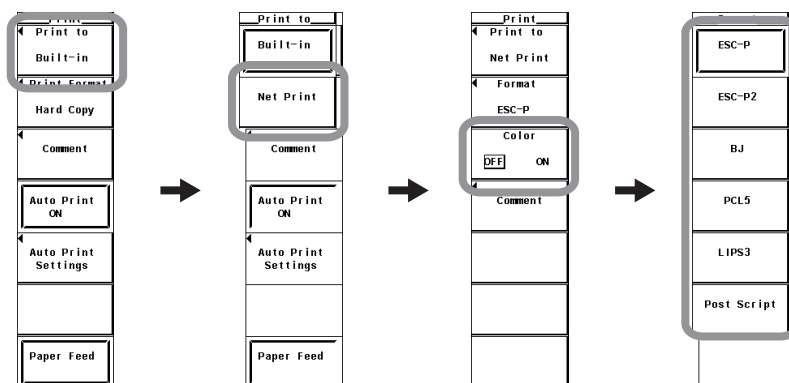
The image shows a screen titled "Net Print Setup". It has two input fields: "LPR Server" and "LPR Name". The "LPR Name" field contains the text "PASSTHRU".

- **Setting the Output Destination to a Network Printer**

1. Press **SHIFT+PRINT (MENU)** to display the Print menu.
2. Press the **Print** to soft key to display the Print to menu.
3. Press the **Net Print** soft key.

- **Selecting the Output Command**

4. Press the **Format** soft key to display the Format menu.
 5. Press any soft key from **ESC-P** to **Post Script** to select the output command.
- If you selected BJ, proceed to step 6.
 If you selected ESC-P, ESC-P2, or PCL5, proceed to step 8 on the next page.
 If you selected LIPS3 or Post Script, proceed to step 9 on the next page.



5.4 Printing Screen Images on a Network Printer

- **Selecting the Resolution**

(This procedure is applicable if you selected BJ in step 5.)

6. Press the **BJ_Reso** soft key to display the Resolution menu.
7. Press any soft key from **180dpi** to **360dpi** to select the resolution

- **Turning ON/OFF the Color Output**

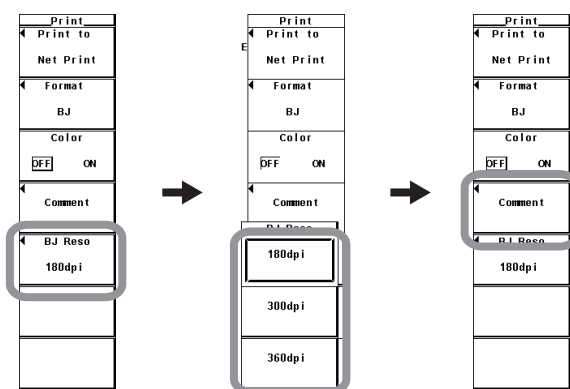
(This procedure is applicable if you selected ESC-P, ESC-P2, BJ, or PCL5 in step 5.)

8. Press the **Color** soft key to select ON or OFF.

- **Setting Comments**

9. Press the **Comment** soft key. A keyboard appears.
10. Use the **keyboard** to enter the comment.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

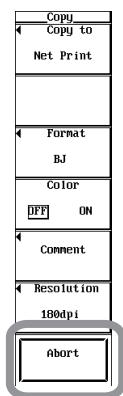


- **Executing the Print Operation**

11. Switch to the screen you wish to print.
12. Press the **PRINT** soft key. The screen image is printed.

- **Canceling the Print Operation**

13. Press the **Abort** soft key in the Print menu.



Explanation

The LPR client function of the WT3000 can be used to output screen images to a network printer.

- **Printer Server**

- Specify the printer server by entering the IP address.
- If you are using DNS (see section 5.2), you can specify the server by name.

- **Printer Name**

Enter the name of the output destination printer on the network.

- **Selecting the Output Command**

Select the output command type from the choices below.

- ESC-P
- ESC-P2 (for printers that support ESC/P raster commands)
- BJ
- PCL5
- LIPS3
- Post Script

- **Turning ON/OFF Color Printing**

You can select whether to output the image in color when the output command type is ESC-P, ESC-P2, BJ, or PCL5.

- **ON**

The displayed screen image can be output to a printer in color (256 colors).

- **OFF**

The displayed screen image can be output to a printer in black and white.

- **Setting Comments**

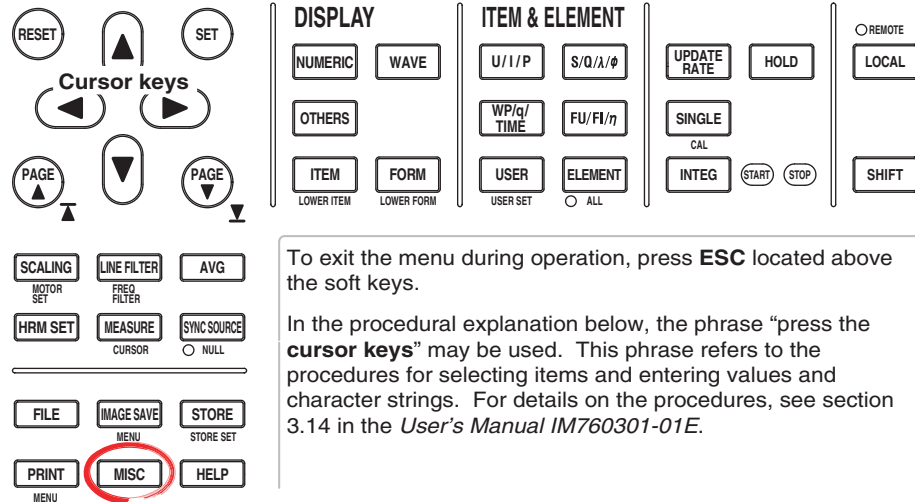
Same as the explanation given in “File Name and Comment” in section 9.3 in the *User's Manual IM760301-01E*.

Note

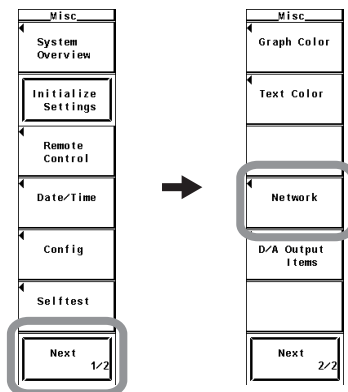
- The LPR client function cannot be used under the following cases.
 - When the WT3000 is performing file operations (see chapter 9 in the *User's Manual IM760301-01E*).
 - When the WT3000 is being accessed by a PC or workstation on the network (FTP server function, see section 5.6).
 - To use the LPR client function, you must configure TCP/IP (see section 5.2) in advance.
 - Output is possible to printers that support the TCP/IP protocol.
-

5.5 Sending E-mail

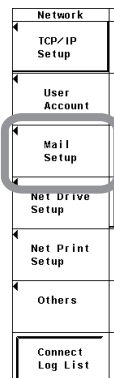
Procedure



1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key The Next 2/2 menu appears.
3. Press the **Network** soft key to display the Network menu.



4. Press the **Mail Setup** soft key to display the Mail Setup dialog box.



- **Specifying the Mail Server**

5. Press the **cursor keys** to select Mail Server.
6. Press **SET**. A keyboard appears.
7. Use the **keyboard** to enter the IP address of the mail server. If you are using DNS, you can specify the server by name.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Entering the Destination Mail Address**

8. Press the **cursor keys** to select Mail Address.
9. Press **SET**. A keyboard appears.
10. Use the **keyboard** to enter the destination mail address.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Setting Comments**

(Enter a comment as necessary.)

11. Press the **cursor keys** to select Comment.
12. Press **SET**. A keyboard appears.
13. Use the **keyboard** to enter the comment.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

The screenshot shows the 'Mail Setup' menu. It contains four input fields: 'Mail Server', 'Mail Address', 'Comment', and 'MailBaseTime'. The 'MailBaseTime' field is set to '0:0:0'. Below these fields is an 'Interval' dropdown menu currently set to 'OFF'. At the bottom of the menu is a 'Mail Test' button.

- **Setting the Time of Transmission**

14. Press the **cursor keys** to select the hour, minute, or second box of MailBaseTime.
15. Press **SET**. An entry box appears.
16. Press the **cursor keys** to set the hour, minute, or second that you selected in step 14.
17. Press **SET** or **ESC** to close the box.
18. Repeat steps 14 to 17 to set the hour, minute, and second.

This screenshot is identical to the previous one, but the 'MailBaseTime' field is highlighted with a thick border, and a cursor is visible in the first digit (the hour) of the '0:0:0' display.

- **Selecting the Transmission Interval**

19. Press the **cursor keys** to select Interval.
20. Press **SET**. An entry box appears.
21. Press the **cursor keys** to select OFF or 1h to 24h.
If you select OFF, mails are not transmitted.
22. Press **SET** or **ESC** to close the box.

- **Performing a Test Transmission**

23. Press the **cursor keys** to select Mail Test.
24. Press **SET**. A test mail is sent to the destination.

The image shows a 'Mail Setup' screen with the following fields and controls:

- Mail Server**: A text input field.
- Mail Address**: A text input field.
- Comment**: A text input field.
- MailBaseTime**: A time selection field showing '0:0:0'.
- Interval**: A dropdown menu currently set to 'OFF'.
- Mail Test**: A button to initiate a test transmission.

Explanation

The condition of the WT3000 can be sent in e-mail messages at a certain interval to a specified mail destination.

- **Mail Server**

- Specify the mail server by entering the IP address.
- If you are using DNS (see section 5.2), you can specify the server by name.

- **Transmission Destination Mail Address**

Enter the mail address of the device that is to receive the messages sent by the WT3000.

- **Setting Comments**

Same as the explanation given in "File Name and Comment" in section 9.3 in the *User's Manual IM760301-01E*.

- **Setting the Time of Transmission**

- Specify the time to start transmitting the e-mail messages.
- Set the time in units of hour : minute : second in the following range.
0:0:0 to 23:59:59

- **Selecting the Transmission Interval**

- Specify the interval for transmitting the e-mail messages.
- You can select the measurement range from the following: If you select OFF, mails are not transmitted.
OFF, 1h, 2h, 3h, 4h, 6h, 8h, 12h, and 24h

- **Transmitted Information of the WT3000**

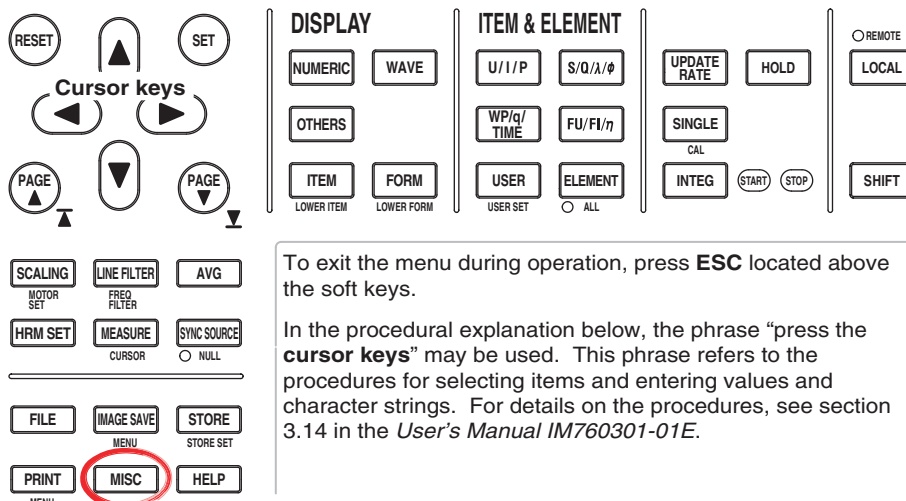
| Number of Displayed Items | Transmitted Data |
|---------------------------|--|
| 4 Items | All numeric data on pages 1 to 9 on the screen (36 data values) |
| 8 Items | All numeric data on pages 1 to 9 on the screen (72 data values) |
| 16 Items | All numeric data on pages 1 to 9 on the screen (144 data values) |
| All Items | The numeric data of measurement functions that are selected |
| Single List | in "Saving Numeric Data" of the data save/load function is |
| Dual List | transmitted. For details on saving numeric data, see section 9.3 |
| | in the <i>User's Manual IM760301-01E</i> . |

Note

- To use the SMTP client function, you must configure TCP/IP (see section 5.2) in advance.
- The sender (From) address of the mail messages sent by the WT3000 is the same as the specified recipient address.
- E-mail cannot be transmitted when the transmission interval is set to OFF.

5.6 Accessing the WT3000 from a PC or Workstation (FTP Server Function)

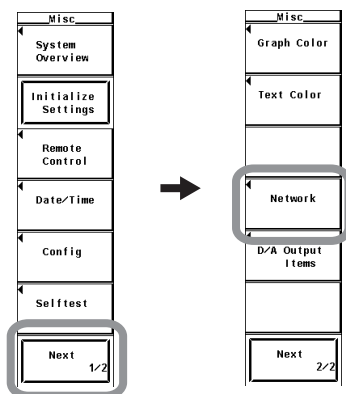
Procedure



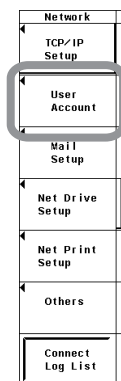
In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

The FTP server function can be used when a PC card or USB storage is connected to the WT3000.

1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key to display the Next 2/2 menu.
3. Press the **Network** soft key to display the Network menu.



4. Press the **User Account** soft key to display the User Account dialog box.



5.6 Accessing the WT3000 from a PC or Workstation (FTP Server Function)

- **Setting the User Name**

5. Press the **cursor keys** to select User Name.
6. Press **SET** to display the keyboard.
7. Use the **keyboard** to enter the user name.
 - For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.
 - When not restricting the access, specify anonymous. If you specify anonymous, you do not have to set the password.

- **Setting the Password**

(If you set user name to anonymous in step 7, you do not have to set the password.)

8. Press the **cursor keys** to select Password.
9. Press **SET** to display the keyboard.
10. Use the **keyboard** to enter the password.

For keyboard operations, see section 3.14 in the *User's Manual IM760301-01E*.

- **Setting the Timeout Value**

11. Press the **cursor keys** to select Time Out.
12. Press **SET** to display the timeout time selection box.
13. Press the **cursor keys** to set the timeout value.
14. Press **SET** or **ESC** to close the box.

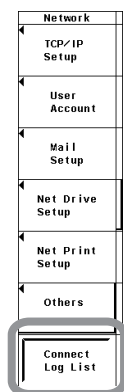
The screenshot shows a dialog box titled "User Account". It contains three input fields: "User Name" with the text "anonymous", "Password" which is empty, and "Time Out(sec)" with the value "600".

- **Accessing the WT3000**

15. Execute an FTP client on the PC or workstation.
16. Access the WT3000 using the user name and password specified in the previous section.

- **Displaying the Logging List**

17. Press the **Connect Log List** soft key. The WT3000 access log is displayed.



Explanation

The floppy disk, built-in hard disk, and SCSI devices connected via SCSI (optional) of the WT3000 can be accessed from a PC or workstation on the network.

To access the WT3000, a FTP client is needed on the PC or workstation.

- **Setting the User Name**

- Enter the user name to allow access to the WT3000.
- Enter up to 15 characters.
- The characters that can be used are 0-9, A-Z, %, _ , () (parentheses), - (minus sign).
- If you specify anonymous, the WT3000 can be accessed from the outside (PC or workstation) without a password.

- **Setting the Password**

- Enter the password for the user name to allow access to the WT3000.
- Enter up to 15 characters.
- The characters that can be used are 0-9, A-Z, %, _ , () (parentheses), - (minus sign).
- If the user name is set to anonymous, the WT3000 can be accessed from the outside (PC or workstation) without a password.

- **Setting the Timeout Value**

The WT3000 closes the connection to the network if there is no access for a certain period of time (timeout value).


You can set the timeout value in the range of 0 to 3600 s. The default value is 60 s.

- **Logging List**

The access log of the WT3000 can be displayed. The data and time, user name, and IP address of the 25 most recent accesses are displayed.

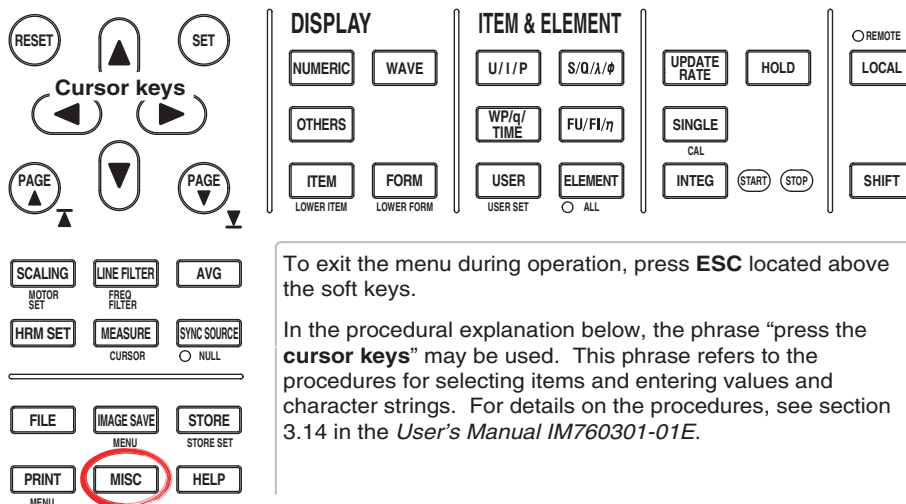
5.6 Accessing the WT3000 from a PC or Workstation (FTP Server Function)

Note

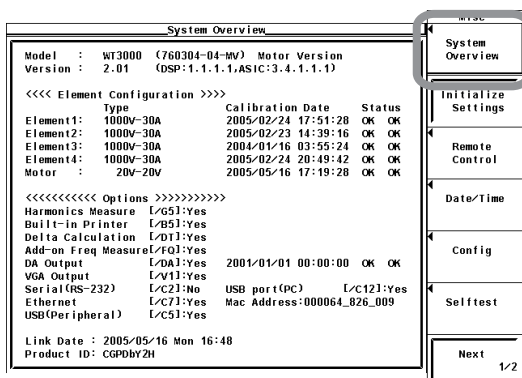
- The WT3000 supports only a single client.
 - When the WT3000 is accessed from the PC or workstation (login),  is displayed in the upper left corner of the screen.
 - The FTP server function cannot be used under the following cases.
 - When the WT3000 is accessing a PC or workstation on the network (FTP client function, see section 5.3).
 - When the WT3000 is outputting to a network printer (LPR client function, see section 5.3).
 - When the WT3000 is performing file operations (see chapter 9 in the *User's Manual IM760301-01E*).
 - The PC card, USB storage, and network drive are displayed as [PC_Card], [USB], and [ND0], respectively, at the root directory of the PC or workstation accessing the WT3000.
 - The log list is cleared when the power is turned OFF.
 - When using the FTP server function, set the TCP/IP parameters according to section 5.2, "Setting the Ethernet Interface (TCP/IP)."
 - To apply new settings, the WT3000 must be power cycled.
-

5.7 Checking the Ethernet Communication Function (Option) Availability and MAC Address

Procedure



1. Press **MISC** to display the Misc menu.
2. Press the **System Overview** soft key to display the System Overview window.
The availability of the Ethernet communication function (option) and the MAC address information are displayed in the System Overview window.



Explanation

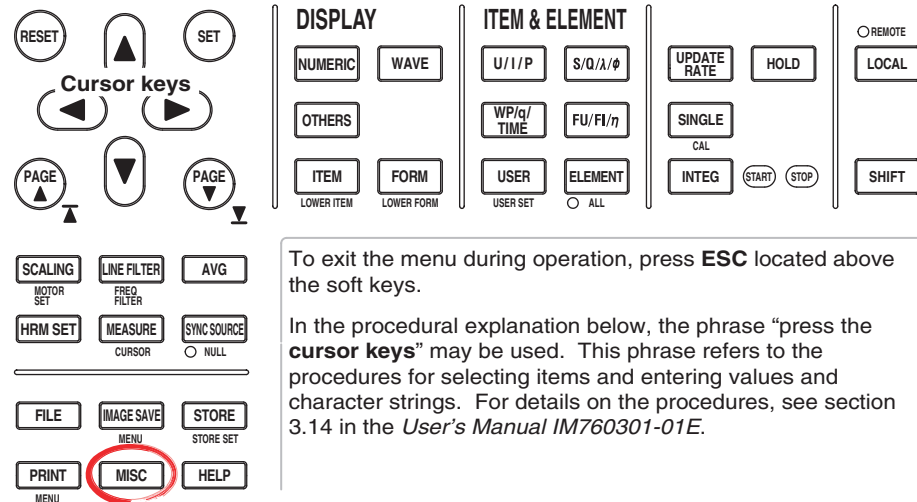
- **Availability of the Ethernet Communication Function (Option)**
The availability is displayed under Ethernet in the System Overview window.
 - If Yes is displayed, the Ethernet communication function is available.
 - If No is displayed, the Ethernet communication function is not available.
- **MAC Address**
The MAC address is a unique address that is pre-assigned to the WT3000. The MAC address is displayed under Mac Address in the System Overview window.

Note

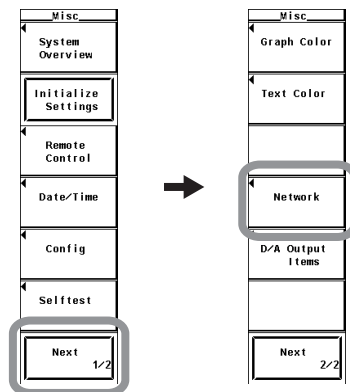
The MAC address is displayed only on products with the Ethernet communication function. If the MAC address is displayed as “xxxxxx_xxx_xxx” even though the Ethernet communication function is installed, contact your nearest YOKOGAWA dealer.

5.8 Setting the FTP Passive Mode and LPR/SMTP Timeout

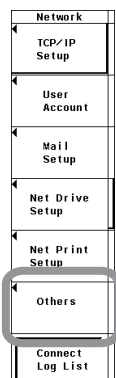
Procedure



1. Press **MISC** to display the Misc menu.
2. Press the **Next 1/2** soft key. The Next 2/2 menu appears.
3. Press the **Network** soft key to display the Network menu.



4. Press the **Others** soft key to display the Others dialog box.



- **Turning ON/OFF the FTP Passive Mode**

5. Press the **cursor keys** to select FTP Passive.
6. Press **SET** to select ON or OFF.

- **Setting the LPR Timeout Value**

5. Press the **cursor keys** to select LPR Time Out.
6. Press **SET**. The timeout value entry box appears.
7. Press the **cursor keys** to set the timeout value.
8. Press **SET** or **ESC** to close the box.

- **Setting the SMTP Timeout Value**

5. Press the **cursor keys** to select SMTP Time Out.
6. Press **SET**. The timeout value entry box appears.
7. Press the **cursor keys** to set the timeout value.
8. Press **SET** or **ESC** to close the box.

The screenshot shows a window titled 'Others' with three settings:

- FTP Passive: A toggle switch currently set to 'OFF', with 'ON' also visible.
- LPR Time Out(sec): A numeric input field containing the value '15'.
- SMTP Time Out(sec): A numeric input field containing the value '15'.

Explanation

Special settings related to the FTP client, LPR, and SMTP are entered. Set these items as necessary.

- **Turning ON/OFF the FTP Passive Mode**

Turn this function ON when using the WT3000 behind a firewall* that requires the passive mode. The default setting is OFF.

* A firewall is furnished on a system that has security features. It prevents intrusion from the outside into the network system.

- **Setting the LPR Timeout Value**

The WT3000 closes the connection to the printer if there is no response from the printer for a certain period of time (timeout time) while it attempts to access the printer. You can set the timeout value in the range of 0 to 3600 s. The default value is 15 s.

- **Setting the SMTP* Timeout Value**

When a mail server is accessed from the WT3000 and connection cannot be established after a certain period of time (timeout time), the WT3000 decides that the connection to the mail server is not possible and closes the connection.

You can set the timeout value in the range of 0 to 3600 s. The default value is 15 s.

* SMTP (Simple Mail Transfer Protocol) is a protocol that resides above the TCP/IP layer and is used by the e-mail transmission system.

5.9 Ethernet Interface Specifications

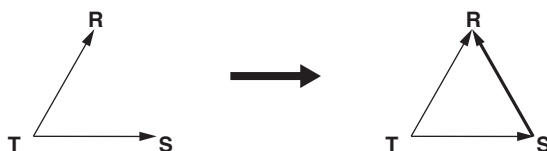
| Item | Specifications |
|--|--|
| Number of communication ports | 1 |
| Connector type | RJ-45 connector |
| Electrical and mechanical specifications | Conforms to IEEE 802.3. |
| Transmission system | Ethernet (100BASE-TX/10BASE-T) |
| Data rate | 100 Mbps maximum |
| Communication protocol | TCP/IP |
| Supported service | <p>FTP client</p> <p>Save setup parameters, waveform display data, numeric data, and screen image data to an FTP server (network drive) on the network. Load the setup parameters that have been saved to the FTP server.</p> <p>FTP server</p> <p>Access the WT3000 from a PC or workstation on the network and download the file on the PC card or USB memory in the WT3000. However, an FTP client is needed on the PC or workstation.</p> <p>LPR client (network printer)</p> <p>Print the screen image on a network printer.</p> <p>SMTP client (mail transmission)</p> <p>Periodically transmit the information of the WT3000 to a specified mail address.</p> <p>DHCP</p> <p>DNS</p> <p>Remote control</p> <p>The WT3000 can be controlled remotely from a host such as a PC. For details, see the <i>Communication Interface User's Manual (IM760301-17E)</i>.</p> |

6.1 Delta Computation Function

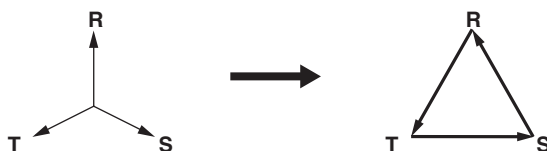
The sum or difference of the instantaneous values (sampled data) of the voltage or current between the elements in a wiring unit can be used to determine various types of data such as the differential voltage and phase voltage. This operation is called delta computation.

Delta computation enables the following computations.

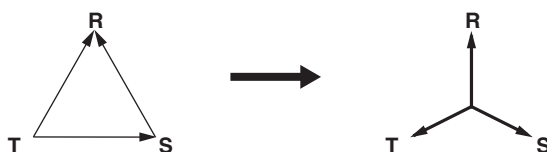
- The differential voltage and differential current between two elements can be computed on a single-phase, three-wire system or a three-phase, three-wire system (using two elements).
- The line voltage and phase current that are not measured on a single-phase, three-wire system or a three-phase, three-wire system (using 2 elements) can be computed.



- Using the data from a three-phase, four-wire system, various data of a delta connection can be computed from the data of a star connection (star-delta transformation).



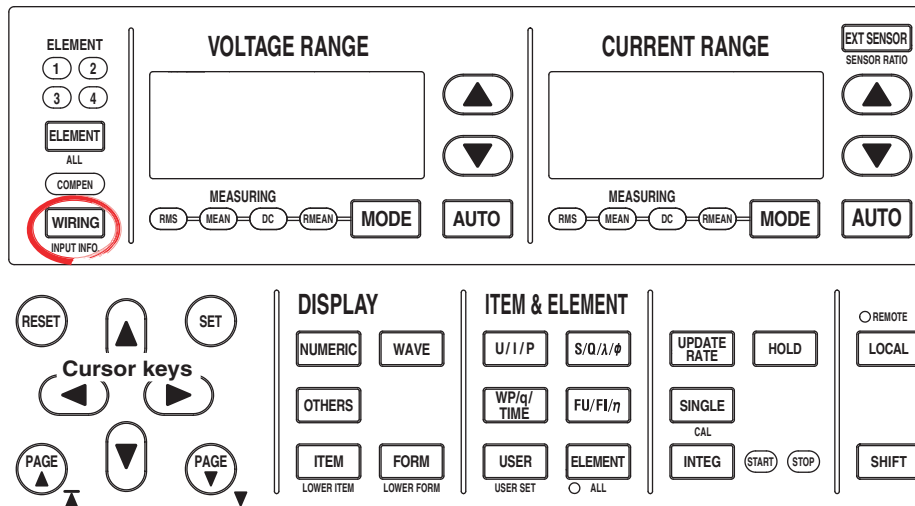
- Using the data from a three-phase, three-wire (three-voltage, three-current) system, various data of a star connection can be computed from the data of a delta connection (delta-star transformation). This function is effective when you wish to observe the phase voltage of an object that has no neutral line such as a motor.



For the equations, see section 6.3.

6.2 Setting the Delta Computation

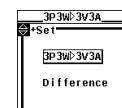
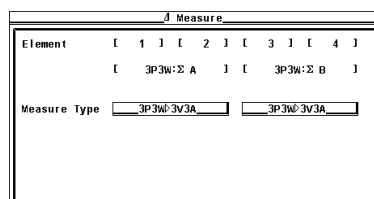
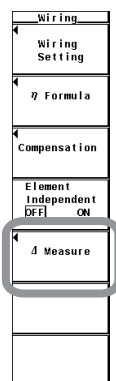
Procedure



To exit the menu during operation, press **ESC** located above the soft keys.

In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

1. Press **WIRING** to display the Wiring menu.
 2. Press the Δ **Measure** soft key to display the Δ Measure dialog box.
- **Selecting the Target Wiring Unit for the Delta Computation**
 3. Press the **cursor keys** to select the wiring unit.
(This step may not be necessary depending on the wiring system.)
 4. Press **SET** to confirm. A type selection box appears.
 - **Selecting the Delta Computation Type**
 5. Press the **cursor keys** to select the delta computation type.
(The menu varies depending on the wiring system.)
 6. Press **SET** to confirm.



Explanation

In the normal measurement of U and I, the sum or difference of the instantaneous values (sampled data) of the voltage or current between the elements assigned to the target wiring unit for the delta computation can be used to determine the measurement functions, ΔU and ΔI . This operation is called delta computation. For the equations, see section 6.3. The measurement period is the same as that described in section 2.2, "Measurement Function and Measurement Period" in the *User's Manual IM760301-01E*.

- **Selecting the Target Wiring Unit for the Delta Computation**

The wiring units for delta computation can be selected only on models with 4 input elements installed when the wiring system combination is as follows:

- Input elements 1 and 2 are set to 1P3W or 3P3W (ΣA).
- Input elements 2 and 3 are set to 1P3W or 3P3W (ΣA).
- Input elements 3 and 4 are set to 1P3W or 3P3W (ΣB).

- **Selecting the Delta Computation Type**

You can select the delta computation type from the choices below. The selectable items vary depending on the selected wiring system pattern.

| Wiring system | Selectable delta computation type |
|---------------|-----------------------------------|
| 1P3W | Difference, 3P3W>3V3A |
| 3P3W | Difference, 3P3W>3V3A |
| 3P4W | Star>Delta |
| 3P3W(3V3A) | Delta>Star |

- **Difference**

Computes the differential voltage and differential current between two elements.

When Difference is specified for wiring unit ΣA

$$\Delta F1[U_{diffA}]$$

$$\Delta F2[I_{diffA}]$$

When Difference is specified for wiring unit ΣB

$$\Delta F3[U_{diffB}]$$

$$\Delta F4[I_{diffB}]$$

- **3P3W>3V3A**

Computes other data when the wiring system is changed from three-phase, three-wire (3P3W) to three-voltage, three-current (3V3A).

When 3P3W>3V3A is specified for wiring unit ΣA

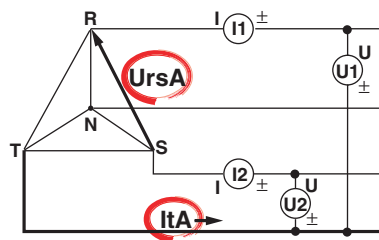
$$\Delta F1[U_{rsA}]$$

$$\Delta F2[I_{tA}]$$

When 3P3W>3V3A is specified for wiring unit ΣB

$$\Delta F3[U_{rsB}]$$

$$\Delta F4[I_{tB}]$$



6.2 Setting the Delta Computation

- **Star>Delta**

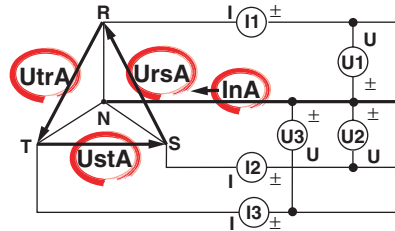
Computes various data of a delta connection from the data of a star connection (star-delta transformation) using the data from a three-phase, four-wire system.

$\Delta F1[UrsA]$

$\Delta F2[UstA]$

$\Delta F3[UtrA]$

$\Delta F4[InA]$



- **Delta>Star**

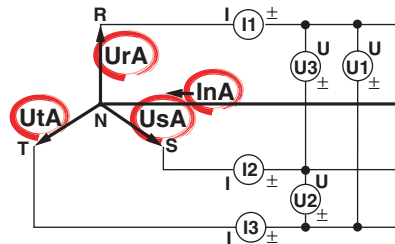
Computes various data of a star connection from the data of a delta connection (delta-star transformation) using the data from a three-voltage, three-current system. The neutral point of the star connection is computed as a centroid of the delta connection. If the actual neutral point does not match the centroid, an error results.

$\Delta F1[UrA]$

$\Delta F2[UsA]$

$\Delta F3[UtA]$

$\Delta F4[InA]$



Note

- It is recommended that the measurement range and scaling (VT/CT ratio and coefficients) of the elements that are being computed (delta computation) be set the same as much as possible. Using a different measurement range or scaling causes the measurement resolution of the sampled data to be different. In effect, the computation result will have errors.
- The number (1, 2, 3, and 4) that is attached to the measurement function symbol of the delta computation has no relation to the element number. The computation of the measurement functions $\Delta F1$ to $\Delta F4$ of delta computation varies depending on the wiring system and the delta computation type. For details, see section 6.3.
- On models with a single element, this function does not work. Therefore, the setup menus do not appear.
- If the target wiring system for delta computation is a single-phase, two-wire system (1P2W), delta computation cannot be performed.

6.3 Determination of Delta Computation

Delta Computation Type, Sampled Data, and Measurement Function of Delta Computation

The sampled data in the table are substituted in the equations of the voltage U and current I^* , and the computed result is determined. The synchronization source for the delta computation is the synchronization source (Sync Src) that is assigned to the first input element (smallest number) of the wiring unit on which delta computation is to be performed.

| Delta Computation Type | Sampled Data Substituted into the Voltage U and Current I Equations* | | Data Determined with the Delta Computation and Their Measurement Function Symbols | | Note |
|------------------------|--|-------------------|---|--|--|
| | $u(n)$ | $i(n)$ | | | |
| difference | $u_1 - u_2$ | $i_1 - i_2$ | Differential voltage Differential current | $\Delta F1[U_{diff}A]$ $\Delta F2[I_{diff}A]$ | — |
| 3P3W ▷3V3A | $u_1 - u_2$ | $-i_1 - i_2$ | Line voltage between phase R and S Line current of phase T | $\Delta F1[U_{rs}A]$ $\Delta F2[I_{tA}]$ | Assumptions $i_1 + i_2 + i_3 = 0$ |
| Delta ▷Star | $u_1 - \frac{(u_1+u_2)}{3}$ | — | Phase voltage of each phase | $\Delta F1[U_{rA}]$ | Assumptions The centroid of the delta connection is computed as the neutral point of the star connection. |
| | $u_2 - \frac{(u_1+u_2)}{3}$ | — | | $\Delta F2[U_{sA}]$ | |
| | $-\frac{(u_1+u_2)}{3}$ | — | | $\Delta F3[U_{tA}]$ | |
| | — | $i_1 + i_2 + i_3$ | Line current of the neutral line | $\Delta F4[I_{nA}]$ | — |
| Star ▷Delta | $u_1 - u_2$ | — | Line voltage of each phase | $\Delta F1[U_{rs}A]$ | |
| | $u_2 - u_3$ | — | | $\Delta F2[U_{stA}]$ | |
| | $u_3 - u_1$ | — | | $\Delta F3[U_{trA}]$ | |
| | — | $i_1 + i_2 + i_3$ | Line current of the neutral line | $\Delta F4[I_{nA}]$ | |

* Voltage U and current I equations in appendix 1, "Symbols and Determination of Measurement Functions" in the *User's Manual IM760301-01E*.

Note

- The wiring unit on which to perform delta computation can be selected from ΣA and ΣB . The input element that is assigned to the selected element is the element on which delta computation is performed. The numbers 1, 2, and 3 that are attached to sampled data u and i in the above table indicate that elements 1, 2, and 3 are target elements on which delta computation is performed. If the target elements of delta computation are 2, 3, and 4, replace the numbers 1, 2, and 3 that are attached to sampled data u and i with 2, 3, and 4, respectively.
- u_1 , u_2 , u_3 denote the sampled data of voltage of elements 1, 2, and 3, respectively. i_1 , i_2 , and i_3 denote the sampled data of current of elements 1, 2, and 3, respectively.
- The number (1, 2, 3, and 4) that is attached to the measurement function symbol of the delta computation has no relation to the element number.
- It is recommended that the measurement range and scaling (transformation ratio and coefficients) of the elements on which delta computation is performed be set the same as much as possible. Using a different measurement range or scaling causes the measurement resolution of the sampled data to be different. In effect, the computation result will have errors.

6.4 Delta Computation Specifications

| Item | Specifications |
|------------|---|
| difference | Differential voltage and differential current determined by computation |
| 3P3W→3V3A | Line voltage and phase current that are not measured but can be computed for a three-phase, three-wire system |
| DELTA→STAR | Line voltage and neutral line current that can be computed for a three-phase, three-wire (3V3A) system |
| STAR→DELTA | Neutral line voltage and neutral line current that can be computed for a three-phase, four-wire system |

7.1 Harmonic Measurement Function

Harmonic measurement can be used to measure the harmonic components of the voltage, current, and power as well as measurement functions such as the phase angle of each harmonic order with respect to the fundamental signal. It can also be used to compute the harmonic distortion of the voltage and current.

- **Elements**

Element refers to a set of input terminals that can input a single phase of voltage and current to be measured. The WT3000 can contain up to four elements, which are numbered from 1 to 4. An element number is appended to the measurement function symbol for the measured data that the WT3000 displays, so that the correspondence between the numeric data and the element can be seen. For example, "U1(2)" represents the voltage of the 2nd order harmonic of element 1.

- **Wiring System**

You can specify five wiring systems--single-phase, two-wire; single-phase, three-wire; three-phase, three-wire; three-phase, four-wire; and three-phase, three-wire (three-voltage, three current)--on the WT3000 to measure the power of various single-phase and three-phase power transmission systems.

- **Wiring Unit**

A wiring unit refers to a set of two or three input elements of the same wiring system that are grouped. Depending on the wiring system pattern, up to two wiring units can be constructed, which are represented by symbols ΣA and ΣB . The measurement function of a wiring unit is called a Σ function.

For example, "USA(1)" represents the voltage average of the fundamental signal of the input elements that are assigned to wiring unit ΣA .

- **PLL Source «For procedures, see section 7.4»**

When measuring harmonics, the fundamental period (period of the fundamental signal) must be determined in order to analyze the higher orders. The PLL (Phase Locked Loop) source is the signal that is used to determine the fundamental period. Selecting a signal with little distortion or fluctuation for the PLL source results in a stable harmonic measurement. An ideal signal would be a rectangular wave with amplitude that is greater than or equal to 50% or 100% of the measurement range (see section 1.3) when the crest factor (see section 4.6 in the *User's Manual IM760301-01E*) is set to 3 or 6, respectively.

In addition, stable harmonic measurement can also be achieved by applying a clock signal (Ext Clk) that has the same period as the waveform on which to perform harmonic measurements.

For a description of the terminology such as fundamental signal, harmonic signal, and harmonic order, see appendix 4 in the *User's Manual IM760301-01E*.

Types of Harmonic Measurement Functions

The data (numeric data) of harmonic measurement functions is measured or computed from the sampled data* described later in “Measurement Period.”

* See the description of the sampled data in “Types of Measurement Functions during Normal Measurement” of chapter 2 in the *User's Manual IM760301-01E*.

- **Types of Harmonic Measurement Functions**

- **Harmonic Measurement Functions for Each Input Element**

The following 28 types of harmonic measurement functions are available. For details related to the determination of measurement function data, see section 7.9.

| Measurement function | | Characters or Numbers in Parentheses | | | All (No Parentheses) |
|---|--------------|--------------------------------------|-----|-----|----------------------|
| | | dc | 1 | k | |
| Voltage | $U()$ | Yes | Yes | Yes | No |
| Current | $I()$ | Yes | Yes | Yes | No |
| Active power | $P()$ | Yes | Yes | Yes | No |
| Apparent power | $S()$ | Yes | Yes | Yes | No |
| Reactive power | $Q()$ | Always 0 | Yes | Yes | No |
| Power factor | $\lambda()$ | Yes | Yes | Yes | No |
| Phase difference | $\phi()$ | No | Yes | Yes | No |
| Phase difference with respect to U(1) | $\phi U()$ | No | No | Yes | No |
| Phase difference with respect to I(1) | $\phi I()$ | No | No | Yes | No |
| Impedance of the load circuit | $Z()$ | Yes | Yes | Yes | No |
| Series resistance of the load circuit | $R_s()$ | Yes | Yes | Yes | No |
| Series reactance of the load circuit | $X_s()$ | Yes | Yes | Yes | No |
| Parallel resistance of the load circuit | $R_p()$ | Yes | Yes | Yes | No |
| Parallel reactance of the load circuit | $X_p()$ | Yes | Yes | Yes | No |
| Voltage harmonic distortion factor | $Uhdf()$ | Yes | Yes | Yes | No |
| Current harmonic distortion factor | $Ihdf()$ | Yes | Yes | Yes | No |
| Active power harmonic distortion factor | $Phdf()$ | Yes | Yes | Yes | No |
| Total harmonic distortion of voltage | $Uthd$ | No | No | No | Yes |
| Total harmonic distortion of current | $Ithd$ | No | No | No | Yes |
| Total harmonic distortion of active power | $Pthd$ | No | No | No | Yes |
| Voltage telephone harmonic factor | $Uthf$ | No | No | No | Yes |
| Current telephone harmonic factor | $Ithf$ | No | No | No | Yes |
| Voltage telephone influence factor | $Utif$ | No | No | No | Yes |
| Current telephone influence factor | $Itif$ | No | No | No | Yes |
| Harmonic voltage factor | hvf | No | No | No | Yes |
| Harmonic current factor | hcf | No | No | No | Yes |

Yes: Numeric data available, No: No numeric data available

- The meaning of measurement functions with parentheses varies depending on the characters or numbers that are inside the parentheses as follows:
 - dc: Indicates numeric data of the DC component.
 - 1: Indicates numeric data of the fundamental wave.
 - k: Indicates numeric data from 2nd to Nth order harmonics. N is the upper limit of the measured order (see section 7.6). The upper limit is determined automatically (maximum is 100) by the frequency of the PLL source.
- Uhdf to hcf are measurement functions that indicate characteristics specific to the harmonics. For details on the determination of the measurement functions, see section 7.9.

- **Harmonic Measurement Function That Indicates the Phase Difference (ϕ) of the Voltage and Current between the Input Elements**

There are five harmonic measurement functions that express the phase difference (ϕ).

ϕU_i-U_j , ϕU_i-U_k , ϕU_i-I_i , ϕU_i-I_j , and ϕU_i-I_k

(where i , j , and k are input element numbers)

Explanation is given for the case when the number of installed input elements is 4, elements 1, 2, and 3 are assigned to wiring unit ΣA using a three-phase, four-wire system. Here $i = 1$, $j = 2$, and $k = 3$.

In this case, the numeric data of the harmonic measurement functions of phase difference concerning elements 1, 2, and 3 can be determined as shown below.

- $\phi U1-U2$
Phase difference of the fundamental voltage $U2(1)$ of element 2 with respect to the fundamental voltage $U1(1)$ of element 1.
- $\phi U1-U3$
Phase difference of the fundamental voltage $U3(1)$ of element 3 with respect to the fundamental voltage $U1(1)$ of element 1.
- $\phi U1-I1$
Phase difference of the fundamental current $I1(1)$ of element 1 with respect to the fundamental voltage $U1(1)$ of element 1.
- $\phi U1-I2$
Phase difference of the fundamental current $I2(1)$ of element 2 with respect to the fundamental voltage $U1(1)$ of element 1.
- $\phi U1-I3$
Phase difference of the fundamental current $I3(1)$ of element 3 with respect to the fundamental voltage $U1(1)$ of element 1.

If the wiring pattern is set up so that input elements 1 and 2 are assigned to wiring unit ΣA using a three-phase, three-wire system and input elements 3 and 4 are assigned to wiring unit ΣB using a three-phase, three-wire system, the numeric data below are determined.

- Wiring unit ΣA : $\phi U1-U2$, $\phi U1-I1$, and $\phi U1-I2$
 - Wiring unit ΣB : $\phi U3-U4$, $\phi U3-I3$, and $\phi U3-I4$
- $\phi U1-U3$ and $\phi U1-I3$ are not determined.

- **Harmonic Measurement Function of Wiring Units ΣA and ΣB (Σ Functions)**

The following 6 types of harmonic measurement functions are available. For details on the determination of each measurement function, see section 7.9.

| Measurement function | Characters or Numbers in Parentheses |
|----------------------|--------------------------------------|
| | 1 |
| $U\Sigma()$ | Yes |
| $I\Sigma()$ | Yes |
| $P\Sigma()$ | Yes |
| $S\Sigma()$ | Yes |
| $Q\Sigma()$ | Yes |
| $\lambda\Sigma()$ | Yes |

Yes: Numeric data available

- For measurement functions with parentheses, the value "1" is entered in the parentheses. This represents the numeric data of the fundamental signal.

Numeric Displays for Harmonic Measurement

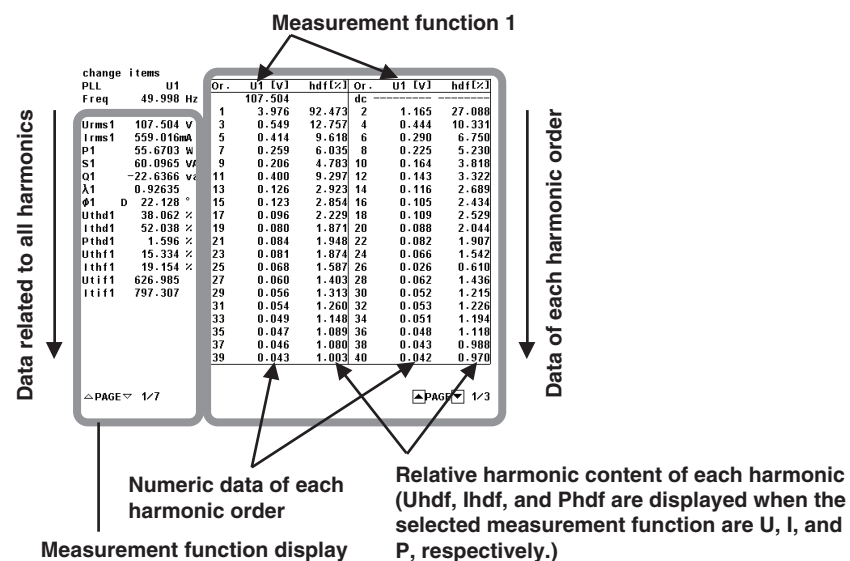
In addition to 4-item, 8-item, 16-item, and all-item displays, list display (single list and dual list) can be shown.

- You can select 4, 8, 16, or All for the number of displayed items. Not all the data can be displayed on one screen. You can scroll through the displayed items to view the following data.

| Measurement function | | | Data |
|----------------------|----------|-----|------|
| Urms1 | 105.677 | v | |
| Irms1 | 569.556 | mA | |
| P1 | 55.7601 | W | |
| S1 | 60.1889 | VA | |
| Q1 | -22.6609 | var | |
| U1(1) | 5.793 | v | |
| I1(1) | 34.467 | mA | |
| P1(1) | 0.1937 | W | |

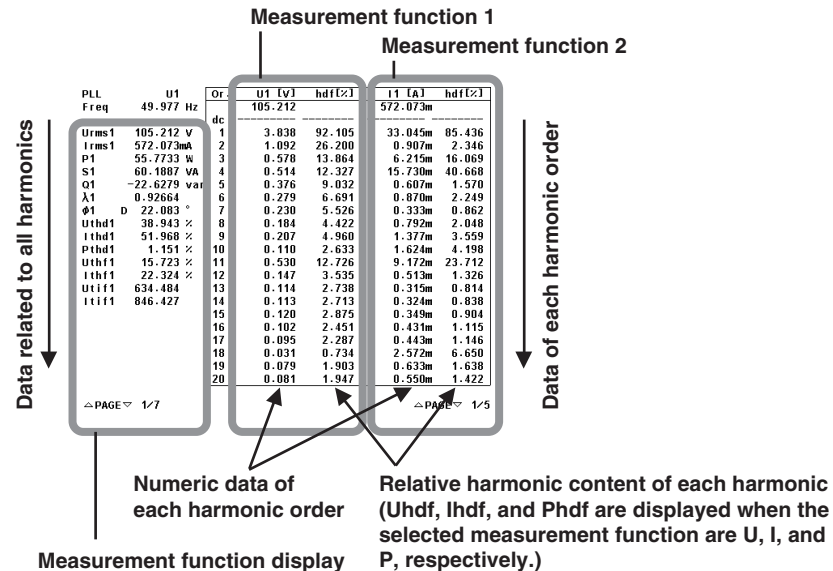
- For each measurement function, the numeric data of the fundamental and all harmonics can be displayed in two columns. When the numeric data is displayed simultaneously with waveforms, bar graphs, or trends, approximately half of the data is displayed.

- The data of a single measurement function is displayed by separating the even and odd harmonics in each column. You can select the following measurement functions: U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp.



- **Dual List**

The data of two measurement functions is displayed in its own column. You can select the following measurement functions: U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp.



- **Scrolling the Page**

The numeric display screen can be switched at the page level. If different items are displayed on each page, the displayed items can be switched collectively.

- **Resetting the Numeric Display**

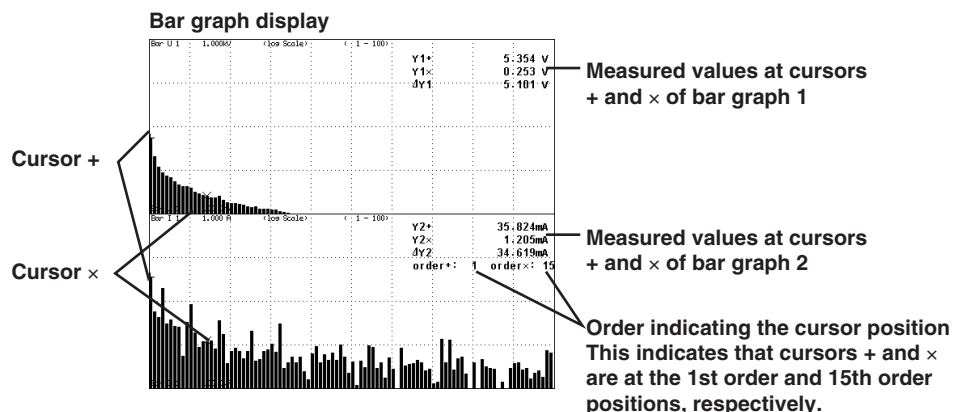
If the number of displayed items is 4, 8, or 16, the displayed order of measurement functions can be reset to factory default settings.

Equation for Distortion Factor «For procedures, see section 7.6.»

The measurement functions, Uhdf, lhdf, Phdf, Uthd, lthd, and Pthd during harmonic measurement have two defining equations. For the equations, see section 7.9.

Bar Graph Display «For procedures, see section 7.7.»

The amplitude of each harmonic can be displayed on the bar graph. The horizontal axis represents harmonic order, and the vertical axis represents the amplitude of each harmonic. The harmonic measurement functions, elements, and order to be displayed can be specified. You can select the following harmonic measurement functions: U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp. The screen can be divided into top and bottom halves so that the bar graph can be displayed simultaneously with the numeric data.



Vector Display «For procedures, see section 7.8.»

During harmonic measurement, vectors can be displayed to show the relationship between the phase difference and amplitude (rms value) of the fundamental signals $U(1)$ and $I(1)$ of each element that is assigned to the selected wiring unit. The positive vertical axis is set to 0 (angle 0), and the vector of each input signal is displayed. In addition, you can zoom in on the vector or display the values of the amplitude and the phase difference between the signals simultaneously.

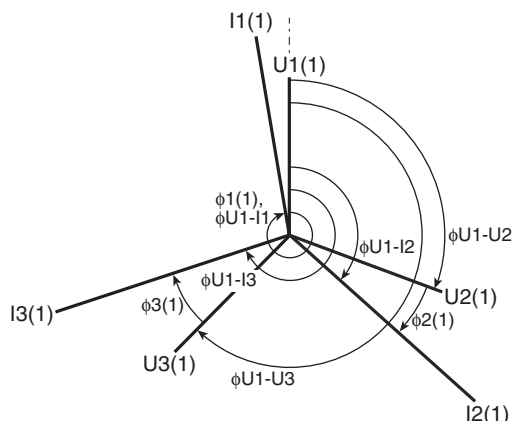
The vector display is shown on the next page.

The elements that are to be displayed as vectors vary depending on the number of installed input elements and the selected wiring pattern. Explanation is given for the case when the number of installed input elements is 4 and wiring unit ΣA is set to a three-phase, four-wire system.

When the target of the vector display is set to wiring unit ΣA , the target elements are 1, 2, and 3. Vectors 1, 2, and 3 correspond to elements 1, 2, and 3, respectively. The relationship between the phase difference and amplitude of $U1(1)$, $U2(1)$, $U3(1)$, $I1(1)$, $I2(1)$, and $I3(1)$ is displayed as vectors.

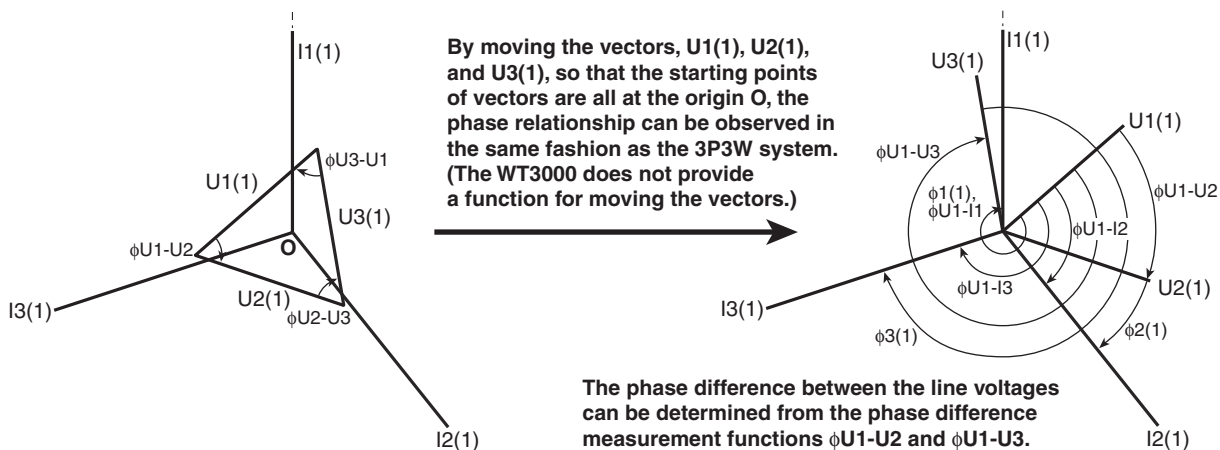
• **Vector Display When the Wiring System Is 3P4W (Three-Phase, Four-Wire)**

$U1(1)$, $U2(1)$, and $U3(1)$ are common mode voltages. $I1(1)$, $I2(1)$, and $I3(1)$ are line currents.



• **Vector Display When the Wiring System Is 3P3W (3V3A) (Three-Voltage, Three-Current)**

$U1(1)$, $U2(1)$, and $U3(1)$ are line voltages. $I1(1)$, $I2(1)$, and $I3(1)$ are line currents.



The phase difference between the line voltages can be determined from the phase difference measurement functions $\phi U1-U2$ and $\phi U1-U3$.

$\phi U1-U2$ = This is the measurement function $\phi U1-U2$.

$\phi U2-U3 = (\phi U1-U3) - (\phi U1-U2) - 180^\circ$

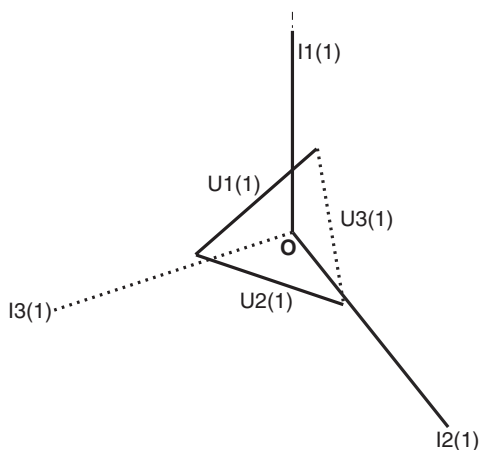
$\phi U3-U1 = -(\phi U1-U3)$

• **Vector Display When the Wiring System Is 3P3W (Three-Phase, Three-Wire)**

$U1(1)$, $U2(1)$, and $U3(1)$ are line voltages. $I1(1)$, $I2(1)$, and $I3(1)$ are line currents.

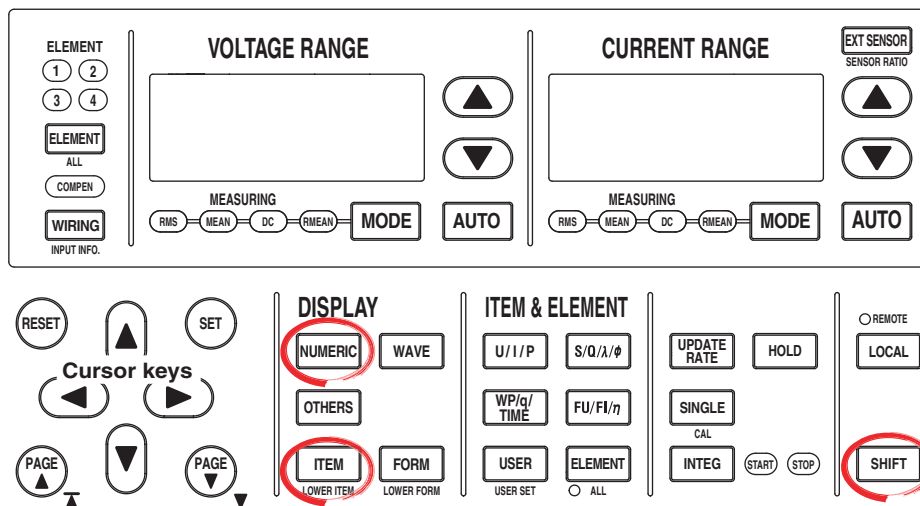
However, $U3(1)$ and $I3(1)$ are not actually measured for the 3P3W system.

The vectors are displayed through computation.



7.2 Displaying Numeric Data

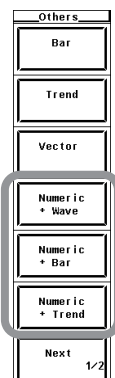
Procedure



To exit the menu during operation, press **ESC** located above the soft keys.

In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

- **Displaying Numeric Data**
 1. Press **NUMERIC** to display numeric data.
- **Displaying Numeric Data on the Split Display**
 1. Press **OTHERS** to display the Others menu.
 2. Press any of the soft keys from **Numeric+Wave**, **Numeric+Bar**, and **Numeric+Trend** to select the display mode.



The following procedures are given as typical examples in which the display mode is set to Numeric.

- **Selecting the Number of Displayed Items or List Display**

2. Press **FORM** to display the Numeric Form menu.
3. Select one of the soft keys from **4 Items** to **Dual List** to select the number of displayed items or list display.



- **Page Scrolling the Display (PAGE ▼ ▲ key)**

- **When Numeric Form (the Number of Displayed Items) Is 4 Items, 8 Items, or 16 Items**

4. Press **PAGE ▼** or **PAGE ▲** to scroll the page.
 - Press **PAGE ▼** to display the next page.
 - Press **PAGE ▲** to display the previous page.

- **When Numeric Form (the Number of Displayed Items) Is ALL Items**

4. Press **PAGE ▼** or **PAGE ▲** to scroll the page.
 - The first page is always displayed in the top half of the screen.
 - Press **PAGE ▼** to display the next page in the lower half of the screen.
 - Press **PAGE ▲** to display the previous page in the lower half of the screen.
 - * If numeric data is displayed on the split display, pages 1 to 9 are scrolled in the top half of the screen.

- **When Numeric Form (the Number of Displayed Items) Is Single List or Dual List**

4. Press **ESC** to clear the soft menu.
5. Press the **cursor keys (left and right keys)** to move the cursor to the left, center, or right column of the screen.
6. Press **PAGE ▼** or **PAGE ▲** to scroll the page.
 - The left and right columns can be scrolled independently.
 - If the cursor is in the left column on the screen, the measurement function display is page scrolled.
 - If the cursor is in the center or left column on the screen, the data display of harmonic orders is page scrolled.

- **Page Scrolling the Display (Cursor Keys)**

- **When Numeric Form (the Number of Displayed Items) Is 4 Items, 8 Items, or 16 Items**

- Press the **cursor keys (up and down keys)** to move the highlight within the page. To switch to the next page or previous page, press **PAGE ▼** or **PAGE ▲**.

- **When Numeric Form (the Number of Displayed Items) Is ALL Items, Single List, or Dual List**

4. Press the **cursor keys (up and down keys)**. The highlight moves.
 - If you press the down cursor key when the highlight is at the bottom row, the next page is displayed.
 - If you press the up cursor key when the highlight is at the top row, the previous page is displayed.

- **Jumping to the Last or First Page**

4. Press **SHIFT+PAGE ▼ (▼)** or **SHIFT+PAGE ▲ (▲)**.
 - Press SHIFT+PAGE ▼ (▼) to display the last page.
 - Press SHIFT+PAGE ▲ (▲) to display the first page.

Explanation

- **Meaning of the Measurement Function Symbols**

For the meanings of the measurement function symbols that are displayed, see section 7.1, “Harmonic Measurement Function” or 7.9, “Harmonic Measurement Specifications.”

Example 20th harmonic voltage of element 2

U2(20)

20th order
Element 2
Voltage

Average of the Fundamental Current of the Elements Combined by Wiring Unit ΣB

IΣB(1)

1st order (fundamental wave)
Σ function of wiring unit ΣB
Current

- **Selecting the Display Mode**

Select the display format of the numeric data from below. [-----] (no data) is displayed in places where the measurement function is not selected or there are no numeric data.

- **Displaying the Numeric Data on the Entire Screen**

Press the NUMERIC key to display the numeric data on the entire screen.

- **Displaying Numeric Data by Dividing the Screen into Halves (Split Display)**

- **Numeric+Wave**
The numeric data and waveform are displayed separately in the top and bottom windows.
- **Numeric+Bar**
The numeric data and bar graph are displayed separately in the top and bottom windows. For details on how to set the bar graph display, see section 7.7.
- **Numeric+Trend**
The numeric data and trend are displayed separately in the top and bottom windows.

- **Selecting the Number of Displayed Items or List Display**

Select the number of numeric data items that are displayed simultaneously or list display from the choices below.

- **4 Items**

- When the display mode is Numeric, four numeric data values are displayed in one column.

- **8 Items**
 - When the display mode is Numeric, eight numeric data values are displayed in one column.
 - When the display mode is not Numeric, eight numeric data values are displayed in two columns.
- **16 Items**
 - When the display mode is Numeric, 16 numeric data values are displayed in two columns.
- **All Items**
 - A table is displayed indicating the numeric data of items with measurement functions listed vertically and symbols indicating elements and wiring units listed horizontally. The number of displayed items varies depending on the number of installed elements.
- **Single List**
 - When the display mode is Numeric, 42 numeric data values for a single measurement function are displayed in two columns.
 - When the display mode is not Numeric, 22 numeric data values for a single measurement function are displayed in two columns.
- **Dual List**
 - When the display mode is Numeric, 22 numeric data values each for two measurement functions are displayed in each column.
 - When the display mode is not Numeric, 11 numeric data values each for two measurement functions are displayed in each column.

Note

- The order can be displayed from normal measured value (---) or from dc (0th order) up to 100th order. However, the numeric data up to the upper limit of measured order (see section 7.9) that is automatically determined by the frequency of the PLL source is the data determined by the harmonic measurement.
- [-----] (no data) is displayed in places where the measurement function is not selected or where no numeric data is present.
- There are no overrange display [-OL-] and zero display (zero suppression) for the harmonic numeric data from dc (0th order) to the 100th order. For details on the overrange display and zero display (zero suppression) of normal measured values (order: ---), see section 5.1 in the *User's Manual IM760301-01E*.
- If the power factor λ is greater than 1 and less than or equal to 2, λ becomes [1]. ϕ displays zero.
- If the power factor λ is greater than 2, λ and ϕ display errors.

• Page Scrolling the Display

• When ALL is selected

The first page is constantly displayed in the upper half of the screen, and page 2 and subsequent pages are switched in the lower half.

| | Element1 | Element2 | Element3 | Element4 |
|---------------|-----------|-----------|-----------|-----------|
| Voltage | 100V/rms | 100V/rms | 100V/rms | 100V/rms |
| Current | 500mA/rms | 500mA/rms | 500mA/rms | 500mA/rms |
| U [V] | 105.715 | 105.746 | 105.620 | 0.000 |
| I [A] | 569.215m | 565.763m | 0.000m | 1.592m |
| P [W] | 55.0692 | 55.5459 | 0.0000 | -0.0000 |
| S [VA] | 60.1748 | 59.8274 | 0.0000 | 0.0000 |
| Q [var] | -22.3526 | -22.2255 | 0.0000 | 0.0000 |
| λ [] | 0.92845 | 0.92844 | ----- | Error |
| ϕ [°] | 21.806 | 21.808 | ----- | Error |
| fU [Hz] | 50.000 | 50.000 | 50.000 | Error |
| fI [Hz] | 1.7288k | 1.9361k | Error | Error |

| | | | | |
|---------|----------|----------|----------|---------|
| U+pk[V] | 148.617 | 148.676 | 148.509 | 0.119 |
| U-pk[V] | -148.622 | -148.669 | -148.506 | -0.104 |
| I+pk[A] | 1.04405 | 1.04036 | 0.000m | 6.537m |
| I-pk[A] | -1.04668 | -1.04046 | 0.000m | -5.616m |
| Cfu [] | 1.406 | 1.406 | 1.406 | Error |
| Cfi [] | 1.839 | 1.839 | ----- | 4.105 |
| Pc [W] | 55.9683 | 55.6440 | 0.0000 | Error |

The first page is always displayed.

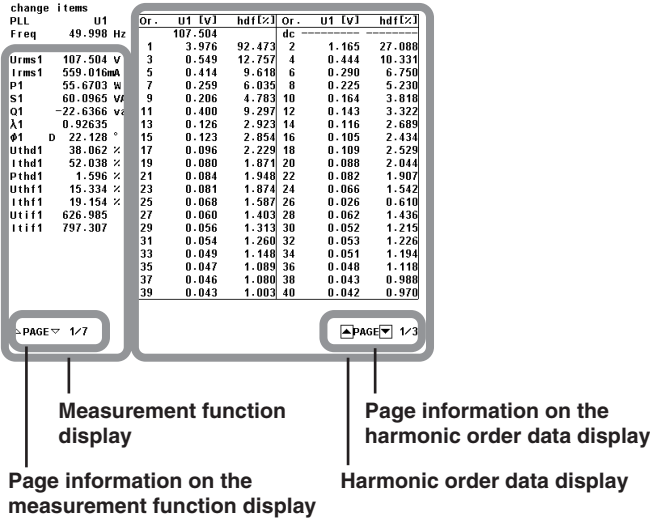
Page 2 and subsequent pages are displayed by page scrolling.

- * If ALL display is shown on the split screen, pages 1 to 9 are scrolled in the top half of the screen.

7.2 Displaying Numeric Data

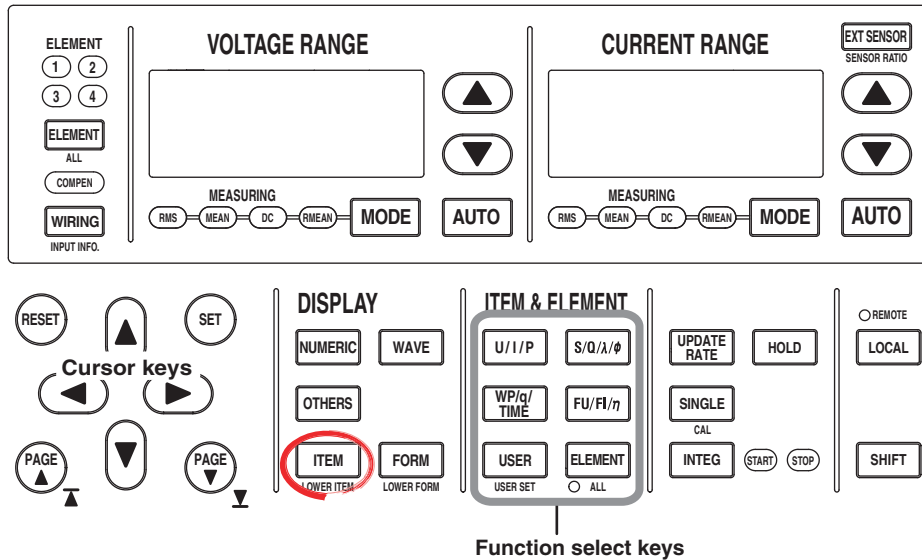
- **When Single List or Dual List is selected**
The measurement function display (left side of the screen) and the harmonic order data display (right side of the screen) can be page scrolled independently.

Single List Display Example



7.3 Changing the Displayed Items of Numeric Data

Procedure



To exit the menu during operation, press **ESC** located above the soft keys.

In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

- Check that display mode is set to Numeric, Numeric+Wave, or Numeric+Trend. For details on how to set the display mode, see section 7.1.
- The following procedures are given as typical examples in which the display mode is set to Numeric.

There are four ways to change the displayed items of numeric data. For the procedures of each method, see the pages indicated below.

- Selecting the displayed items using the function select key
 - Using the preset key See page 7-13.
 - Using the USER key See page 7-14.
 - Selecting the displayed items from the menu See page 7-15.
 - Selecting the harmonic order on the ALL display See page 7-16.
 - Resetting the order of the displayed items See page 7-16.

Changing the Displayed Items Using the Function Select Key

• Using the Preset Key

The display of measurement functions of U, I, P, S, Q, λ , ϕ , WP, q, TIME, FU, FI, and η and the element/wiring unit can be changed using function select keys.

• Selecting the Item to Be Changed

1. Press **ESC** to clear the Numeric Form menu.
2. Press the **cursor keys** to select the item to be changed. The item to be changed is highlighted.
 - If the display mode is set to Single List or Dual List, move the cursor to the center or the right side of the screen.

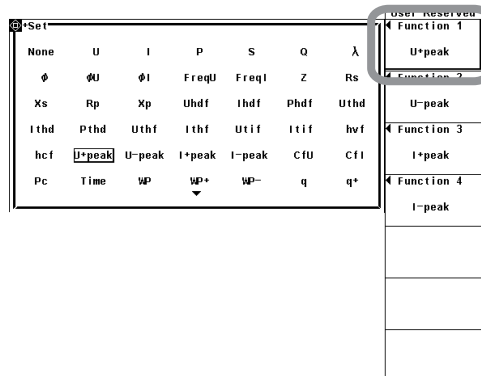
7.3 Changing the Displayed Items of Numeric Data

- **Changing the Measurement Function**
 3. Press the **U/I/P**, **S/Q/λ/φ**, **WP/q/Time**, or **FU/FI/η** function select key to select the displayed measurement function.

When the display mode is set to Single List or Dual List, only the measurement functions that contain harmonic order data can be selected. Press U/I/P to select U, I, or P. Press S/Q/λ/φ to select S, Q, λ, φ, φU, or φI.
- **Changing the Element/Wiring Unit**
 4. Press **ELEMENT** to select the element/wiring unit.
- **Changing the Element/Wiring Unit Collectively**
 5. Press **SHIFT+ELEMENT (ALL)**. ALL LED illuminates, and the element/wiring unit of all the displayed items on the displayed page can be changed collectively. This completes the procedure for changing the displayed items using the function select keys.
- **Using the USER Key**

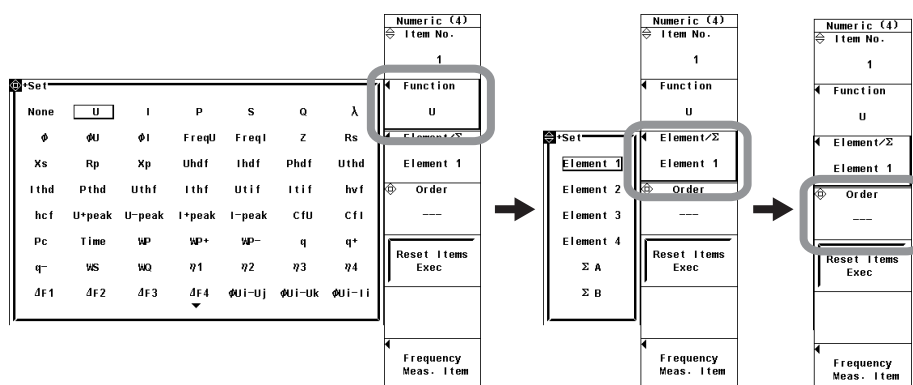
By assigning measurement functions to the USER key, up to four measurement functions can be directly displayed.

 - **Assigning Measurement Functions to the USER Key**
 6. Press **SHIFT+USER (USER SET)** to display the User Reserved menu.
 7. Press any of the soft keys from **Function 1 to 4** to select the desired Function. The measurement function selection box appears.
 8. Press the **cursor keys** to select any of the measurement functions starting with None.
 9. Press **SET**. The symbol for the selected measurement function is displayed at the highlighted position.
 - **Changing the Measurement Function with the USER Key**
 10. Press **USER** to select the measurement function in the same fashion as step 3.



Selecting the Displayed Items from the Menu

1. Press **ITEM** to display the Numeric menu.
- **Selecting the Item to Be Changed**
 2. Press the **Item No.** soft key.
 3. Press the **cursor keys** to select the item to be changed. The item to be changed is highlighted.
 - **Changing the Measurement Function**
 4. Press the **Function** soft key to display the measurement function selection box.
 5. Press the **cursor keys** to select any of the measurement functions starting with None.
 6. Press **SET**. The symbol for the selected measurement function and the numeric data are displayed at the highlighted position.
 - When the display mode is set to Single List or Dual List, only the measurement functions that contain harmonic order data can be selected. (U, I, P, S, Q, λ , ϕ , ϕ U, ϕ I, Z, Rs, Xs, Rp, and Xp)
 - **Changing the Element/Wiring Unit**
 7. Press the **Element/ Σ** soft key to display the element/wiring unit selection box.
 8. Press the **cursor keys** to select any of the elements/wiring units starting with Element1.
 9. Press **SET**. The symbol for the selected element number or wiring unit and the numeric data are displayed at the highlighted position.
 - **Changing the Order**
 10. Press **Order** soft key.
 11. Press the **cursor keys** to set the order. The specified harmonic order and the numeric data are displayed at the highlighted position. This completes the procedure for changing the displayed items using the menu.
 - When the display mode is set to Single List or Dual List, you do not have to set the order.



7.3 Changing the Displayed Items of Numeric Data

Selecting the Harmonic Order on the ALL Display

1. Press **PAGE** ▼ ▲ to display the harmonic order data page (page 6 or page 7).
2. Press **FORM** to display the Numeric Form menu.
3. Press the **cursor keys** to set the order.

| | |
|--------------|-------|
| Numeric Form | |
| 4 | Items |
| 8 | Items |
| 16 | Items |
| All | Items |
| Single | List |
| Dual | List |
| Order | 1 |

Resetting the Order of the Displayed Items

1. Press **ITEM** to display the Numeric menu.
2. Press the **Reset Items Exec** soft key. An Alert dialog box appears.
3. Press the **cursor keys** to select OK or Cancel.
4. Select OK and press **SET** to reset the order of the displayed items on all pages.
If you select Cancel and press **SET** the order of the displayed items are not reset.

Alert

Really

Numeric Items will be initialized.
Do you want to execute?

OK Cancel

| | |
|----------------------|-----------|
| Numeric (8) | |
| Item No. | 1 |
| Function | U |
| Element/Σ | Element 1 |
| Order | |
| Reset Items Exec | |
| Frequency Meas. Item | |

Explanation

The following limitations on changing the displayed items exist depending on Item Amount (the number of displayed items).

| Number of Displayed Items | | Changing the Displayed Items |
|----------------------------|--|--|
| 4 Items, 8 Items, 16 Items | | Yes |
| ALL Items | | The displayed item cannot be changed independently. Switch the display using the cursor keys or by page scrolling. The order can be selected on the harmonic data display on six or seven pages. |
| Single List or Dual List | Measurement function display (left side of the screen) | The displayed item cannot be changed independently. Switch the display using the cursor keys or by page scrolling. |
| | Harmonic order data display (right side of the screen) | Only the measurement functions that contain harmonic order data can be selected. (U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp) |

- **When Numeric Form (the Number of Displayed Items) Is 4 Items, 8 Items, or 16 Items**

- **Changing the Measurement Function**

- The selectable measurement functions are the items indicated in section 7.1, "Harmonic Measurement Function."
 - You can also select not to display the measurement functions (None).

- **Changing the Element/Wiring Unit**

You can select the element/wiring unit from the choices below. The selectable items vary depending on the installed elements.

Element1, Element2, Element3, Element4, SA, and SB

- **Changing the Order**

The order can be set to normal measured value (---) or from dc (0th order) up to 100th order.

| | | | | | | |
|-------|--------|----|---|--------------------|---------|----|
| U1(1) | 4.219 | v | | U1(1) | 5.745 | v |
| I1(1) | 31.921 | mA | | I1(1) | 36.790 | mA |
| P1(1) | 0.1346 | W | Change the measurement function of the third item → | Φ1(1) | -20.322 | ° |
| S1(1) | 0.1347 | VA | | S1(1) | 0.2113 | VA |
| | | | Change the element of the third item ↘ | U1(1) | 7.973 | v |
| | | | | I1(1) | 29.771 | mA |
| | | | | P2(1) | 0.2358 | W |
| | | | | S1(1) | 0.2374 | VA |
| | | | | ↓ Change the order | | |
| | | | | U1(1) | 5.836 | v |
| | | | | I1(1) | 34.188 | mA |
| | | | | P2(7) | 0.0009 | W |
| | | | | S1(1) | 0.1995 | VA |

7.3 Changing the Displayed Items of Numeric Data

- **When Numeric Form (the Number of Displayed Items) Is Single List or Dual List**

Two types of lists are available for displaying the harmonic order data. When set to Single List, the data of List Item No. 1 is displayed using two columns. When set to Dual List, the data of List Item No. 1 and 2 is displayed in each column. You can set the list item No. to 1 or 2.

- **Changing the Measurement Function**

Select the measurement function to be changed from the choices below.

U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp

- **Changing the Element/Wiring Unit**

The description is the same as “When Numeric Form (the Number of Displayed Items) Is 4 Items, 8 Items, or 16 Items” on the previous page.

Single List Display Example

| PLL | U1 | Or. | U1 [V] | hdf [Z] | I1 [A] | hdf [Z] |
|-------------|------------|-----|---------|---------|----------|---------|
| Freq | 49.977 Hz | dc | 105.212 | | 572.073m | |
| Urms1 | 105.212 V | 1 | 3.838 | 92.105 | 33.045m | 85.436 |
| Irms1 | 572.073mA | 2 | 1.092 | 26.200 | 0.907m | 2.346 |
| P1 | 55.7733 W | 3 | 0.578 | 13.864 | 6.215m | 16.069 |
| S1 | 60.1087 V | 4 | 0.514 | 12.327 | 15.730m | 40.668 |
| Q1 | -22.6279 V | 5 | 0.376 | 9.032 | 0.607m | 1.570 |
| λ 1 | 0.92664 | 6 | 0.279 | 6.691 | 0.870m | 2.249 |
| ϕ 1 | D 22.083 ° | 7 | 0.230 | 5.526 | 0.333m | 0.862 |
| Uthd1 | 38.943 % | 8 | 0.184 | 4.422 | 0.792m | 2.048 |
| Ithd1 | 51.968 % | 9 | 0.207 | 4.960 | 1.377m | 3.559 |
| Pthd1 | 1.151 % | 10 | 0.110 | 2.633 | 1.624m | 4.198 |
| Uthf1 | 15.723 % | 11 | 0.530 | 12.726 | 9.172m | 23.712 |
| Ithf1 | 22.324 % | 12 | 0.147 | 3.535 | 0.513m | 1.326 |
| Uthf1 | 634.484 | 13 | 0.114 | 2.738 | 0.315m | 0.814 |
| Ithf1 | 846.427 | 14 | 0.113 | 2.713 | 0.324m | 0.838 |
| | | 15 | 0.120 | 2.875 | 0.349m | 0.904 |
| | | 16 | 0.102 | 2.451 | 0.431m | 1.115 |
| | | 17 | 0.095 | 2.287 | 0.443m | 1.146 |
| | | 18 | 0.031 | 0.734 | 2.572m | 6.650 |
| | | 19 | 0.079 | 1.903 | 0.633m | 1.638 |
| | | 20 | 0.081 | 1.947 | 0.550m | 1.422 |

Harmonic order data display

Measurement function display

- **Selecting the Order on the ALL Display**

The order can be selected on page 6 or 7 of the ALL display.

| Order | Element1 | Element2 | Element3 | Element4 |
|------------------|-----------|-----------|-----------|-----------|
| k = 1 | 100Vrms | 100Vrms | 100Vrms | 100Vrms |
| Voltage | 500mA rms | 500mA rms | 500mA rms | 500mA rms |
| U [V] | 106.336 | 106.367 | 106.240 | 0.000 |
| I [A] | 565.720m | 562.282m | 0.000m | 1.614m |
| P [W] | 55.8231 | 55.5008 | 0.0000 | -0.0000 |
| S [VA] | 60.1563 | 59.8084 | 0.0000 | 0.0000 |
| Q [var] | -22.4181 | -22.2869 | 0.0000 | 0.0000 |
| λ [°] | 0.92797 | 0.92798 | ----- | Error |
| ϕ [°] | D 21.880 | D 21.878 | ----- | Error |
| f [Hz] | 49.995 | 49.995 | 49.995 | Error |
| f1 [Hz] | 1.5035k | 1.6573k | Error | Error |
| U(k)[V] | 3.463 | 3.464 | 3.460 | 0.001 |
| I(k)[A] | 32.380m | 32.154m | 0.000m | 0.022m |
| P(k)[W] | 0.112 | 0.1104 | 0.0000 | 0.0000 |
| S(k)[VA] | 0.1121 | 0.1114 | 0.0000 | 0.0000 |
| Q(k)[var] | -0.0145 | -0.0145 | 0.0000 | 0.0000 |
| λ (k)[°] | 0.99163 | 0.99143 | Error | 0.69764 |
| ϕ (k)[°] | -7.419 | -7.504 | Error | 45.762 |
| ϕU (k)[°] | | | | |
| ϕI (k)[°] | | | | |

Measured data of the selected order

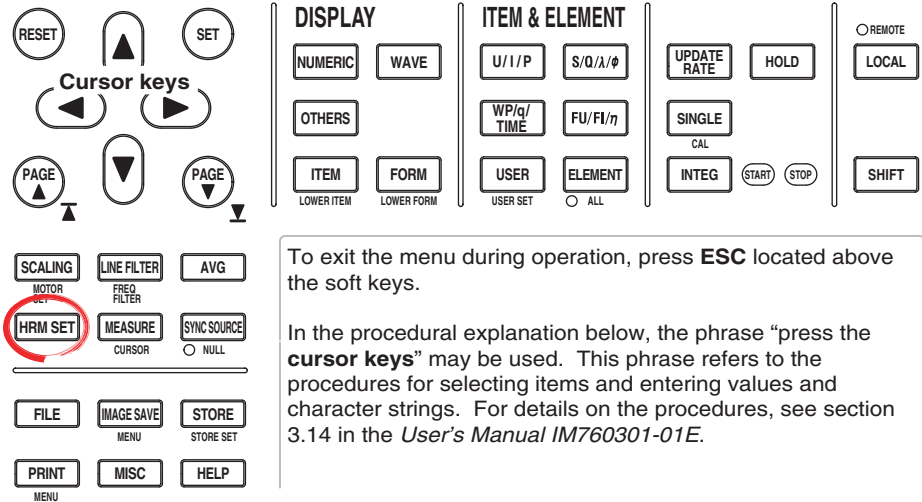
Select the order using the cursor keys

Note

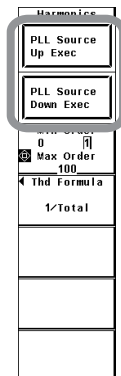
- For the meanings of the measurement function symbols that are displayed, see section 7.1, “Harmonic Measurement Function” or 7.9, “Harmonic Measurement Specifications.”
- [-----] (no data) is displayed in places where the measurement function is not selected or where no numeric data is present.
- The measured order can be set to normal measured value (---) or from dc (0th order) up to 100th order. However, the numeric data up to the upper limit of measured order (see section 7.9) that is automatically determined by the frequency of the PLL source is the data determined by the harmonic measurement.

7.4 Selecting the PLL Source

Procedure



1. Press **HRM SET** to display the Harmonics menu.
2. Press the **PLL Source Up Exec** or the **PLL Source Down Exec** soft key to select the PLL source. The selected PLL source is displayed in the upper right corner of the screen at PLL Source.
 - Press the PLL Source Down Exec soft key to switch the selected PLL source as follows: U1 → I1 → U2 → I2 and so on.
 - Press the PLL Source Up Exec soft key to switch the selected PLL source as follows: I2 → U2 → I1 → U1 and so on.

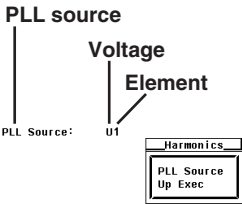


7.4 Selecting the PLL Source

Explanation

For functional details, see section 7.1.
Set the PLL (Phase Locked Loop) source that is used to determine the fundamental period, which acts as the reference in the analysis of the harmonic orders.

- **Displayed Position of the Selected PLL Source**
The selected PLL source is displayed in the upper right corner of the screen when HRM SET is pressed.
Below is a display example when the PLL source is set to the voltage of Element1.



- **Selecting the PLL Source**
Select the PLL source from the choices below. The selectable items vary depending on the installed elements.
U1, I1, U2, I2, U3, I3, U4, I4, and Ext Clk*
* If you select "Ext Clk," harmonic measurement is performed using the frequency of the signal applied to the external clock input connector as the fundamental frequency.

- **When Setting the PLL Source to Ext Clk**
Apply a clock signal to the external clock input connector (EXT CLK) on the rear panel according to the following specifications.



• Ext Clk Specifications

| Item | Specifications |
|-----------------|---------------------------------|
| Connector type | BNC connector |
| Frequency range | 10 Hz to 440 Hz |
| Input level | TTL |
| Input waveform | 50% duty ratio rectangular wave |



CAUTION

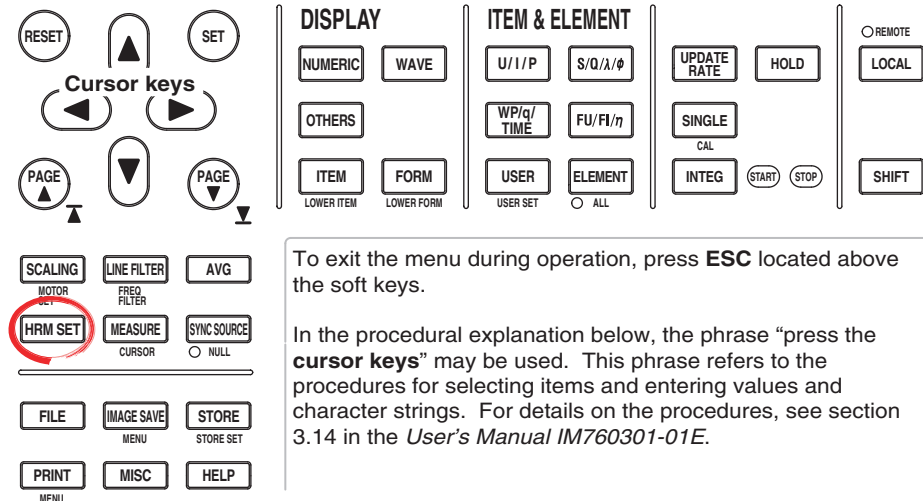
Applying a voltage outside the range of 0 to 5 V to the external clock input connector (EXT CLK) can damage the instrument.

Note

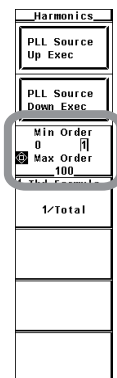
- Select a signal that has the same period as the target signal for the harmonic measurement. Selecting an input signal with little distortion for the PLL source enables stable harmonic measurement. If the fundamental frequency of the PLL source fluctuates or if the fundamental frequency cannot be measured due to waveform distortion, correct measurement results will not be obtained. If the distortion of the voltage signal is smaller than that of the current signal such as when the measured item is a switching power supply, it is recommended that the PLL source be set to the voltage.
If all the input signals are distorted or the amplitude level is small with respect to the measurement range, the specifications may not be met. To achieve accurate measurements on the high orders of the harmonics, set the PLL source to external clock and apply a signal with the same period as the input signal to the external clock input connector.
- If the fundamental frequency is less than or equal to 440 Hz and the signal contains high frequency components, it is recommended that the frequency filter be turned ON. This filter is effective only on the frequency measurement circuit.
- If the amplitude level of the signal input to the element specified as the PLL source is small with respect to the range, PLL synchronization may not be achieved. If the crest factor is set to 3, set the measurement range so that the amplitude level of the PLL source is at least 30%. If the crest factor is set to 6, set the measurement range so that the amplitude level of the PLL source is at least 60%.
- If the frequency of the PLL source changes, correct measured values are displayed from the 4th data update after the change. Correct measured values may not be obtained immediately after the frequency of the PLL source changes or after changing the PLL source, because the PLL circuit inside the WT3000 redetects the frequency.

7.5 Setting the Measured Order

Procedure



1. Press **HRM SET** to display the Harmonics menu.
- **Selecting the Minimum Harmonic Order to Be Measured**
 2. Press the **Min Order** soft key to select 0 or 1.
 - **Selecting the Maximum Harmonic Order to Be Measured**
 3. Press the **cursor keys** to set the maximum harmonic order to be measured.



Explanation

The harmonic measurement range can be specified. The harmonic orders specified here are used to determine the numeric data of the distortion factor. For details on how to determine the distortion factor, see section 7.9.

- **Selecting the Minimum Harmonic Order to Be Measured**

The order can be selected from the following:

- 0: Includes the 0th order (DC) component when determining various numeric data of the harmonic waveform.
- 1: Does not include the 0th order (DC) component when determining various numeric data of the harmonic waveform. 1st order (fundamental signal) is the first component used.

- **Setting the Maximum Harmonic Order to Be Measured**

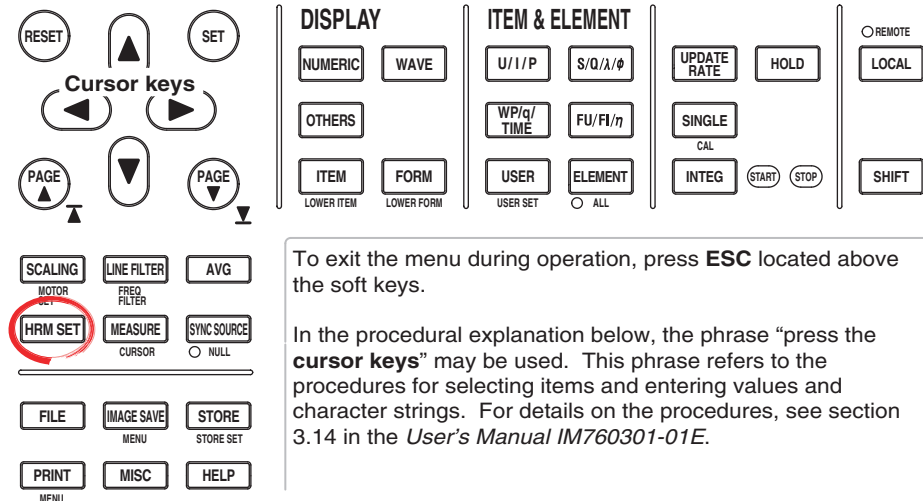
Select the harmonic order in the range from 1 to 100th order.

Note

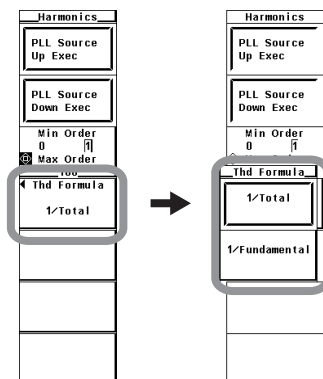
- If the minimum harmonic order to be measured is set to 1, the data of the DC component is not included when determining the numeric data of distortion factor.
- You can set the maximum harmonic order up to 100th order, but the maximum harmonic order that is actually used to determine the numeric data is the order corresponding to the upper limit of the measured order. The upper limit is determined automatically (maximum is 100th) by the frequency of the PLL source. The numeric data corresponding harmonic orders exceeding the upper limit are shown as [-----] (no data).

7.6 Selecting the Distortion Factor Equation

Procedure



1. Press **HRM SET** to display the Harmonics menu.
2. Press the **Thd Formula** soft key to display the Thd Formula menu.
3. Press the **1/Total** or **1/Fundamental** soft key to select the equation for the distortion factor.



Explanation

When determining the measurement functions Uhdf, Ihdf, Phdf, Uthd, lthd, and Pthd of the harmonic measurement mode, select the denominator of the equation from the choices below. For the equations, see section 7.9.

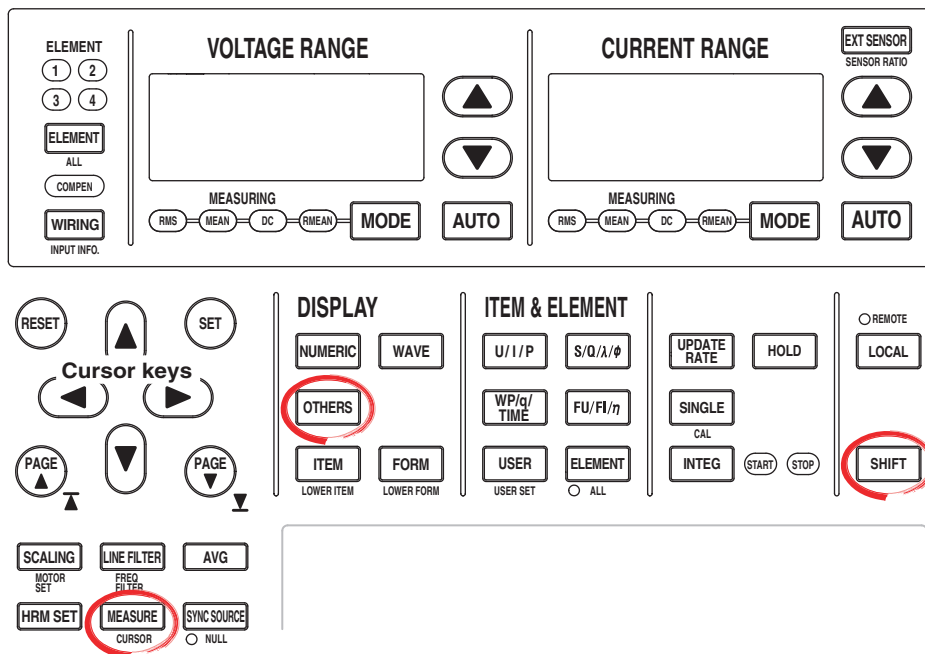
- **1/Total**
All harmonic measurement data from the minimum to the maximum harmonic order (up to the upper limit of measured order) to be measured become the denominator.
- **1/Fundamental**
The data of the fundamental signal component (1st order) become the denominator.

Note

The minimum and maximum harmonic orders to be measured are the values selected in section 7.5.

7.7 Changing the Displayed Items on the Bar Graph and Cursor Measurement

Procedure

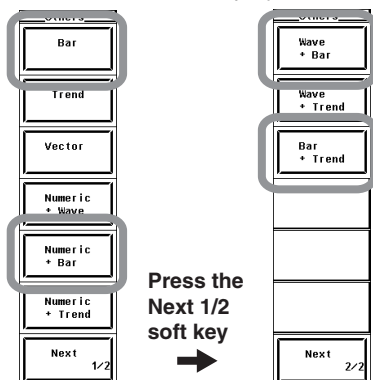


To exit the menu during operation, press **ESC** located above the soft keys.

In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

• Displaying Bar Graphs

1. Press **OTHERS** to display the Others menu.
2. Press any of the soft keys from **Bar**, **Numeric+Bar**, **Wave+Bar**, and **Bar+Trend** to select the display mode.



The following procedures are given as typical examples in which the display mode is set to Bar.

• Selecting the Item to Be Changed

3. Press **ITEM** to display the Bar Item menu.
If the bar graph is at the lower section of the screen on the split display, press **SHIFT+ITEM** (LOWER ITEM).
4. Press the **cursor keys** to select a value between 1 and 3.

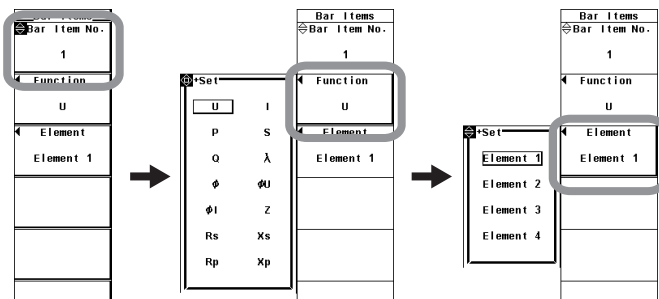
• Changing the Measurement Function

5. Press the **Function** soft key to display the measurement function selection box.
6. Press the **cursor keys** to select the measurement function.
7. Press **SET**. The symbol for the selected measurement function and the bar graph are displayed.

7.7 Changing the Displayed Items on the Bar Graph and Cursor Measurement

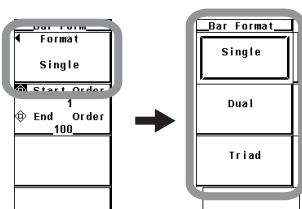
• Changing the Element

8. Press the **Element** soft key to display the element selection box.
9. Press the **cursor keys** to select any of the elements/wiring units starting with Element1.
10. Press **SET**. The bar graph of the selected element number is displayed.



• Selecting the Number of Split Windows for the Bar Graph

11. Press **FORM** to display the Bar Form menu.
If the bar graph is displayed at the lower section of the screen on the split display, press SHIFT+FORM (LOWER FORM).
12. Press the **Format** soft key to display the Bar Format menu.
13. Press any of the keys from **Single** to **Triad** to select the number of windows.
 - If Single is selected, the bar graph of Bar Item No. 1 is displayed.
 - If Dual is selected, the bar graphs of Bar Item No. 1 and 2 are displayed.
 - If Triad is selected, the bar graphs of Bar Item No. 1 to 3 are displayed.



• Setting the Display Range of the Bar Graph

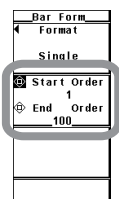
(The difference between the start order and the end order must be greater than or equal to 10.)

• Setting the Start Order

14. Press the **Start Order/End Order** soft key to set the cursor key target to Start Order.
15. Press the **cursor keys** to set the start order of the bar graph.

• Setting the End Order

14. Press the **Start Order/End Order** soft key to set the cursor key target to End Order.
15. Press the **cursor keys** to set the end order of the bar graph.



- **Performing Cursor Measurements**

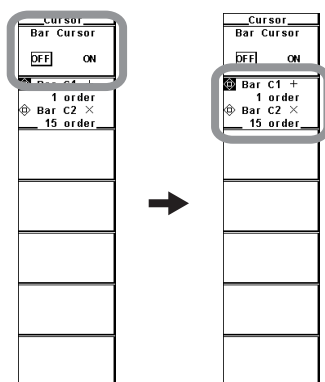
2. Press **SHIFT+MEASURE (CURSOR)** to display the Cursor menu.

- **Turning ON/OFF Cursor Measurement**

3. Press the **Bar Cursor** soft key to select ON or OFF.
If ON is selected, the result of the cursor measurement is displayed.

- **Moving the Cursors**

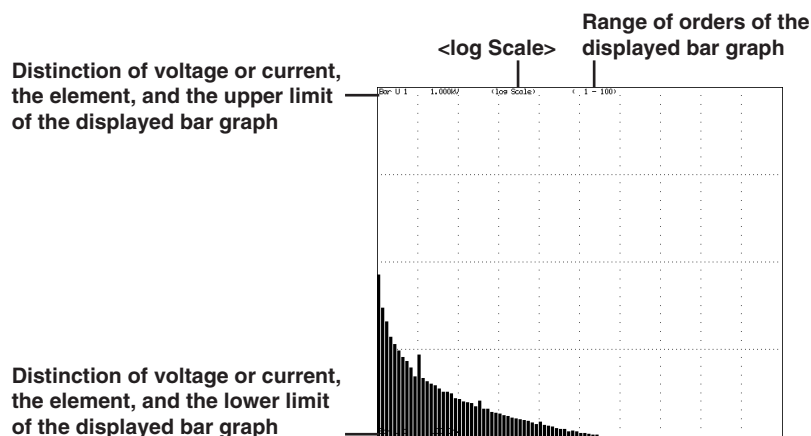
4. Press the **Bar C1 +/Bar C2 x** soft key to set the cursor target to Bar C1 +, Bar C2 x, or both Bar C1 + and Bar C2 x.
 - If you select Bar C1 +, the position of cursor + can be moved.
 - If you select Bar C2 x, the position of cursor x can be moved.
 - If you select both Bar C1 + and Bar C2 x, the two cursors can be moved without changing the spacing between the two. The value of the digit being specified by Bar C1 + changes.
5. Press the **cursor keys** to set and move the cursor position in terms of the harmonic order.



7.7 Changing the Displayed Items on the Bar Graph and Cursor Measurement

Explanation

A display example is shown below. The vertical axis is in logarithmic scale. The word <log Scale> appears at the top section of the screen.



- **Selecting the Display Mode**

Select the bar graph display format from the choices below.

- **Displaying the Bar Graph on the Entire Screen**

Press Bar to display the bar graph on the entire screen.

- **Displaying the Bar Graph by Dividing the Screen into Halves (Split Display)**

- **Numeric+Bar**

The numeric data and bar graph are displayed separately in the top and bottom windows.

- **Wave+Bar**

The waveform and bar graph are displayed separately in the top and bottom windows.

- **Bar+Trend**

The bar graph and trend are displayed separately in the top and bottom windows.

- **Changing the Measurement Function**

Select the measurement function to be changed from the choices below.

U, I, P, S, Q, λ , ϕ , ϕU , ϕI , Z, Rs, Xs, Rp, and Xp

- **Changing the Element**

Select the element from the choices below. The selectable items vary depending on the installed elements.

Element1, Element2, Element3, and Element4

- **Selecting the Item to Be Changed**

Three types of bar graphs can be specified. Select the type from 1 (bar graph 1) to 3 (bar graph 3).

- **Setting the Display Range of the Bar Graph**

- Set the display range of the bar graph using harmonic order.
- The display range of bar graph 1 to bar graph 3 is the same.
- The minimum value is 0th order (DC). However, if the measurement function is set to ϕ , ϕU , or ϕI , there is no value for the 0th order. Thus, 0th order is not displayed on the bar graph.
- If the measurement function is set to ϕU or ϕI , there is no value for the 1st order. Thus, 1st order is not displayed on the bar graph.
- The maximum setting is 100th order. However, bar graphs of orders that exceed the upper limit of the measured order (see section 7.9) are not displayed.

- **Cursor Measurement**

- **ON/OFF**

A cursor can be placed on the displayed bar graph to measure the value at that point.

- ON: Performs cursor measurement.
- OFF: Does not perform cursor measurement.

- **Measurement Item**

- Y1+: Y-axis value of cursor + of bar graph 1
- Y1x: Y-axis value of cursor x of bar graph 1
- $\Delta Y1$: The difference between the Y-axis values of cursor + and cursor x of bar graph 1

- Y2+: Y-axis value of cursor + of bar graph 2
- Y2x: Y-axis value of cursor x of bar graph 2
- $\Delta Y2$: The difference between the Y-axis values of cursor + and cursor x of bar graph 2

- Y3+: Y-axis value of cursor + of bar graph 3
- Y3x: Y-axis value of cursor x of bar graph 3
- $\Delta Y3$: The difference between the Y-axis values of cursor + and cursor x of bar graph 3

- **Moving the Cursor**

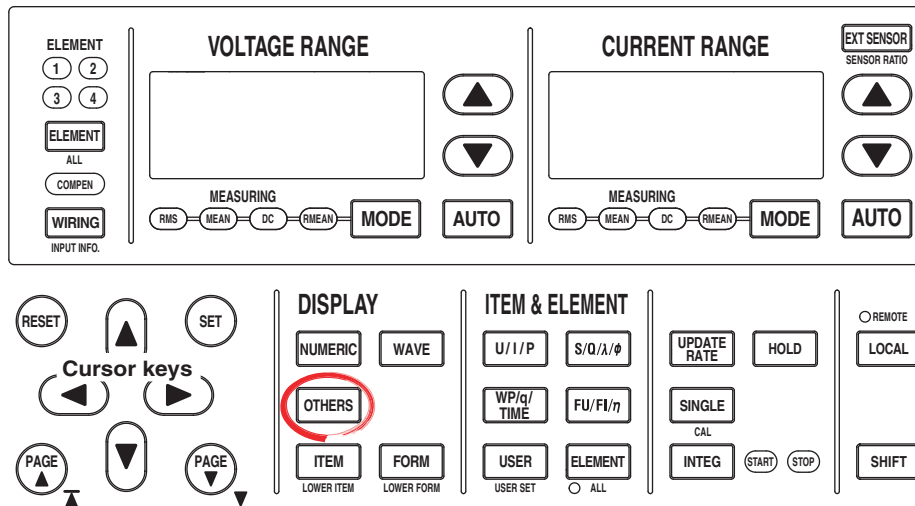
- Two cursors (+ and x) are displayed in each graph (bar graphs 1 to 3).
- The cursor position is set using harmonic order.
- Bar graph displays the harmonic order indicating the cursor position.
 - The position of cursor + is displayed as in order+: 2.
 - The position of cursor x is displayed as in orderx: 55.
- The harmonic order indicating the positions of cursor + and x are common to bar graph 1 to bar graph 3.

Note

If immeasurable data exists, *** is displayed in the measured value display area.

7.8 Changing the Vector Display

Procedure

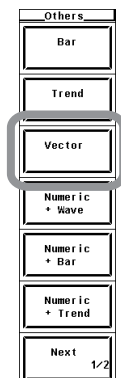


To exit the menu during operation, press **ESC** located above the soft keys.

In the procedural explanation below, the phrase “press the **cursor keys**” may be used. This phrase refers to the procedures for selecting items and entering values and character strings. For details on the procedures, see section 3.14 in the *User's Manual IM760301-01E*.

- **Displaying Vectors**

1. Press **OTHERS** to display the Others menu.
2. Press the **Vector** soft key to select the display mode.



- **Selecting the Wiring Unit to Be Displayed**

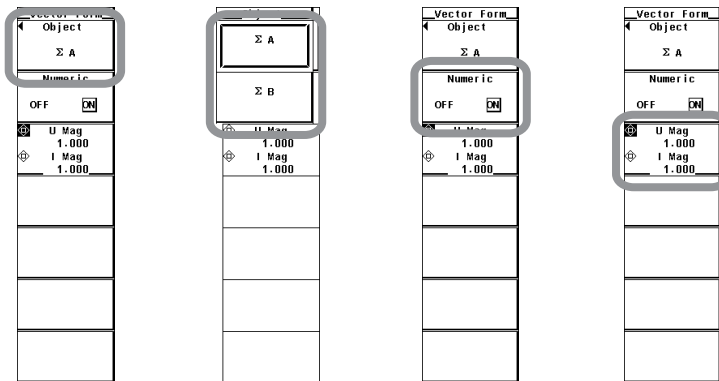
3. Press **FORM** to display the Vector Form menu.
4. Press the **Object** soft key to display the Object menu.
5. Press the ΣA or ΣB soft key to select the wiring unit to be displayed.

- **Turning ON/OFF the Numeric Data Display**

Press the **Numeric** soft key to select ON or OFF.

- **Zooming in on the Vector**

3. Press the **U Mag/I Mag** soft key to set the cursor key target to U Mag, I Mag, or both U Mag and I Mag.
 - If U Mag is selected, you can zoom in on the vector of the fundamental wave U(1) of each element that is specified for harmonic measurement.
 - If I Mag is selected, you can zoom in on the vector of the fundamental wave I(1) of each element that is specified for harmonic measurement.
 - If both U Mag and I Mag is selected, you can zoom in on the vector of the fundamental waves U(1) and I(1) of each element that are specified for harmonic measurement without changing the difference in the zoom factor between U Mag and I Mag. The value of the digit being specified by U Mag changes.
4. Press the **cursor keys** to set the zoom factor.



Explanation

The phase and size (rms value) relationship between the fundamental waves U(1) and I(1) of each element in the wiring unit of ΣA or ΣB can be displayed using vectors. The positive vertical axis is set to 0 (angle zero), and the vector of each input signal is displayed.

- **Turning ON/OFF the Numeric Data Display**

Select whether to display the numeric data. The size and the phase difference between the signals can be displayed along with the vector display. For the display format of the phase difference, see section 5.10 in the *User's Manual IM760301-01E*.

- ON: Displays the numeric data.
- OFF: Does not display the numeric data.

- **Setting the Zoom Factor of Vectors**

The size of the vectors can be changed.

- The zoom factor can be set in the range of 0.100 to 100.000.
- You can specify separate zoom factors for the fundamental waves U(1) and I(1).

Note

If all the wiring systems are single-phase, two-wire (1P2W), no Σ wiring units exist. Therefore, nothing is displayed on the vector display. Therefore, the nothing is displayed on the vector display.

Vector Display Examples

When Displaying Numeric Data
(the size of the signal and the phase difference between signals)

For a 3P4W (three-phase four-wire) wiring system

- U1(1), U2(1), and U3(1) are common mode voltages.
- I1(1), I2(1), and I3(1) are line currents.

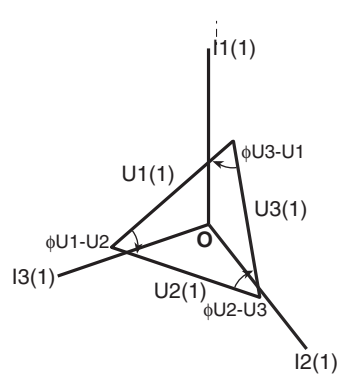
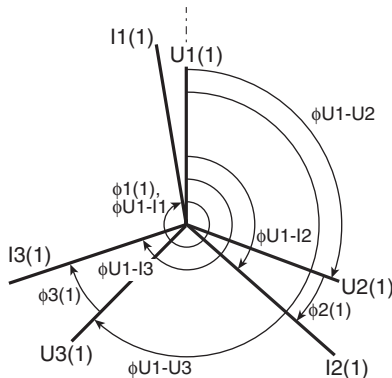
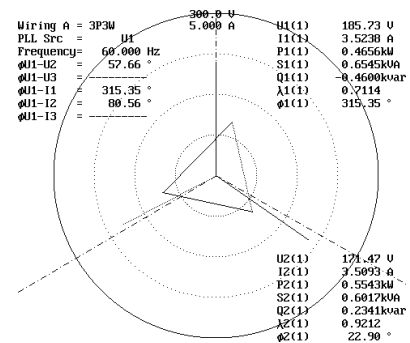
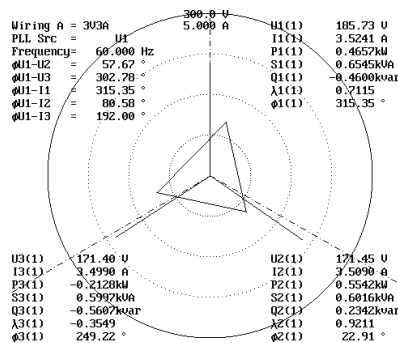
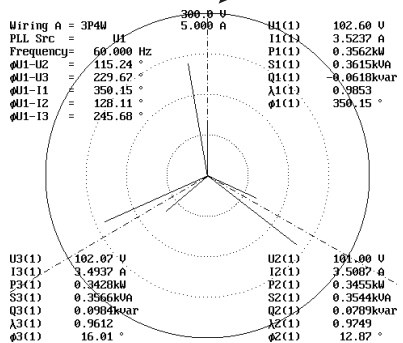
For a 3V3A (three-voltage, three-current) wiring system

- U1(1), U2(1), and U3(1) are line voltages.
- I1(1), I2(1), and I3(1) are line currents.

For a 3P3W (three-phase three-wire) wiring system

- U1(1), U2(1), and U3(1) are line voltages.
- I1(1), I2(1), and I3(1) are line currents. However, U3(1) and I3(1) are not actually measured for the 3P3W system. The vectors are displayed through computation.

Size of the peripheral circle (range)



- By moving the vectors, U1(1), U2(1), and U3(1), so that the starting points of vectors are all at the origin O, the phase relationship can be observed in the same fashion as the 3P3W system. For the relationship between the positions of the vectors after moving them, see "Vector Display of Harmonics" in section 7.1, "Vector Display of Harmonics." (The WT3000 does not provide a function for moving the vectors.)

- The phase difference between the line voltages can be determined from the phase difference measurement functions $\phi U1-U2$ and $\phi U1-U3$.

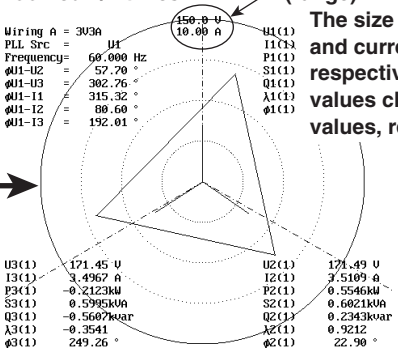
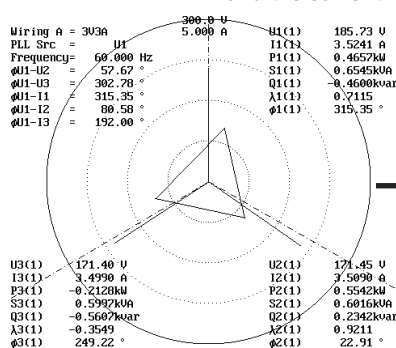
$\phi U1 - U2$ = This is the measurement function $\phi U1U2$.

$\phi U2 - U3 = (\phi U1 - U3) - (\phi U1 - U2) - 180^\circ$

$\phi U3 - U1 = -(\phi U1 - U3)$

When the vector size is zoomed

Example in which the voltage is zoomed 2 and the current is zoomed 1/2 times



The value indicating the size of the peripheral circle (range)

The size of the vector representing the voltage and current is expanded 2 times and 1/2 times, respectively. The voltage range and current range values change to one-half and twice the original values, respectively.

7.9 Harmonic Measurement Specifications

| Item | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--|---|--|-----------------------------------|--|-----------------------------------|----------|-----------------|---|-----|----------|-----------------|---|-----|----------|----------------|----|-----|----------|----------------|----|-----|-----------|----------------|----|----|------------|----------------|----|----|
| Measured source | All installed elements | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Format | PLL synchronization method | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Frequency range | Fundamental frequency of the PLL source is in the range of 10 Hz to 440 Hz. | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PLL source | Select the voltage, current, or external clock of each input element. | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Measurement function | See the next section. | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| FFT data length | 9000 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| FFT processing word length | 32 bits | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Window function | Rectangular | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Anti-aliasing filter | Set using a line filter (5.5 kHz or 50 kHz). | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Sample rate (sampling frequency), window width, and upper limit of measured order during PLL synchronization | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | <table><tr><th>Fundamental Frequency of the PLL Source (Hz)</th><th>Sample Rate (S/s)</th><th>Window Width against the FFT Data Length (Frequency of the Fundamental Wave)</th><th>Upper Limit of the Measured Order</th></tr><tr><td>10 to 20</td><td>$f \times 3000$</td><td>3</td><td>100</td></tr><tr><td>20 to 40</td><td>$f \times 1500$</td><td>6</td><td>100</td></tr><tr><td>40 to 55</td><td>$f \times 900$</td><td>10</td><td>100</td></tr><tr><td>55 to 75</td><td>$f \times 750$</td><td>12</td><td>100</td></tr><tr><td>75 to 150</td><td>$f \times 450$</td><td>20</td><td>50</td></tr><tr><td>150 to 440</td><td>$f \times 150$</td><td>60</td><td>15</td></tr></table> | Fundamental Frequency of the PLL Source (Hz) | Sample Rate (S/s) | Window Width against the FFT Data Length (Frequency of the Fundamental Wave) | Upper Limit of the Measured Order | 10 to 20 | $f \times 3000$ | 3 | 100 | 20 to 40 | $f \times 1500$ | 6 | 100 | 40 to 55 | $f \times 900$ | 10 | 100 | 55 to 75 | $f \times 750$ | 12 | 100 | 75 to 150 | $f \times 450$ | 20 | 50 | 150 to 440 | $f \times 150$ | 60 | 15 |
| Fundamental Frequency of the PLL Source (Hz) | Sample Rate (S/s) | Window Width against the FFT Data Length (Frequency of the Fundamental Wave) | Upper Limit of the Measured Order | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 10 to 20 | $f \times 3000$ | 3 | 100 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 20 to 40 | $f \times 1500$ | 6 | 100 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 40 to 55 | $f \times 900$ | 10 | 100 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 55 to 75 | $f \times 750$ | 12 | 100 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 75 to 150 | $f \times 450$ | 20 | 50 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 150 to 440 | $f \times 150$ | 60 | 15 | | | | | | | | | | | | | | | | | | | | | | | | | | |

7.9 Harmonic Measurement Specifications

Accuracy

- When the line filter is OFF

| Frequency | Voltage and Current ±(reading error + measurement range error) | Power ±(reading error + measurement range error) |
|----------------------|---|---|
| 10 Hz ≤ f < 30 Hz | 0.15% of reading + 0.3% of range | 0.25% of reading + 0.4% of range |
| 30 Hz ≤ f ≤ 440 Hz | 0.1% of reading + 0.15% of range | 0.2% of reading + 0.15% of range |
| 440 Hz < f ≤ 2.5 kHz | 0.6% of reading + 0.15% of range | 1.2% of reading + 0.2% of range |
| 2.5 kHz < f ≤ 5 kHz | 1.6% of reading + 0.15% of range | 3.2% of reading + 0.2% of range |
| 5 kHz < f ≤ 7.5 kHz | 2.5% of reading + 0.15% of range | 5% of reading + 0.2% of range |

- When the line filter (5.5 kHz) is ON

| Frequency | Voltage and Current ±(reading error + measurement range error) | Power ±(reading error + measurement range error) |
|---------------------|---|---|
| 10 Hz ≤ f < 30 Hz | 0.25% of reading + 0.3% of range | 0.5% of reading + 0.4% of range |
| 30 Hz ≤ f ≤ 66 Hz | 0.2% of reading + 0.15% of range | 0.4% of reading + 0.15% of range |
| 66 Hz < f ≤ 440 Hz | 0.5% of reading + 0.15% of range | 1.2% of reading + 0.15% of range |
| 440 Hz < f ≤ 1 kHz | 1.2% of reading + 0.15% of range | 2% of reading + 0.15% of range |
| 1 kHz < f ≤ 2.5 kHz | 2.5% of reading + 0.15% of range | 6% of reading + 0.2% of range |

- When the line filter (50 kHz) is ON

| Frequency | Voltage and Current ±(reading error + measurement range error) | Power ±(reading error + measurement range error) |
|----------------------|---|---|
| 10 Hz ≤ f < 30 Hz | 0.25% of reading + 0.3% of range | 0.45% of reading + 0.4% of range |
| 30 Hz ≤ f ≤ 440 Hz | 0.2% of reading + 0.15% of range | 0.4% of reading + 0.15% of range |
| 440 Hz < f ≤ 2.5 kHz | 1% of reading + 0.15% of range | 2% of reading + 0.2% of range |
| 2.5 kHz < f ≤ 5 kHz | 2% of reading + 0.15% of range | 4% of reading + 0.2% of range |
| 5 kHz < f ≤ 7.5 kHz | 3.5% of reading + 0.15% of range | 6.5% of reading + 0.2% of range |

However, all the items below apply to all the tables.

When averaging is ON, the averaging type is EXP, and the attenuation constant is greater than or equal to 8.

When the crest factor is set to 3

Power figures that exceed 440 Hz are reference values.

For n^{th} order component input, add $(n^{\text{th}} \text{ order reading}) \times \{n/(m+1)\}/50\%$ to $n+m^{\text{th}}$ order and $n-m^{\text{th}}$ order.

Add $(n/500)\%$ of reading to the n^{th} component.

Accuracy when the crest factor is 6: The same as when the range is doubled for crest factor 3.

If the amplitude of the high frequency component is large, influence of approximately 1% may appear in certain orders. The influence depends on the size of the frequency component.

Therefore, if the frequency component is small with respect to the range rating, this does not cause a problem.

Measurement Functions Determined for Each Input Element

| Item | Symbol and Meaning |
|---|---|
| Voltage (V) | $U(k)$: rms value of the harmonic voltage of order k ^{*1} |
| Current (A) | $I(k)$: rms value of the harmonic current of order k |
| Active power (W) | $P(k)$: Active power of the harmonic signal of order k |
| Apparent power (VA) | $S(k)$: Apparent power of the harmonic signal of order k |
| Reactive power (var) | $Q(k)$: Reactive power of the harmonic signal of order k |
| Power factor | $\lambda(k)$: Power factor of the harmonic signal of order k |
| Phase difference (°) | $\phi(k)$: Phase difference between the harmonic voltage and current of order k , ϕ : total phase $\phi U(k)$: Phase difference of each harmonic voltage $U(k)$ with respect to the fundamental signal $U(1)$ $\phi I(k)$: Phase difference of each harmonic current $I(k)$ with respect to the fundamental signal $I(1)$ |
| Impedance (Ω) of the load circuit | $Z(k)$: Impedance of the load circuit observed by the k^{th} order harmonic signal. |
| Resistance and reactance | $R_s(k)$: Resistance observed by the k^{th} order harmonic signal of the load circuit that has a resistor R , (Ω) of the load circuit inductor L , and capacitor C connected in series $X_s(k)$: Reactance observed by the k^{th} order harmonic signal of the load circuit that has a resistor R , inductor L , and capacitor C connected in series $R_p(k)$: Resistance observed by the k^{th} order harmonic signal of the load circuit that has a resistor R , inductor L , and capacitor C connected in parallel $X_p(k)$: Reactance observed by the k^{th} order harmonic signal of the load circuit that has a resistor R , inductor L , and capacitor C connected in parallel |
| Harmonic distortion factor [%] | $U_{hdf}(k)$: The ratio of the harmonic voltage $U(k)$ to $U(1)$ or U expressed as a percentage. $I_{hdf}(k)$: The ratio of the harmonic current $I(k)$ to $I(1)$ or I expressed as a percentage. $P_{hdf}(k)$: The ratio of the active power $P(k)$ of the harmonic signal to $P(1)$ or P expressed as a percentage. |
| Total harmonic distortion [%] | U_{thd} : The ratio of the total harmonic voltage to $U(1)$ or U^2 expressed as a percentage. I_{thd} : The ratio of the total harmonic current to $I(1)$ or I expressed as a percentage. P_{thd} : The ratio of the active power of the total harmonic signal to $P(1)$ or P expressed as a percentage. |
| Telephone harmonic factor ^{*3} (Applicable standard IEC34-1(1996)) | U_{thf} : Voltage telephone harmonic factor, I_{thf} : Current telephone harmonic factor |
| Telephone influence factor ^{*3} (Applicable standard IEEE Std 100(1996)) | U_{tif} : Voltage telephone influence factor, I_{tif} : Current telephone influence factor |
| Harmonic voltage factor ^{*4} | hvf : harmonic voltage factor |
| Harmonic current factor ^{*4} | hcf : harmonic current factor |

*1 Order k is an integer in the range from 0 to the upper limit of the measured order. 0th order is the DC component. The upper limit is determined automatically (maximum is 100th) by the frequency of the PLL source.

*2 Total harmonic is a value determined according to the equation given in the next section from all harmonic components (2nd to the upper limit of measured order).

*3 Measurement functions specific to the IEC or IEEE standard.

*4 The equation may vary depending on the definitions given in the respective standard. For details, see the respective standard.

Measurement Functions Indicating the Phase Difference of the Fundamental Voltage and Current between Elements

These measurement functions express the phase difference of fundamental wave $U(1)$ and $I(1)$ of other elements with respect to the fundamental wave $U(1)$ of the element with the smallest number of the input elements that are assigned to the wiring unit. The following table indicates the measurement functions for a wiring unit that combines elements 1, 2, and 3.

| Item | Symbol and Meaning |
|------------------------------|---|
| Phase difference $U1-U2$ (°) | $\phi U1-U2$: Phase difference of the fundamental voltage ($U2(1)$) of element 2 with respect to the fundamental voltage ($U1(1)$) of element 1. |
| Phase difference $U1-U3$ (°) | $\phi U1-U3$: Phase difference of the fundamental voltage ($U3(1)$) of element 3 with respect to $U1(1)$. |
| Phase difference $U1-I1$ (°) | $\phi U1-I1$: Phase difference of the fundamental current ($I1(1)$) of element 1 with respect to $U1(1)$. |
| Phase difference $U1-I2$ (°) | $\phi U1-I2$: Phase difference of the fundamental current ($I2(1)$) of element 2 with respect to $U1(1)$. |
| Phase difference $U1-I3$ (°) | $\phi U1-I3$: Phase difference of the fundamental current ($I3(1)$) of element 3 with respect to $U1(1)$. |

Measurement Functions (Σ Functions) Determined for Each Wiring Unit (ΣA and ΣB)

| Item | Symbol and Meaning |
|----------------------|---|
| Voltage (V) | $U\Sigma(1)$: rms value of the harmonic voltage of order 1 |
| Current (A) | $I\Sigma(1)$: rms value of the harmonic current of order 1 |
| Active power (W) | $P\Sigma(1)$: Active power of the harmonic signal of order 1 |
| Apparent power (VA) | $S\Sigma(1)$: Apparent power of the harmonic signal of order 1 |
| Reactive power (var) | $Q\Sigma(1)$: Reactive power of the harmonic signal of order 1 |
| Power factor | $\lambda\Sigma(1)$: Power factor of the harmonic signal of order 1 |

Determination of Measurement Functions during Harmonic Measurement

(Table 1/2)

| Measurement Functions during Harmonic Measurement | Method of Determination, Equation | | |
|---|--|--|---|
| | Characters/Numbers inside the parentheses of measurement functions | | |
| | dc (when k = 0) | 1 (when k = 1) | k (When k = 2 to max) |
| Voltage $U(k)$ [V] | $U(dc) = U_r(0)$ | $U(k) = \sqrt{U_r(k)^2 + U_j(k)^2}$ | |
| Current $I(k)$ [A] | $I(dc) = I_r(0)$ | $I(k) = \sqrt{I_r(k)^2 + I_j(k)^2}$ | |
| Active power $P(k)$ [W] | $P(dc) = U_r(0) \cdot I_r(0)$ | $P(k) = U_r(k) \cdot I_r(k) + U_j(k) \cdot I_j(k)$ | |
| Apparent power $S(k)$ [VA] (TYPE3)* | $S(dc) = P(dc)$ | $S(k) = \sqrt{P(k)^2 + Q(k)^2}$ | |
| Reactive power $Q(k)$ [var] (TYPE3)* | $Q(dc) = 0$ | $Q(k) = U_r(k) \cdot I_j(k) - U_j(k) \cdot I_r(k)$ | |
| Power factor $\lambda(k)$ | $\lambda(dc) = \frac{P(dc)}{S(dc)}$ | $\lambda(k) = \frac{P(k)}{S(k)}$ | |
| Phase difference $\phi(k)$ [°] | — | $\phi(k) = \cos^{-1} \left\{ \frac{P(k)}{S(k)} \right\}$ | |
| Phase difference with respect to $U(1)$ $\phi_U(k)$ [°] | — | | $\phi_U(k)$ = Phase difference of $U(k)$ with respect to $U(1)$ |
| Phase difference with respect to $I(1)$ $\phi_I(k)$ [°] | — | | $\phi_I(k)$ = Phase difference of $I(k)$ with respect to $I(1)$ |
| Impedance of the load circuit $Z(k)$ [Ω] | $Z(dc) = \left \frac{U(dc)}{I(dc)} \right $ | $Z(k) = \left \frac{U(k)}{I(k)} \right $ | |
| Series resistance of the load circuit $R_s(k)$ [Ω] | $R_s(dc) = \frac{P(dc)}{I(dc)^2}$ | $R_s(k) = \frac{P(k)}{I(k)^2}$ | |
| Series reactance of the load circuit $X_s(k)$ [Ω] | $X_s(dc) = \frac{Q(dc)}{I(dc)^2}$ | $X_s(k) = \frac{Q(k)}{I(k)^2}$ | |
| Parallel resistance of the load circuit $R_p(k)$ [Ω] (= 1/G) | $R_p(dc) = \frac{U(dc)^2}{P(dc)}$ | $R_p(k) = \frac{U(k)^2}{P(k)}$ | |
| Parallel reactance of the load circuit $X_p(k)$ [Ω] (= 1/B) | $X_p(dc) = \frac{U(dc)^2}{Q(dc)}$ | $X_p(k) = \frac{U(k)^2}{Q(k)}$ | |

(Continues on the next page)

* For details on the type of S and Q equations, see section 5.9 in the *User's Manual IM760301-01E*.**Note**

- Variables k, r, and j denote the harmonic order, real part, and imaginary part, respectively.
- Variables $U(k)$, $U_r(k)$, $U_j(k)$, $I(k)$, $I_r(k)$, and $I_j(k)$ are expressed using rms values.
- Variable max is the upper limit of measured order. The upper limit is determined automatically (maximum is 100) by the frequency of the PLL source.

7.9 Harmonic Measurement Specifications

(Table 2/2)

| Measurement Functions during Harmonic Measurement | | Method of Determination, Equation | | | |
|--|-------------------|--|--------------------------------|---|-------------------------------|
| | | Characters/Numbers inside the parentheses of measurement functions are dc (when k = 0) and k (when k = 1 to max). | | | |
| | | When the numerator of the distortion factor equation is all (Total) | | When the numerator of the distortion factor equation is fundamental | |
| Voltage harmonic distortion factor U _{hdf} () [%] | | $\frac{U(k)}{U(Total)^2} \cdot 100$ | | $\frac{U(k)}{U(1)} \cdot 100$ | |
| Current harmonic distortion factor I _{hdf} () [%] | | $\frac{I(k)}{I(Total)^2} \cdot 100$ | | $\frac{I(k)}{I(1)} \cdot 100$ | |
| Active power harmonic distortion factor P _{hdf} () [%] | | $\frac{P(k)}{P(Total)^2} \cdot 100$ | | $\frac{P(k)}{P(1)} \cdot 100$ | |
| Total harmonic distortion of voltage U _{thd} [%] | | $\frac{\sqrt{\sum_{k=2}^{max} U(k)^2}}{U(Total)^2} \cdot 100$ | | $\frac{\sqrt{\sum_{k=2}^{max} U(k)^2}}{U(1)} \cdot 100$ | |
| Total harmonic distortion of current I _{thd} [%] | | $\frac{\sqrt{\sum_{k=2}^{max} I(k)^2}}{I(Total)^2} \cdot 100$ | | $\frac{\sqrt{\sum_{k=2}^{max} I(k)^2}}{I(1)} \cdot 100$ | |
| Total harmonic distortion of active power P _{thd} [%] | | $\left \frac{\sum_{k=2}^{max} P(k)}{P(Total)^{*2}} \right \cdot 100$ | | $\left \frac{\sum_{k=2}^{max} P(k)}{P(1)} \right \cdot 100$ | |
| Voltage telephone harmonic factor U _{thf} [%] Current telephone harmonic factor I _{thf} [%] | | $U_{thf} = \frac{1}{U(Total)^{*2}} \sqrt{\sum_{k=1}^{max} \{\lambda(k) \cdot U(k)\}^2} \cdot 100 \quad I_{thf} = \frac{1}{I(Total)^{*2}} \sqrt{\sum_{k=1}^{max} \{\lambda(k) \cdot I(k)\}^2} \cdot 100$ Constant defined in the applicable standard (IEC34-1(1996)) | | | |
| Voltage telephone influence factor U _{tif} Current telephone influence factor I _{tif} | | $U_{tif} = \frac{1}{U(Total)^2} \sqrt{\sum_{k=1}^{max} \{T(k) \cdot U(k)\}^2} \quad I_{tif} = \frac{1}{I(Total)^2} \sqrt{\sum_{k=1}^{max} \{T(k) \cdot I(k)\}^2}$ Constant defined in the applicable standard (IEEE Std 100(1992)) | | | |
| Harmonic voltage factor hvf [%] Harmonic current factor hcf [%] | | $hvf = \frac{1}{U(Total)^{*2}} \sqrt{\sum_{k=2}^{max} \frac{U(k)^2}{k}} \cdot 100$ | | $hcf = \frac{1}{I(Total)^2} \sqrt{\sum_{k=2}^{max} \frac{I(k)^2}{k}} \cdot 100$ | |
| Σ function | Wiring system | Single-phase, three-wire (1P3W) | Three-phase, three-wire (3P3W) | Three-voltage, three-current (3V3A) | Three-phase, four-wire (3P4W) |
| | UΣ [V] | (U1 + U2) / 2 | | (U1 + U2 + U3) / 3 | |
| | IΣ [A] | (I1 + I2) / 2 | | (I1 + I2 + I3) / 3 | |
| | PΣ [W] (TYPE3)*1 | P1 + P2 | | | P1 + P2 + P3 |
| | SΣ [VA] (TYPE3)*1 | $\sqrt{P\Sigma^2 + Q\Sigma^2}$ | | | |
| | QΣ [var] | Q1 + Q2 | | | Q1 + Q2 + Q3 |
| | λΣ | $\frac{P\Sigma}{S\Sigma}$ | | | |

*1 For details on the type of S Σ and Q Σ equations, see section 5.9 in the *User's Manual IM760301-01E*.

$$*2 \ U(\text{Total}) = \sqrt{\sum_{k=\min}^{\max} U(k)^2}, \quad I(\text{Total}) = \sqrt{\sum_{k=\min}^{\max} I(k)^2}, \quad P(\text{Total}) = \sum_{k=\min}^{\max} P(k)$$

Note

- Variables k, r, and j denote the harmonic order, real part, and imaginary part, respectively.
- Variable min is the minimum measured order.
- Variable max is the upper limit of measured order. The upper limit is determined automatically (maximum is 100) by the frequency of the PLL source.
- The numbers 1, 2, and 3 in the equations U Σ , I Σ , P Σ , S Σ , and Q Σ indicate the case when input elements 1, 2, and 3 are set to the wiring system shown in the table. If elements 2, 3, and 4 are set to the wiring system shown in the table, replace the numbers 1, 2, and 3 with 2, 3, and 4, respectively.
- For Σ , only dc (0th) and fundamental wave (1st) are computed.

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